

# Elektromagnetische Feldtheorie I (EFT I) / Electromagnetic Field Theory I (EFT I)

## 4th Lecture / 4. Vorlesung

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# Faraday's Induction Law in Integral Form / Faradaysches Induktionsgesetz in Integralform (1)

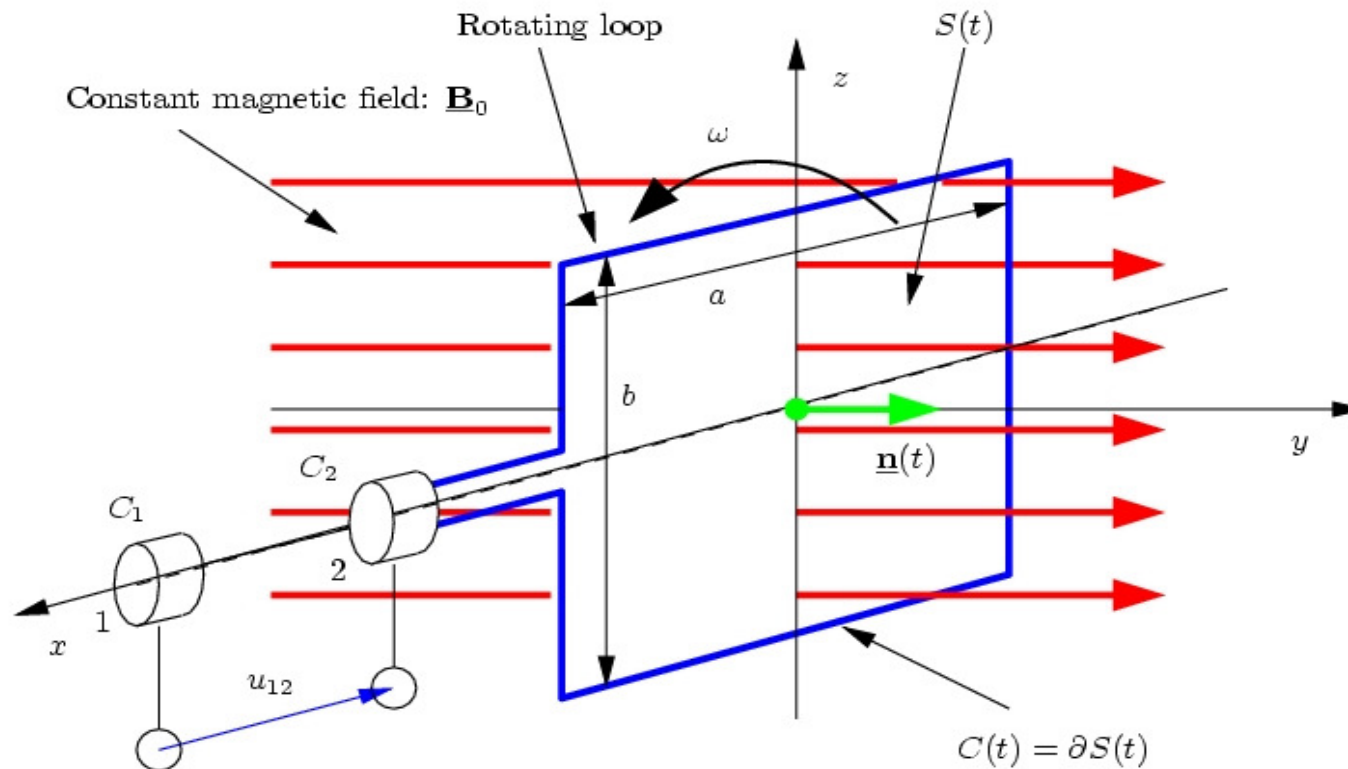
## Faraday's Induction Law / Faradaysches Induktionsgesetz

$$\oint_{C(t)=\partial S(t)} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} = -\frac{d}{dt} \iint_{S(t)} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} - \iint_{S(t)} \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

Time Dependent Surface /  
Zeitabhängige Fläche

$S(t)$   $C(t) = \partial S(t)$

Time Dependent Contour /  
Zeitabhängige Kontur



# Faraday's Induction Law in Integral Form / Faradaysches Induktionsgesetz in Integralform (2)

## Faraday's Induction Law / Faradaysches Induktionsgesetz

$$\oint_{C(t)=\partial S(t)} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}} = -\frac{d}{dt} \iint_{S(t)} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}} - \iint_{S(t)} \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}$$

$\oint_{C(t)=\partial S(t)} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}}$	[m]	Closed Contour Integral / Geschlossenes Kurvenintegral
$\underline{\mathbf{E}}(\underline{\mathbf{R}}, t)$	[V/m]	Electric Field Strength / Elektrische Feldstärke
$\underline{\mathbf{dR}}$	[m]	Vectorial Differential Line Element / Vektoriell differenzielles Linienelement
$\underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}}$	[V]	Scalar Product of E and dR = tangential projection of E onto dR / Skalarprodukt von E auf dR = Tangentialprojektion von E auf dR

Vectorial Differential Line Element /  
Vektoriell differenzielles  
Linienelement

$$\underline{\mathbf{dR}} = \underline{\mathbf{s}} \, dR$$

Tangential Unit Vector /  
Tangentialer Einheitsvektor
Scalar Differential Line Element / Skalares  
differenzielles Linienelement

# Different Products / Verschiedene Produkte

Scalar Product / Skalarprodukt  $C = \underline{\mathbf{A}} \cdot \underline{\mathbf{B}}$

Vector Product / Vektorprodukt  $\underline{\mathbf{C}} = \underline{\mathbf{A}} \times \underline{\mathbf{B}}$

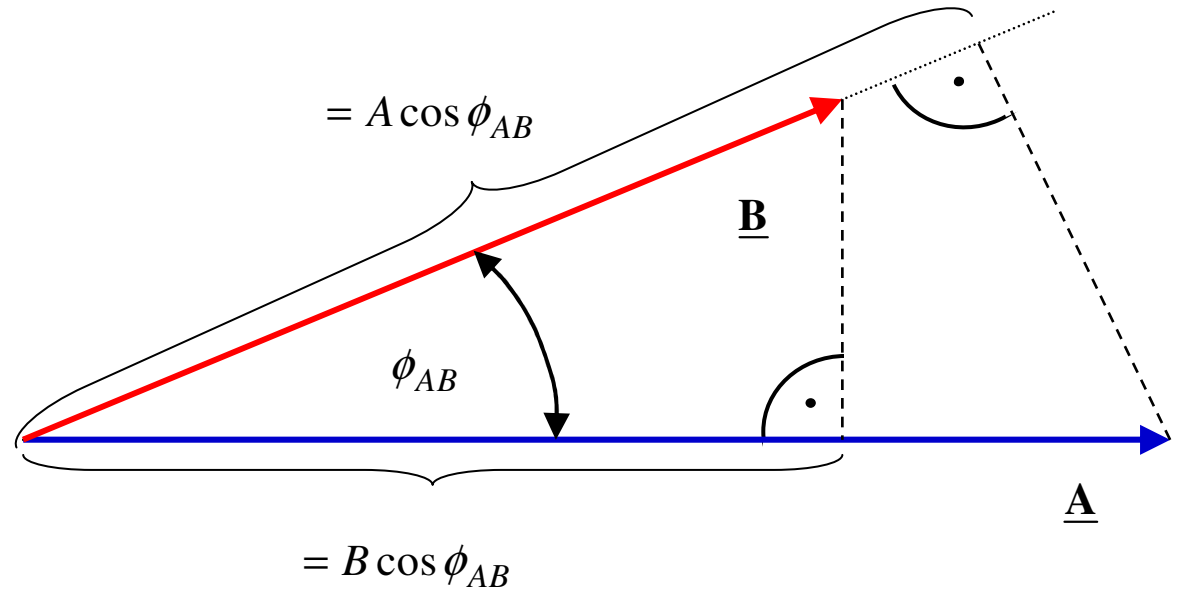
Dyadic Product / Dyadisches Produkt  $\underline{\underline{\mathbf{C}}} = \underline{\mathbf{A}} \underline{\mathbf{B}}$

# Scalar Product (Dot or Inner Product) / Skalarprodukt (Punktprodukt oder inneres Produkt) (1)

$$\underline{\mathbf{A}} \cdot \underline{\mathbf{B}} = |\underline{\mathbf{A}}| |\underline{\mathbf{B}}| \cos \underbrace{\angle(\underline{\mathbf{A}}, \underline{\mathbf{B}})}_{\phi_{AB}}$$

$$= AB \cos \phi_{AB}$$

Enclosed Angle /  
Eingeschlossener Winkel  $\phi_{AB}$



$$\underline{\mathbf{A}} \cdot \underline{\mathbf{B}} = \underline{\mathbf{B}} \cdot \underline{\mathbf{A}}$$

$$= BA \cos \phi_{BA}$$

$$= AB \cos \phi_{AB}$$

$$\cos(\phi_{AB}) = \cos(-\phi_{AB})$$

$$\cos \phi_{AB} = \frac{\underline{\mathbf{A}} \cdot \underline{\mathbf{B}}}{|\underline{\mathbf{A}}| |\underline{\mathbf{B}}|}$$

$$\phi_{AB} = \arccos \left( \frac{\underline{\mathbf{A}} \cdot \underline{\mathbf{B}}}{|\underline{\mathbf{A}}| |\underline{\mathbf{B}}|} \right)$$

# Scalar Product (Dot or Inner Product) / Skalarprodukt (Punktprodukt oder inneres Produkt) (2)

$$\begin{aligned}
 \underline{\mathbf{A}} \cdot \underline{\mathbf{B}} &= (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z) \\
 &= A_x B_x \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_x}_{=1} + A_x B_y \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_y}_{=0} + A_x B_z \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_z}_{=0} \\
 &\quad + A_y B_x \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_x}_{=0} + A_y B_y \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_y}_{=1} + A_y B_z \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_z}_{=0} \\
 &\quad + A_z B_x \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_x}_{=0} + A_z B_y \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_y}_{=0} + A_z B_z \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_z}_{=1} \\
 &= A_x B_x + A_y B_y + A_z B_z
 \end{aligned}$$

## Orthonormal Unit Vectors / Orthonormale Einheitsvektoren

$$\underline{\mathbf{e}}_x \perp \underline{\mathbf{e}}_y \perp \underline{\mathbf{e}}_z$$

$$\begin{array}{lll}
 \underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_x = 1 & \underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_x = 0 & \underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_x = 0 \\
 \underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_y = 0 & \underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_y = 1 & \underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_y = 0 \\
 \underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_z = 0 & \underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_z = 0 & \underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_z = 1
 \end{array}$$

$$\begin{aligned}
 \underline{\mathbf{A}} \cdot \underline{\mathbf{B}} &= (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z) \\
 &= A_x B_x + A_y B_y + A_z B_z \\
 &= (A_{x_1} \underline{\mathbf{e}}_{x_1} + A_{x_2} \underline{\mathbf{e}}_{x_2} + A_{x_3} \underline{\mathbf{e}}_{x_3}) \cdot (B_{x_1} \underline{\mathbf{e}}_{x_1} + B_{x_2} \underline{\mathbf{e}}_{x_2} + B_{x_3} \underline{\mathbf{e}}_{x_3}) \\
 &= A_{x_1} B_{x_1} + A_{x_2} B_{x_2} + A_{x_3} B_{x_3} \\
 &= \sum_{i=1}^3 A_{x_i} B_{x_i}
 \end{aligned}$$

## Cartesian Coordinates / Kartesische Koordinaten

$$x = x_1$$

$$y = x_2$$

$$z = x_3$$

# Scalar Product (Dot or Inner Product) / Skalarprodukt (Punktprodukt oder inneres Produkt) (3)

$$\underline{\mathbf{A}} \cdot \underline{\mathbf{B}} = (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z)$$

$$= \sum_{i=1}^3 A_{x_i} \underline{\mathbf{e}}_{x_i} \cdot \sum_{j=1}^3 B_{x_j} \underline{\mathbf{e}}_{x_j}$$

$$= \sum_{i=1}^3 \sum_{j=1}^3 A_{x_i} \underline{\mathbf{e}}_{x_i} \cdot B_{x_j} \underline{\mathbf{e}}_{x_j}$$

$$= \sum_{i=1}^3 \sum_{j=1}^3 A_{x_i} B_{x_j} \underbrace{\underline{\mathbf{e}}_{x_i} \cdot \underline{\mathbf{e}}_{x_j}}_{=\delta_{ij}}$$

$$= A_{x_i} B_{x_j} \underbrace{\underline{\mathbf{e}}_{x_i} \cdot \underline{\mathbf{e}}_{x_j}}_{=\delta_{ij}}$$

$$= A_{x_i} \underbrace{B_{x_j} \delta_{ij}}_{=B_{x_i}} \quad \left( \text{or/oder} \quad \underbrace{A_{x_i} \delta_{ij} B_{x_j}}_{=A_{x_j}} \right) \quad \left( \underbrace{\hspace{10em}}_{=A_{x_j} B_{x_j}} \right)$$

$$= A_{x_i} B_{x_i}$$

Kronecker Delta /  
Kronecker-Delta

$$\delta_{ij} = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

with Einstein's Summation Convention /  
mit Einsteinscher Summationskonvention

*Einstein's Summation Convention:* If a index appears two times at one side of an equation (and not at the other side), the index is automatically summed over 1 to 3. /  
*Einsteinsche Summenkonvention:* Wenn ein Index auf einer Seite einer Gleichung zweimal vorkommt (und auf der anderen nicht), wird darüber von 1 bis 3 summiert.

## Magnitude of a Vector / Betrag eines Vektors

$$\begin{aligned}
 |\underline{\mathbf{A}}| &= \sqrt{\underline{\mathbf{A}} \cdot \underline{\mathbf{A}}} \\
 &= \sqrt{(A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z)} \\
 &= \left( \begin{aligned}
 &A_x A_x \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_x}_{=1} + A_x A_y \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_y}_{=0} + A_x A_z \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_z}_{=0} \\
 &+ A_y A_x \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_x}_{=0} + A_y A_y \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_y}_{=1} + A_y A_z \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_z}_{=0} \\
 &+ A_z A_x \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_x}_{=0} + A_z A_y \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_y}_{=0} + A_z A_z \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_z}_{=1}
 \end{aligned} \right)^{\frac{1}{2}} \\
 &= \sqrt{A_x A_x + A_y A_y + A_z A_z} \\
 &= \sqrt{A_x^2 + A_y^2 + A_z^2} \\
 &= A
 \end{aligned}$$

$$\begin{aligned}
 |\underline{\mathbf{A}}| &= \sqrt{\underline{\mathbf{A}} \cdot \underline{\mathbf{A}}} \\
 &= \sqrt{\sum_{i=1}^3 A_{x_i} \underline{\mathbf{e}}_{-x_i} \cdot \sum_{j=1}^3 B_{x_j} \underline{\mathbf{e}}_{-x_j}} \\
 &= \sqrt{A_{x_i} \underline{\mathbf{e}}_{-x_i} \cdot A_{x_j} \underline{\mathbf{e}}_{-x_j}} \\
 &= \sqrt{A_{x_i} A_{x_j} \underbrace{\underline{\mathbf{e}}_{-x_i} \cdot \underline{\mathbf{e}}_{-x_j}}_{=\delta_{ij}}} \\
 &= \sqrt{A_{x_i}^2}
 \end{aligned}$$



# Example: Position Vector and Electric Field Strength Vector / Beispiel: Ortsvektor und elektrischer Feldstärkevektor

Cartesian Coordinate System / Kartesisches Koordinatensystem

Position Vector /  
Ortsvektor

$$\begin{aligned}\underline{\mathbf{R}}(x, y, z) &= R_x(x, y, z)\underline{\mathbf{e}}_x + R_y(x, y, z)\underline{\mathbf{e}}_y + R_z(x, y, z)\underline{\mathbf{e}}_z \\ &= x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z\end{aligned}$$

Magnitude of the Position Vector (Distance) /  
Betrag des Ortsvektor (Abstand)

$$\begin{aligned}|\underline{\mathbf{R}}(x, y, z)| &= \sqrt{\underline{\mathbf{R}}(x, y, z) \cdot \underline{\mathbf{R}}(x, y, z)} \\ &= \sqrt{(x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z) \cdot (x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z)} \\ &= \sqrt{x^2 + y^2 + z^2}\end{aligned}$$

Position Unit Vector (Direction) /  
Ortseinheitsvektor (Richtung)

$$\begin{aligned}\hat{\underline{\mathbf{R}}}(x, y, z) &= \frac{\underline{\mathbf{R}}(x, y, z)}{|\underline{\mathbf{R}}(x, y, z)|} \\ &= \frac{x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z}{\sqrt{x^2 + y^2 + z^2}}\end{aligned}$$

Electric Field Strength Vector /  
Elektrische Feldstärkevektor

$$\begin{aligned}\underline{\mathbf{E}}(\underline{\mathbf{R}}, t) &= \underline{\mathbf{E}}(x, y, z, t) \\ &= E_x(x, y, z, t)\underline{\mathbf{e}}_x + E_y(x, y, z, t)\underline{\mathbf{e}}_y + E_z(x, y, z, t)\underline{\mathbf{e}}_z\end{aligned}$$

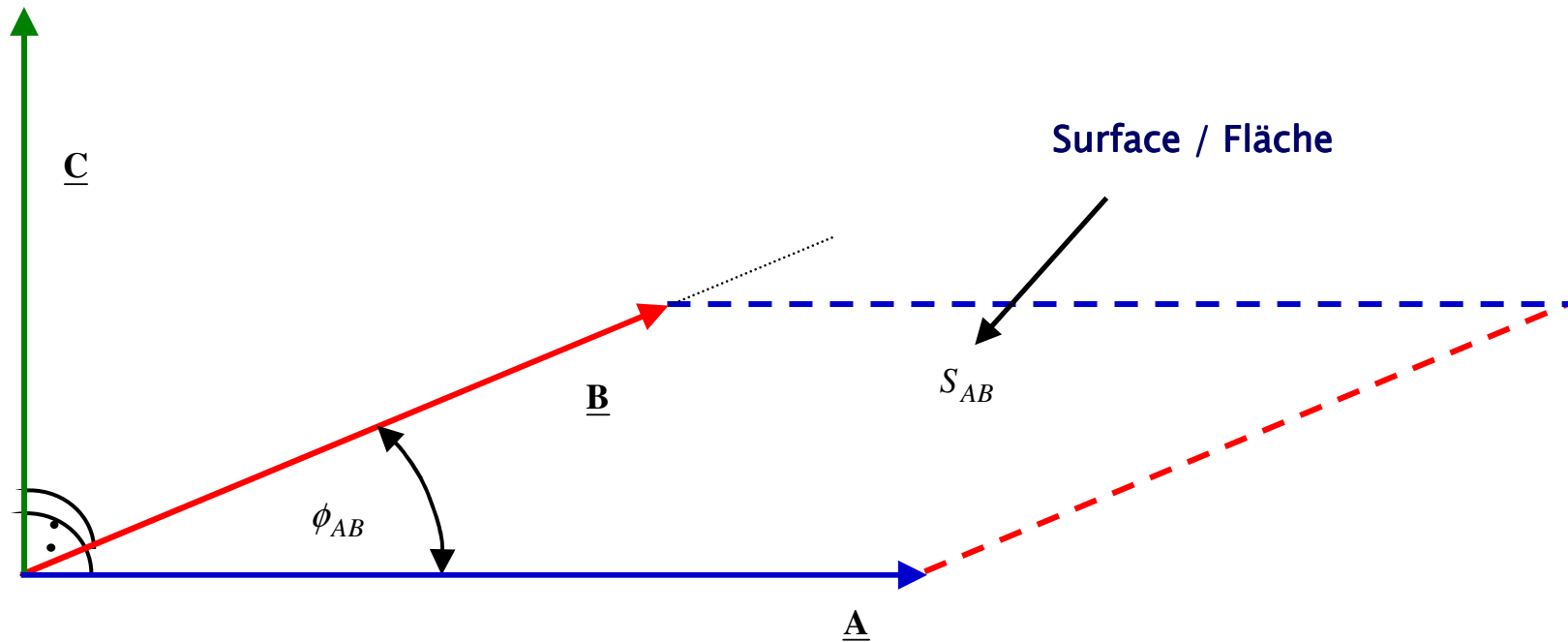
Magnitude of the Electric Field Strength Vector  
(Strength) / Betrag des elektrische Feldstärkevektors  
(Stärke)

$$\begin{aligned}|\underline{\mathbf{E}}(x, y, z)| &= \sqrt{\underline{\mathbf{E}}(x, y, z) \cdot \underline{\mathbf{E}}(x, y, z)} \\ &= \sqrt{(E_x\underline{\mathbf{e}}_x + E_y\underline{\mathbf{e}}_y + E_z\underline{\mathbf{e}}_z) \cdot (E_x\underline{\mathbf{e}}_x + E_y\underline{\mathbf{e}}_y + E_z\underline{\mathbf{e}}_z)} \\ &= \sqrt{E_x^2 + E_y^2 + E_z^2}\end{aligned}$$

Electric Field Strength Unit Vector (Direction) /  
Elektrische Feldstärkeeinheitsvektor (Richtung)

$$\begin{aligned}\hat{\underline{\mathbf{E}}}(x, y, z) &= \frac{\underline{\mathbf{E}}(x, y, z)}{|\underline{\mathbf{E}}(x, y, z)|} \\ &= \frac{E_x\underline{\mathbf{e}}_x + E_y\underline{\mathbf{e}}_y + E_z\underline{\mathbf{e}}_z}{\sqrt{E_x^2 + E_y^2 + E_z^2}}\end{aligned}$$

# Vector Product (Cross or Outer Product) / Vektorprodukt (Kreuzprodukt oder äußeres Produkt) (1)



$$\begin{aligned} \underline{C} &= \underline{A} \times \underline{B} & \underline{C} \perp \underline{A} & \text{and /} & \underline{C} \perp \underline{B} \\ C &= |\underline{A}| |\underline{B}| \sin \underbrace{\angle(\underline{A}, \underline{B})}_{\phi_{AB}} & \text{und} & & \\ &= AB \sin \phi_{AB} & & & \\ &= S_{AB} & & & \end{aligned}$$

# Vector Product (Cross or Outer Product) / Vektorprodukt (Kreuzprodukt oder äußeres Produkt) (2)

## Orthonormal Unit Vectors / Orthonormale Einheitsvektoren

$$\begin{aligned}
 \underline{\mathbf{A}} \times \underline{\mathbf{B}} &= (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \times (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z) \\
 &= A_x B_x \underbrace{\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_x}_{=0} + A_x B_y \underbrace{\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_y}_{=\underline{\mathbf{e}}_z} + A_x B_z \underbrace{\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_z}_{=-\underline{\mathbf{e}}_y} \\
 &\quad + A_y B_x \underbrace{\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_x}_{=-\underline{\mathbf{e}}_z} + A_y B_y \underbrace{\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_y}_{=0} + A_y B_z \underbrace{\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_z}_{=\underline{\mathbf{e}}_x} \\
 &\quad + A_z B_x \underbrace{\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_x}_{=\underline{\mathbf{e}}_y} + A_z B_y \underbrace{\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_y}_{=-\underline{\mathbf{e}}_x} + A_z B_z \underbrace{\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_z}_{=0} \\
 &= (A_y B_z \underline{\mathbf{e}}_x - A_z B_y) \underline{\mathbf{e}}_x + (A_z B_x - A_x B_z) \underline{\mathbf{e}}_y + (A_x B_y - A_y B_x) \underline{\mathbf{e}}_z
 \end{aligned}$$

$$\underline{\mathbf{A}} \times \underline{\mathbf{B}} = -\underline{\mathbf{B}} \times \underline{\mathbf{A}} \quad \underline{\mathbf{A}} \times \underline{\mathbf{A}} = \underline{\mathbf{0}}$$

$$\underline{\mathbf{e}}_x \perp \underline{\mathbf{e}}_y \perp \underline{\mathbf{e}}_z$$

$$\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_x = \underline{\mathbf{0}}$$

$$\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_y = \underline{\mathbf{e}}_z$$

$$\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_z = -\underline{\mathbf{e}}_y$$

$$\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_x = -\underline{\mathbf{e}}_z$$

$$\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_y = \underline{\mathbf{0}}$$

$$\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_z = \underline{\mathbf{e}}_x$$

$$\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_x = \underline{\mathbf{e}}_y$$

$$\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_y = -\underline{\mathbf{e}}_x$$

$$\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_z = \underline{\mathbf{0}}$$

# Vector Product (Cross or Outer Product) / Vektorprodukt (Kreuzprodukt oder äußeres Produkt) (3)

$$\underline{\mathbf{A}} \times \underline{\mathbf{B}} = \begin{vmatrix} \underline{\mathbf{e}}_x & \underline{\mathbf{e}}_y & \underline{\mathbf{e}}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Add the first two Columns /  
Addiere die beiden ersten Spalten

$$= \begin{vmatrix} \underline{\mathbf{e}}_x & \underline{\mathbf{e}}_y & \underline{\mathbf{e}}_z & \underline{\mathbf{e}}_x & \underline{\mathbf{e}}_y \\ A_x & A_y & A_z & A_x & A_y \\ B_x & B_y & B_z & B_x & B_y \end{vmatrix}$$

$$= (A_y B_z - A_z B_y) \underline{\mathbf{e}}_x \\ + (A_z B_x - A_x B_z) \underline{\mathbf{e}}_y \\ + (A_x B_y - A_y B_x) \underline{\mathbf{e}}_z$$

Sarrus Law /  
Regel von Sarrus

[Pierre Frédéric Sarrus, 1831]

[http://de.wikipedia.org/wiki/Regel\\_von\\_Sarrus](http://de.wikipedia.org/wiki/Regel_von_Sarrus)

# Dyadic Product / Dyadisches Produkt

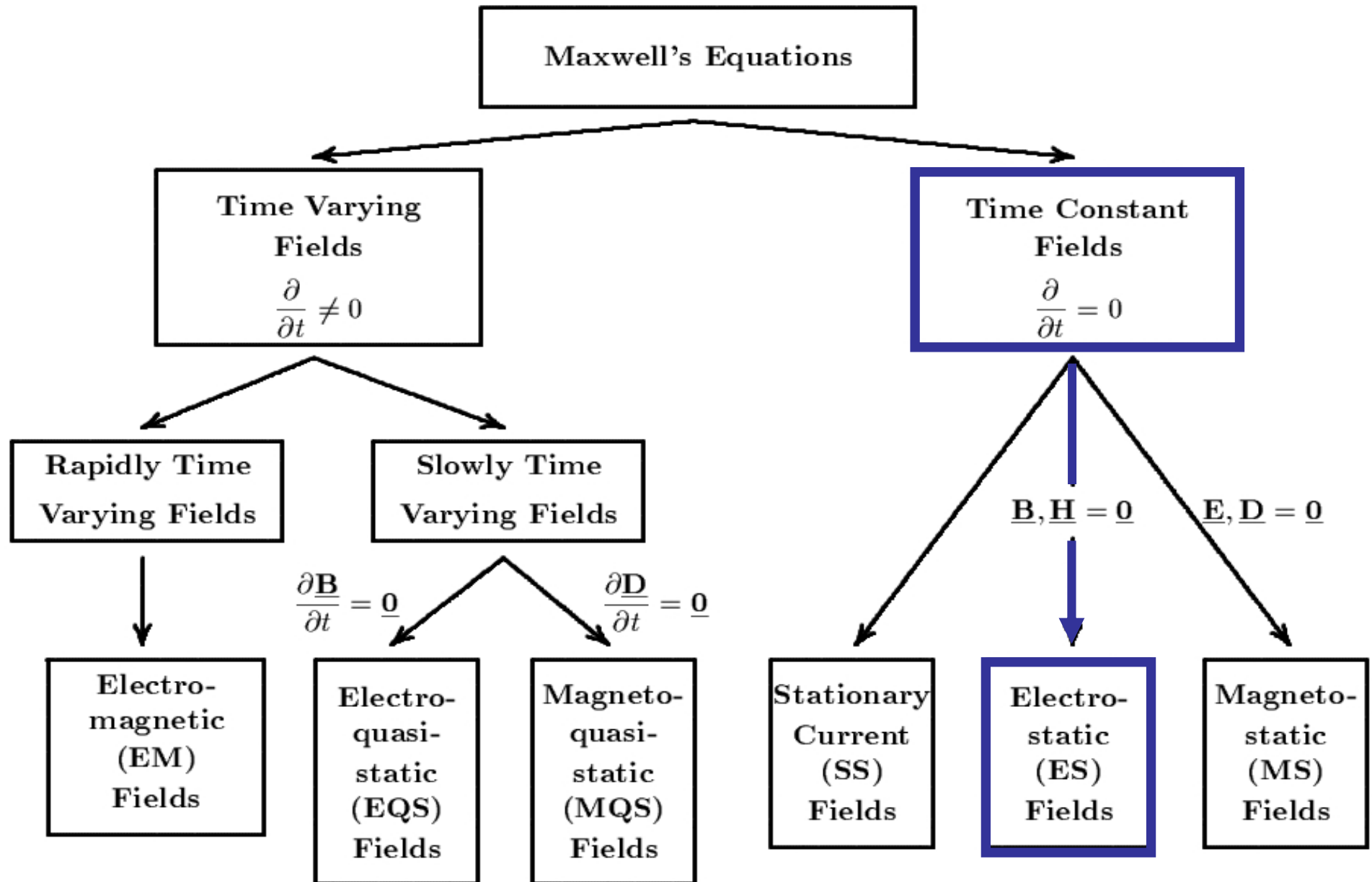
$$\begin{aligned}\underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{B}}} &= \sum_{i=1}^3 A_{x_i} \underline{\underline{\mathbf{e}}}_{x_i} \sum_{j=1}^3 B_{x_j} \underline{\underline{\mathbf{e}}}_{x_j} \\ &= \sum_{i=1}^3 \sum_{j=1}^3 A_{x_i} \underline{\underline{\mathbf{e}}}_{x_i} B_{x_j} \underline{\underline{\mathbf{e}}}_{x_j} \\ &= A_{x_i} \underline{\underline{\mathbf{e}}}_{x_i} B_{x_j} \underline{\underline{\mathbf{e}}}_{x_j} \\ &= \underbrace{A_{x_i} B_{x_j}}_{=D_{x_i x_j}} \underline{\underline{\mathbf{e}}}_{x_i} \underline{\underline{\mathbf{e}}}_{x_j} \\ &= D_{x_i x_j} \underline{\underline{\mathbf{e}}}_{x_i} \underline{\underline{\mathbf{e}}}_{x_j} \\ &= \underline{\underline{\underline{\mathbf{D}}}}\end{aligned}$$

$$\underline{\underline{\mathbf{B}}}\underline{\underline{\mathbf{A}}} \neq \underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{B}}}$$

$$\underline{\underline{\underline{\mathbf{D}}}} = \underline{\underline{\underline{\boldsymbol{\varepsilon}}}} \cdot \underline{\underline{\underline{\mathbf{E}}}}$$

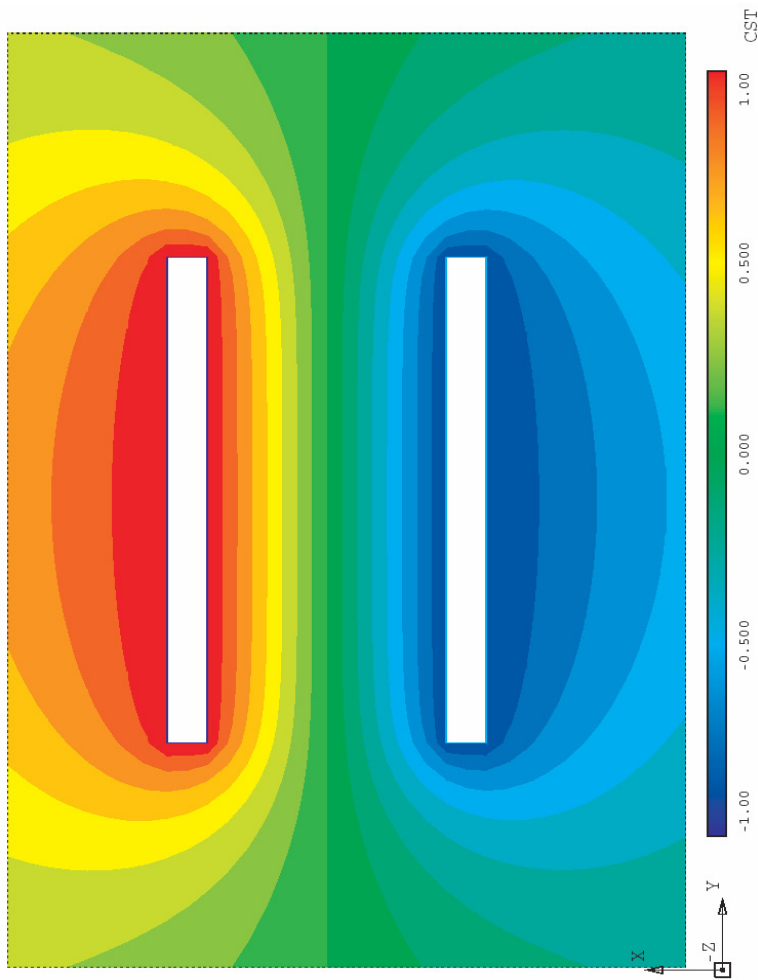
$$\underline{\underline{\underline{\mathbf{B}}}} = \underline{\underline{\underline{\boldsymbol{\mu}}}} \cdot \underline{\underline{\underline{\mathbf{H}}}}$$

# Electrostatic (ES) Fields / Elektrostatische (ES) Felder

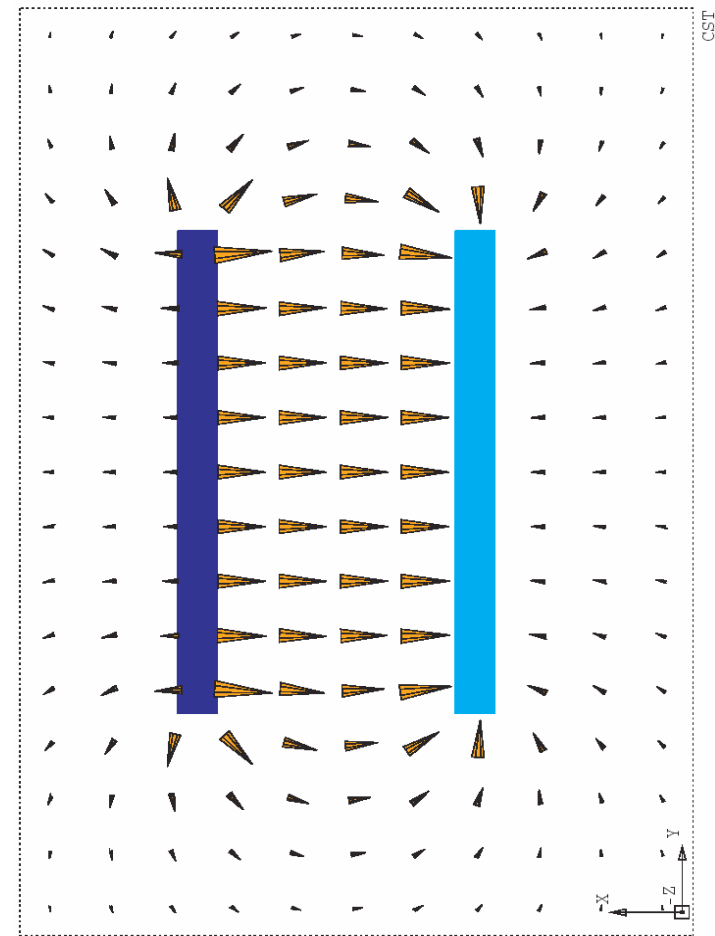


# Electrostatic Field Problem – Example: Parallel Plate Capacitor / Elektrostatisches Feldproblem – Beispiel: Paralleler Plattenkondensator

Scalar Field: Electrostatic Potential /  
Skalarfeld: Elektrostatisches Potenzial



Vector Field: Electrostatic Field Strength /  
Vektorfeld: Elektrostatische Feldstärke



# Electrostatic (ES) Fields – Governing Equations / Elektrostatische (ES) Felder – Grundgleichungen

Electrostatic /  
Elektrostatik  $\frac{\partial}{\partial t} \equiv 0$  No Time Dependence and No Magnetic Field Quantities /  
Keine Zeitabhängigkeit und keine magnetischen Feldgrößen

$\underline{\mathbf{E}}(\underline{\mathbf{R}})$ : Electric Field Strength / Elektrische Feldstärke  
 $\underline{\mathbf{D}}(\underline{\mathbf{R}})$ : Electric Flux Density / Elektrische Flussdichte  
 $\rho_e(\underline{\mathbf{R}})$ : Electric Charge Density / Elektrische Raumladungsdichte

Integral Form /  
Integralform

Differential Form /  
Differentialform

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dR}} = 0$$

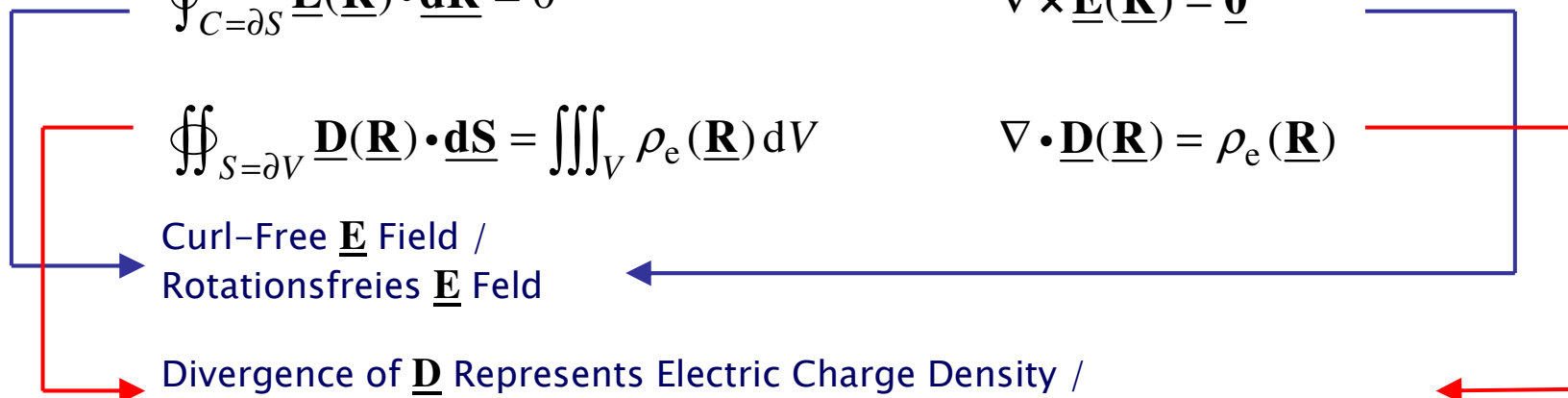
$$\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}) = \underline{\mathbf{0}}$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} = \iiint_V \rho_e(\underline{\mathbf{R}}) dV$$

$$\nabla \cdot \underline{\mathbf{D}}(\underline{\mathbf{R}}) = \rho_e(\underline{\mathbf{R}})$$

Curl-Free  $\underline{\mathbf{E}}$  Field /  
Rotationsfreies  $\underline{\mathbf{E}}$  Feld

Divergence of  $\underline{\mathbf{D}}$  Represents Electric Charge Density /  
Quellstärke von  $\underline{\mathbf{D}}$  entspricht der elektrischen Raumladungsdichte





# Electrostatic (ES) Fields – Governing Equations / Elektrostatische (ES) Felder – Grundgleichungen

## Integral Form / Integralform

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dR}} = 0$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} = \iiint_V \rho_e(\underline{\mathbf{R}}) dV$$

$$= Q_e$$

$$\underline{\mathbf{E}}(\underline{\mathbf{R}}) \quad [\text{V/m} = \text{Newton /Coulomb} = \text{N/C}]$$

$$\underline{\mathbf{D}}(\underline{\mathbf{R}}) \quad [\text{As/ m}^2]$$

$$\rho_e(\underline{\mathbf{R}}) \quad [\text{As/m}^3]$$

## Vacuum / Vakuum

$$\underline{\mathbf{D}}(\underline{\mathbf{R}}) = \varepsilon_0 \underline{\mathbf{E}}(\underline{\mathbf{R}})$$

Electric Field Constant / Elektrische Feldkonstante  
(IEEE, VDE)  
Permittivity of Free Space / Permittivität des Freiraumes

## Differential Form / Differentialform

$$\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}) = \underline{\mathbf{0}}$$

$$\nabla \cdot \underline{\mathbf{D}}(\underline{\mathbf{R}}) = \rho_e(\underline{\mathbf{R}})$$

Side Remark: In some Cases /  
Nebenbemerkung: In einigen Fällen

$$\underline{\mathbf{D}}(\underline{\mathbf{R}}) = \varepsilon_0 \varepsilon_r \underline{\mathbf{E}}(\underline{\mathbf{R}})$$

Permittivity /  
Permittivität

Material	$\varepsilon_r$
Air / Luft	1.006
Paper / Papier	2...4
Wet Earth / Nasse Erde	5...15
Gallium Arsenide / Gallium Arsenid	13
Seawater / Seewasser	70

# ES Fields – Electric Points Charge and Electric Field Strength – Coulomb’s Law / ES Felder – Elektrische Punktladung und elektrische Feldstärke – Coulombsches Gesetz

## Coulomb’s Law / Coulombsches Gesetz

Charles Augustin de Coulomb (1736 – 1806)

$$\underline{\mathbf{F}}(\underline{\mathbf{R}}) = \frac{1}{4\pi\epsilon} \frac{Q_e^{(1)} Q_e^{(2)}}{R_{12}^2} \hat{\underline{\mathbf{R}}}_{12} \quad [\text{N}]$$

Force /  
Kraft

$$\underline{\mathbf{F}}(\underline{\mathbf{R}}) \quad [\text{N}]$$

Electric Point Charge /  
Elektrische Punktladung

$$Q_e^{(1)} \quad [\text{As}]$$

Electric Point Charge /  
Elektrische PunktLadung

$$Q_e^{(2)} \quad [\text{As}]$$

Distance /  
Abstand

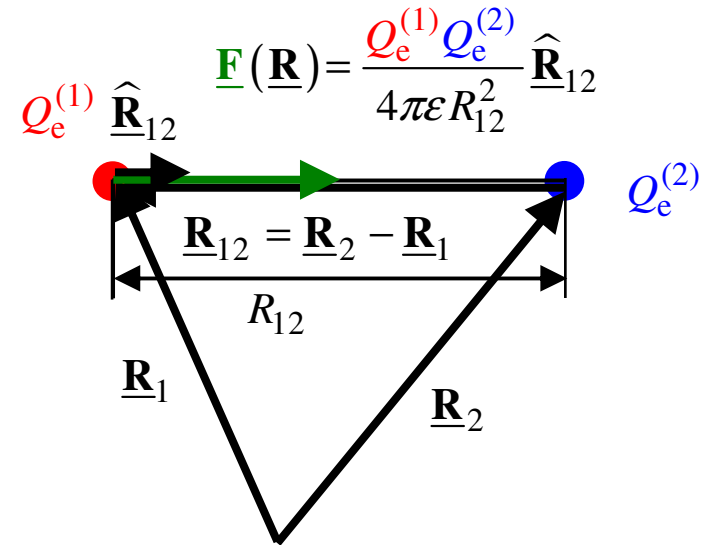
$$R \quad [\text{m}]$$

Distance Unit Vector /  
Abstandseinheitsvektor

$$\hat{\underline{\mathbf{R}}} \quad [1]$$

Permittivity of Free-Space /  
Permittivität des Freiraumes

$$\epsilon \quad [\text{As/Vm}]$$



$$\hat{\underline{\mathbf{R}}} = \frac{\underline{\mathbf{R}}}{|\underline{\mathbf{R}}|} = \frac{\underline{\mathbf{R}}}{R} \quad [1] \quad R = |\underline{\mathbf{R}}| = \sqrt{\underline{\mathbf{R}} \cdot \underline{\mathbf{R}}} \quad [\text{m}]$$

$$\underline{\mathbf{R}} = x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z$$

$$R = \sqrt{\underline{\mathbf{R}} \cdot \underline{\mathbf{R}}} = \sqrt{x^2 + y^2 + z^2}$$

$$\hat{\underline{\mathbf{R}}} = \frac{x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z}{\sqrt{x^2 + y^2 + z^2}} = \underline{\mathbf{e}}_R(\vartheta, \varphi)$$

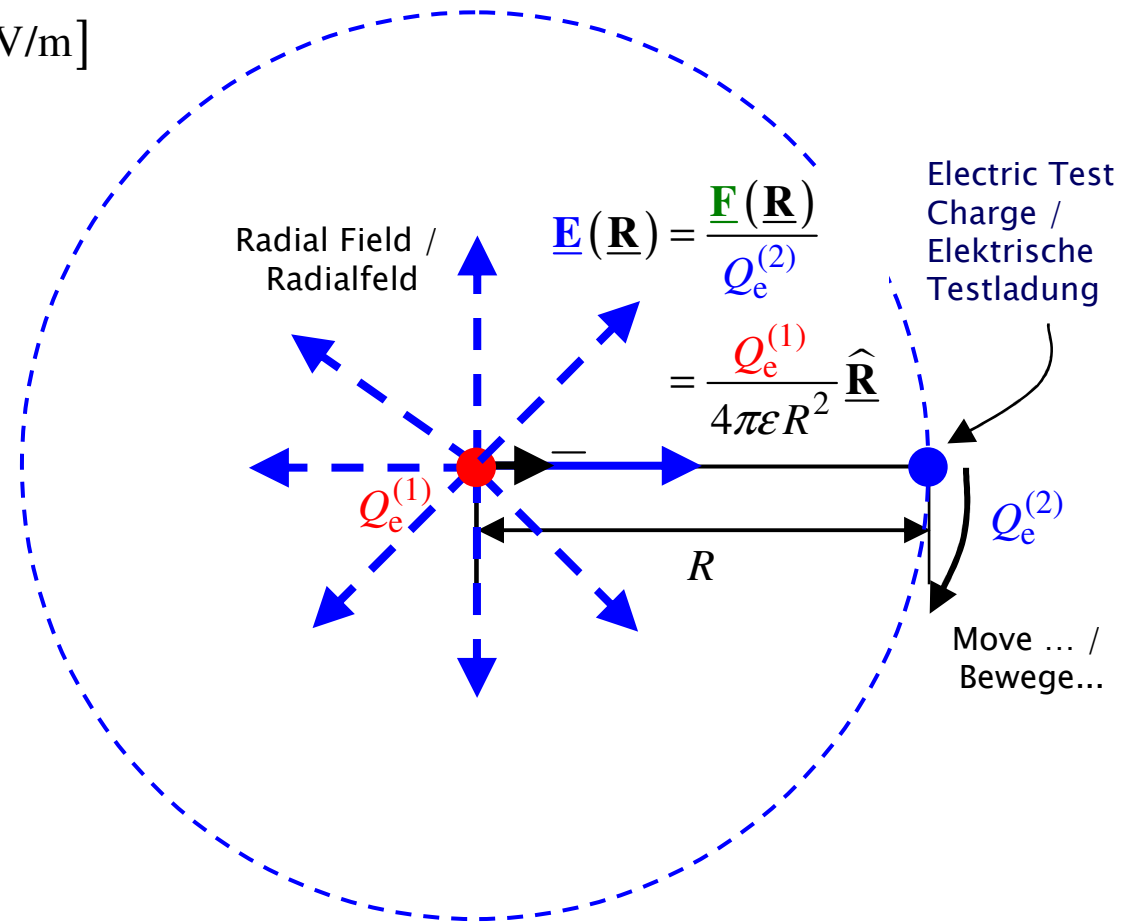
# ES Fields – Electric Charge and Electric Field Strength – Coulomb’s Law / ES Felder – Elektrische Ladung und elektrische Feldstärke – Coulombsches Gesetz

**Electric Field Strength: Force Per Unit Charge /  
Elektrische Feldstärke: Kraft pro Einheitsladung**

$Q_e^{(2)}$  Electric Test Charge /  
Elektrische Testladung

$$\underline{\mathbf{E}}(\underline{\mathbf{R}}) = \frac{\underline{\mathbf{F}}(\underline{\mathbf{R}})}{Q_e^{(2)}} = \frac{Q_e^{(1)}}{4\pi\epsilon R^2} \hat{\underline{\mathbf{R}}} \quad [\text{N/C or V/m}]$$

Electric Field Strength / Elektrische Feldstärke	$\underline{\mathbf{E}}(\underline{\mathbf{R}})$	[V/m]
Force / Kraft	$\underline{\mathbf{F}}(\underline{\mathbf{R}})$	[N]
Electric Charge / Elektrische Ladung	$Q_e^{(1)}$	[As]
Electric Test Charge / Elektrische Testladung	$Q_e^{(2)}$	[As]
Distance / Abstand	$R$	[m]
Distance Unit Vector / Abstandseinheitsvektor	$\hat{\underline{\mathbf{R}}}$	[1]
Permittivity of Free-Space / Permittivität des Freiraumes	$\epsilon$	[As/Vm]



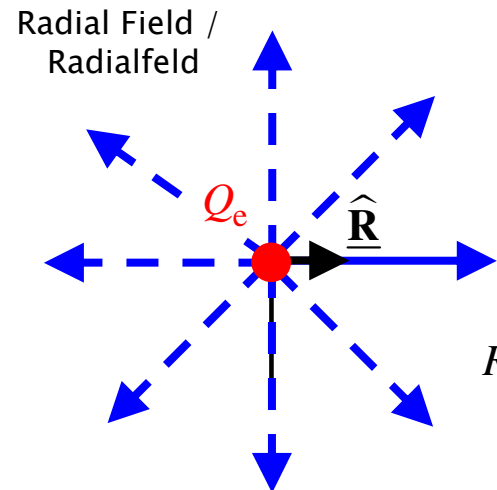
# ES Fields – Electric Charge and Electric Field Strength – Coulomb’s Law / ES Felder – Elektrische Ladung und elektrische Feldstärke – Coulombsches Gesetz

Electric Field Strength: Force Per Unit Charge /  
Elektrische Feldstärke: Kraft pro Einheitsladung

$$\underline{\mathbf{E}}(\underline{\mathbf{R}}) = \frac{Q_e}{4\pi\epsilon R^2} \hat{\underline{\mathbf{R}}} = \frac{Q_e}{4\pi\epsilon R} \underline{\mathbf{R}} \quad [\text{V/m}]$$

$$\underline{\mathbf{R}} = R \hat{\underline{\mathbf{R}}}$$

Electric Field Strength / Elektrische Feldstärke	$\underline{\mathbf{E}}(\underline{\mathbf{R}})$	[V/m]
Electric Charge / Elektrische Ladung	$Q_e$	[As]
Distance / Abstand	$R$	[m]
Distance Unit Vector / Abstandseinheitsvektor	$\hat{\underline{\mathbf{R}}}$	[1]
Permittivity of Free-Space / Permittivität des Freiraumes	$\epsilon$	[As/Vm]



$$\underline{\mathbf{E}}(\underline{\mathbf{R}}) = \frac{Q_e}{4\pi\epsilon R^2} \hat{\underline{\mathbf{R}}}$$

$$= \frac{Q_e}{4\pi\epsilon R} \underline{\mathbf{R}}$$

# Electrostatic (ES) Fields – Governing Equations / Elektrostatische (ES) Felder – Grundgleichungen

Electrostatic /  
Elektrostatik  $\frac{\partial}{\partial t} \equiv 0$

No Time Dependence and No Magnetic Field Quantities /  
Keine Zeitabhängigkeit und keine magnetischen Feldgrößen

$\underline{\mathbf{E}}(\underline{\mathbf{R}})$ : Electric Field Strength / Elektrische Feldstärke

$\underline{\mathbf{D}}(\underline{\mathbf{R}})$ : Electric Flux Density / Elektrische Flussdichte

$\rho_e(\underline{\mathbf{R}})$ : Electric Charge Density / Elektrische Raumladungsdichte

Integral Form /  
Integralform

Differential Form /  
Differentialform

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dR}} = 0$$

$$\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}) = \underline{\mathbf{0}}$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} = \iiint_V \rho_e(\underline{\mathbf{R}}) dV$$

$$\nabla \cdot \underline{\mathbf{D}}(\underline{\mathbf{R}}) = \rho_e(\underline{\mathbf{R}})$$

Curl-Free  $\underline{\mathbf{E}}$ -Field /  
Rotationsfreies  $\underline{\mathbf{E}}$ -Feld

Divergence of  $\underline{\mathbf{D}}$  Represents Electric Charge Density /  
Quellstärke von  $\underline{\mathbf{D}}$  entspricht der elektrischen Raumladungsdichte



Method of Gauss' Electric Law /  
Methode des Gaußschen elektrischen Gesetzes

# ES Fields – Method of Electric Gauss' Law / ES-Felder – Methode des elektrischen Gaußschen Gesetzes

Source Distribution / Quellverteilung

$$\rho_e(\underline{\mathbf{R}}) = \begin{cases} \neq 0 & \underline{\mathbf{R}} \in V_s \\ = 0 & \underline{\mathbf{R}} \notin V_s \end{cases}$$

Source Volume /  
Quellvolumen

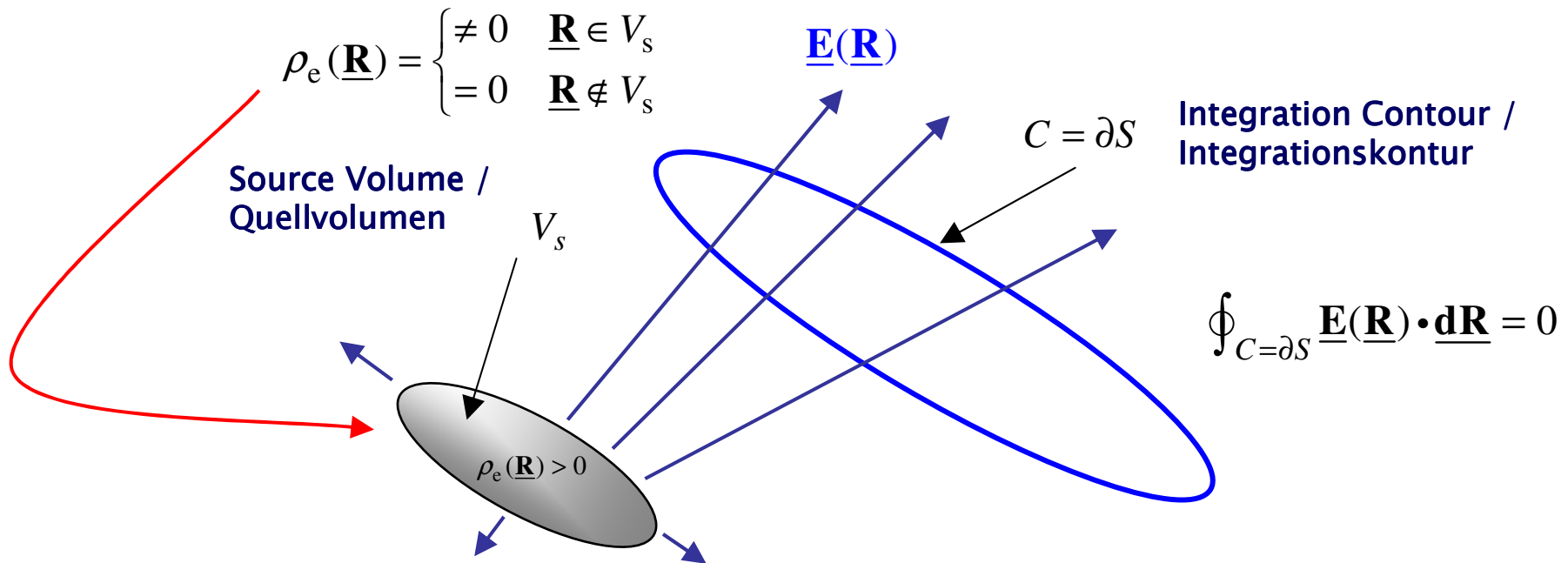
$V_s$

$\underline{\mathbf{E}}(\underline{\mathbf{R}})$

$C = \partial S$

Integration Contour /  
Integrationskontur

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dR}} = 0$$

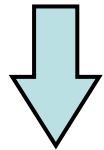


# ES Fields – Method of Electric Gauss’ Law / ES-Felder – Methode des elektrischen Gaußschen Gesetzes

Source Distribution / Quellverteilung

$$\rho_e(\underline{\mathbf{R}}) = \begin{cases} \neq 0 & \underline{\mathbf{R}} \in V_s \\ = 0 & \underline{\mathbf{R}} \notin V_s \end{cases}$$

$$\psi_e = \oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} = \iiint_V \rho_e(\underline{\mathbf{R}}) dV$$



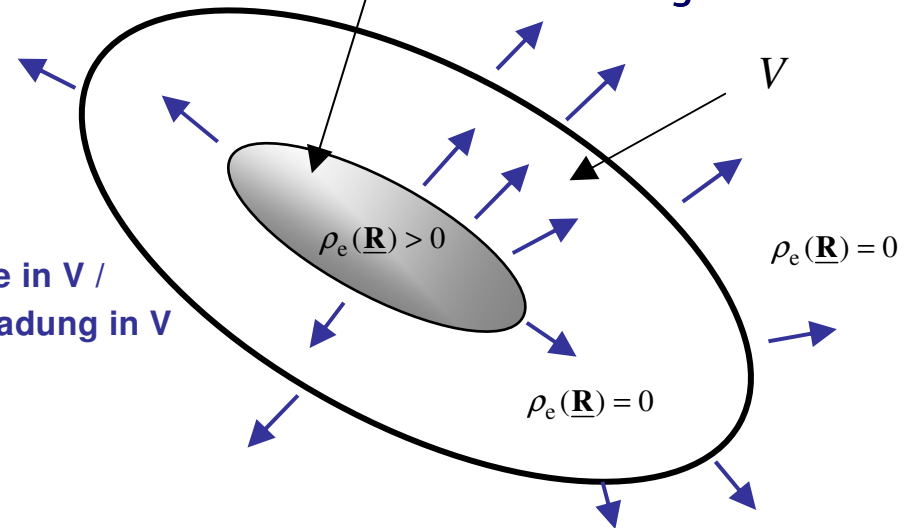
$$\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} = \underbrace{\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}}_{D_n(\underline{\mathbf{R}})} dS$$

$$\underbrace{\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}}}_{\oiint_{S=\partial V} \underbrace{\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}}_{D_n(\underline{\mathbf{R}})} dS}}$$

Summation of all  $D_n = \underline{\mathbf{n}} \cdot \underline{\mathbf{D}}$  Contributions /  
Summation aller  $D_n = \underline{\mathbf{n}} \cdot \underline{\mathbf{D}}$ -Beiträge

Source Volume /  
Quellvolumen  $V_s$

Integration Volume /  
Integrationsvolumen  $V$



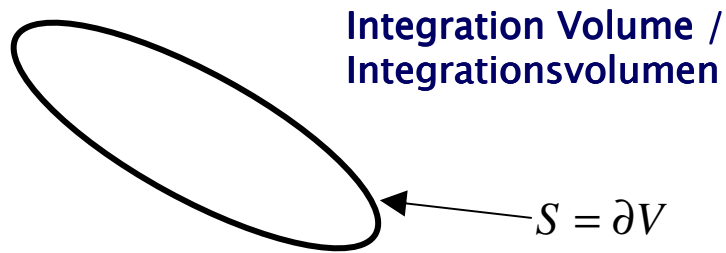
$$= \underbrace{\iiint_V \rho_e(\underline{\mathbf{R}}) dV}_{Q_e}$$

Total electric charge inside the  
volume  $V$  with the closed surface  $S=\partial V$  /  
Gesamte elektrische Ladung im Volumen  
 $V$  mit der geschlossenen Oberfläche  $S=\partial V$

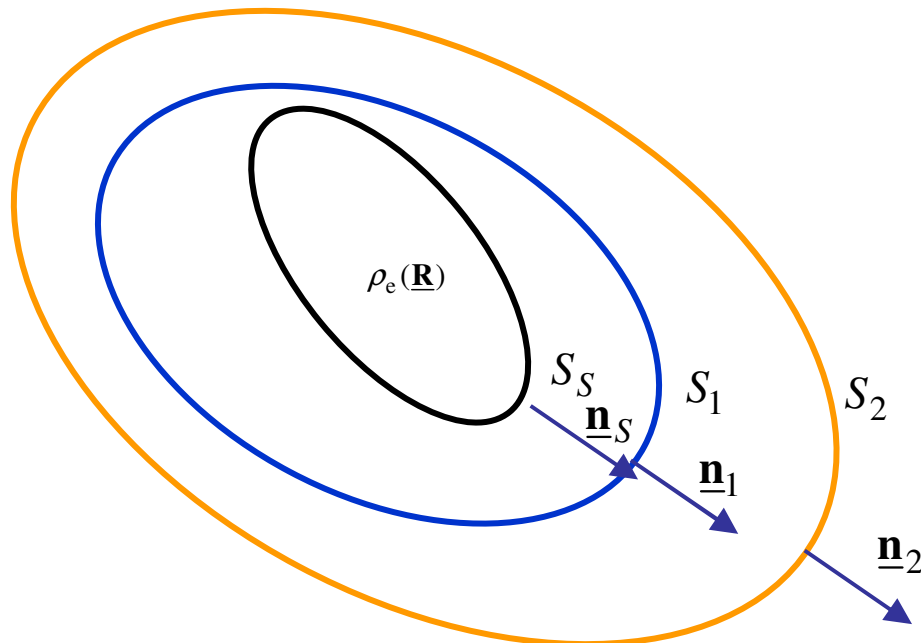
Flux of  $\underline{\mathbf{D}}$  through  $S = Q_e$  in  $V$  /  
Fluss von  $\underline{\mathbf{D}}$  durch  $S = Q_e$  in  $V$

# ES Fields – Method of Electric Gauss' Law / ES-Felder – Methode des elektrischen Gaußschen Gesetzes

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} = \iiint_V \rho_e(\underline{\mathbf{R}}) dV = Q_e$$



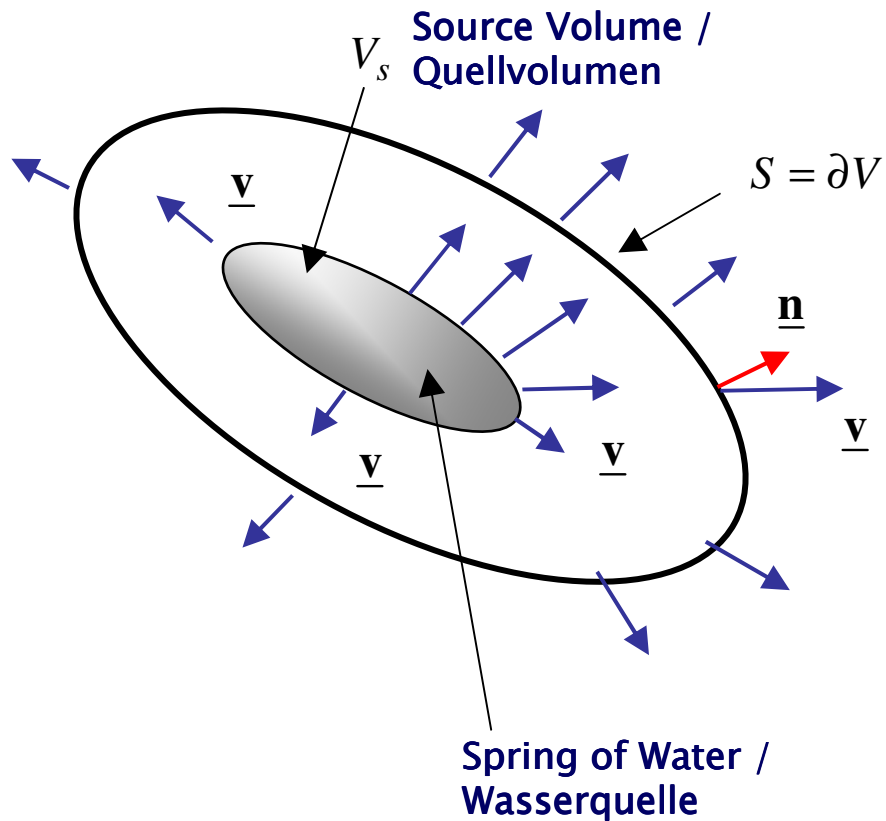
$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} \begin{cases} = 0 & \text{source-free / quellenfrei} \\ > 0 & \text{Source / Quelle} \\ < 0 & \text{Sink / Senke} \end{cases}$$



$$\begin{aligned} & \oiint_{S_S=\partial V_S} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}_S dS \\ &= \oiint_{S_1=\partial V_1} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}_1 dS \\ &= \oiint_{S_2=\partial V_2} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}_2 dS \\ &= Q_e \end{aligned}$$



# Example: Fluid Mechanics – Spring of Water / Beispiel: Strömungsmechanik – Wasserquelle



Integration Surface (Closed Surface) /  
Integrationsfläche (geschlossene Oberfläche)

Total Flux through the Closed Surface /  
Gesamtfluss durch die geschlossene Oberfläche

$$\begin{aligned}
 \oiint_{S=\partial V} \underline{v}(\underline{\mathbf{R}}) \cdot \underline{dS} &= \oiint_{S=\partial V} \underbrace{\underline{v}(\underline{\mathbf{R}}) \cdot \underline{n}}_{=v_n(\underline{\mathbf{R}})} dS \\
 &= \oiint_{S=\partial V} v_n(\underline{\mathbf{R}}) dS \\
 &= \psi_v
 \end{aligned}$$

# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

Consider the Electrostatic (ES) Case /  
Betrachte den elektrostatischen (ES) Fall

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}} = \oiint_{S=\partial V} \underbrace{\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}}_{=D_n(\underline{\mathbf{R}})} dS = \underbrace{\iiint_V \rho_e(\underline{\mathbf{R}}) dV}_{=Q_e}$$

Prescribed: Electric Charge Density /  
Vorgegeben: Elektrische Raumladungsdichte

$$\rho_e(\underline{\mathbf{R}}) = \rho_e(R) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

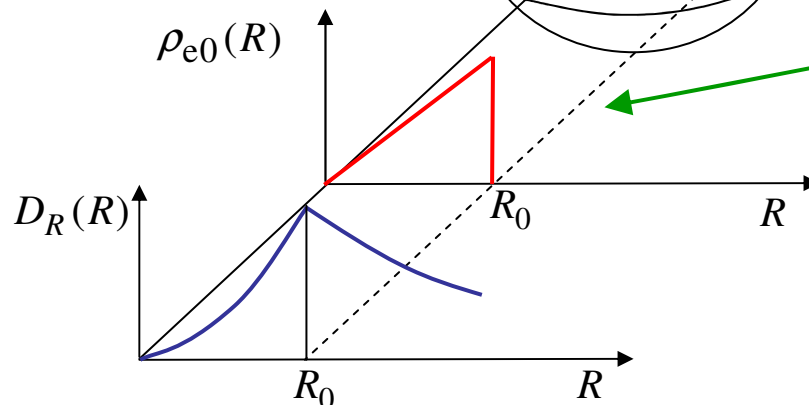
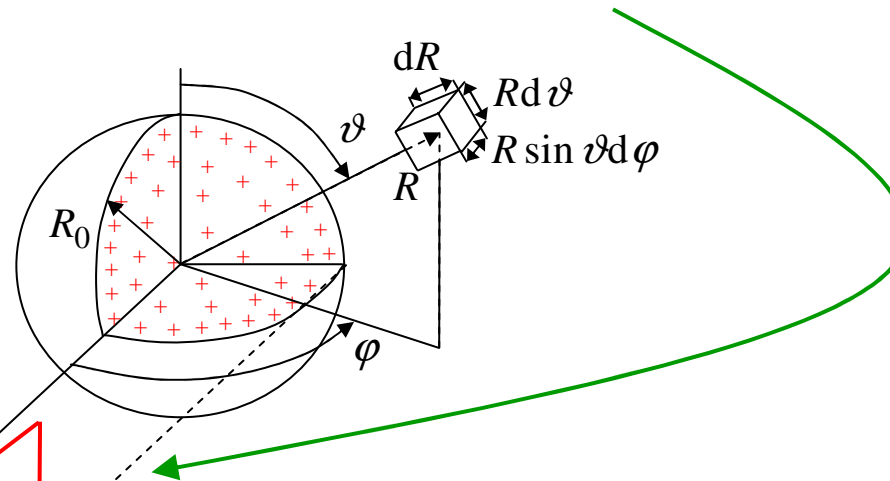
Charged Sphere with Radius  $R_0$  /  
Geladene Kugel mit dem Radius  $R_0$

Radial Symmetry /  
Radialsymmetrie

$$\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}} = \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{e}}_R$$

$$= D_n(\underline{\mathbf{R}}) \quad = D_R(\underline{\mathbf{R}})$$

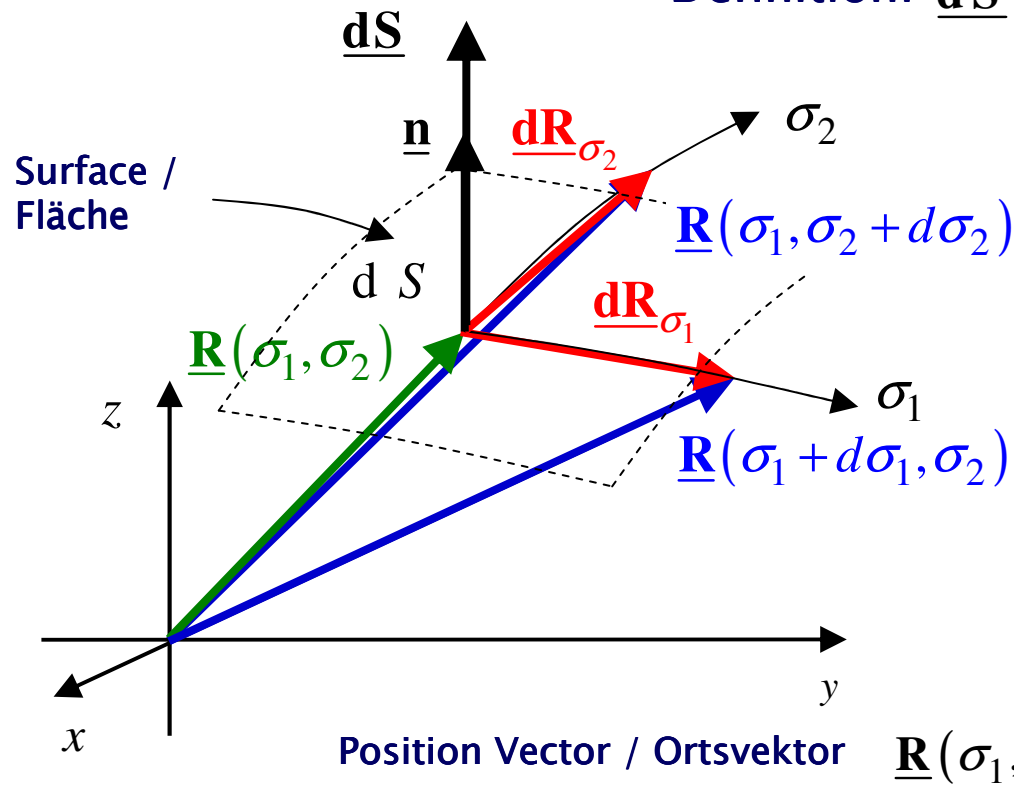
$$D_n(\underline{\mathbf{R}}) = D_R(\underline{\mathbf{R}})$$



Solution for  $\underline{\mathbf{D}}(\underline{\mathbf{R}})$  /  
Lösung für  $\underline{\mathbf{D}}(\underline{\mathbf{R}})$

# Vector Differential Surface Element / Vektoriellles differentielles Flächenelement (1)

Definition:  $\underline{dS} = \underline{n} dS$



$\sigma_1, \sigma_2$  Surface Parameters /  
Flächenparameter

$\underline{R}(\sigma_1, \sigma_2)$  Position Vector /  
Ortsvektor

$\underline{R}(\sigma_1 + d\sigma_1, \sigma_2)$  Position Vectors /  
Ortsvektoren  
 $\underline{R}(\sigma_1, \sigma_2 + d\sigma_2)$

$\underline{dR}_{\sigma_1}$  Vector Differential Line  
Elements / Vektorielle  
differentielle  
Linielemente  
 $\underline{dR}_{\sigma_2}$

Tangential Vectors / Tangentialvektoren

$$\underline{\sigma}_1(\sigma_1, \sigma_2) = \frac{\partial}{\partial \sigma_1} \underline{R}(\sigma_1, \sigma_2)$$

$$\underline{\sigma}_2(\sigma_1, \sigma_2) = \frac{\partial}{\partial \sigma_2} \underline{R}(\sigma_1, \sigma_2)$$

# Vector Differential Surface Element / Vektoriellles differentielles Flächenelement (2)

## Vector Differential Line Elements / Vektoriellles differentielles Linienelement

$$\underline{dR}_{\sigma_1} = \underline{\sigma}_1(\sigma_1, \sigma_2) d\sigma_1$$

$$\underline{dR}_{\sigma_2} = \underline{\sigma}_2(\sigma_1, \sigma_2) d\sigma_2$$

## Scalar Differential Surface Elements / Skalares differentielles Flächenelement

$$\begin{aligned} dS &= \left| \underline{dR}_{\sigma_1} \times \underline{dR}_{\sigma_2} \right| \\ &= \left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right| d\sigma_1 d\sigma_2 \end{aligned}$$

## Normal Unit-Vector / Normaleneinheitsvektor

$$\underline{n} = \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{\left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right|}$$

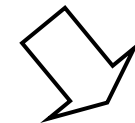
## Vector Differential Surface Element / Vektoriellles differentielles Flächenelement

$$\begin{aligned} \underline{dS} &= \underline{n} dS \\ &= \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{\left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right|} \left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right| d\sigma_1 d\sigma_2 \\ &= \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) d\sigma_1 d\sigma_2 \end{aligned}$$

# Gauss' Electric Law / Gaußsches elektrisches Gesetz

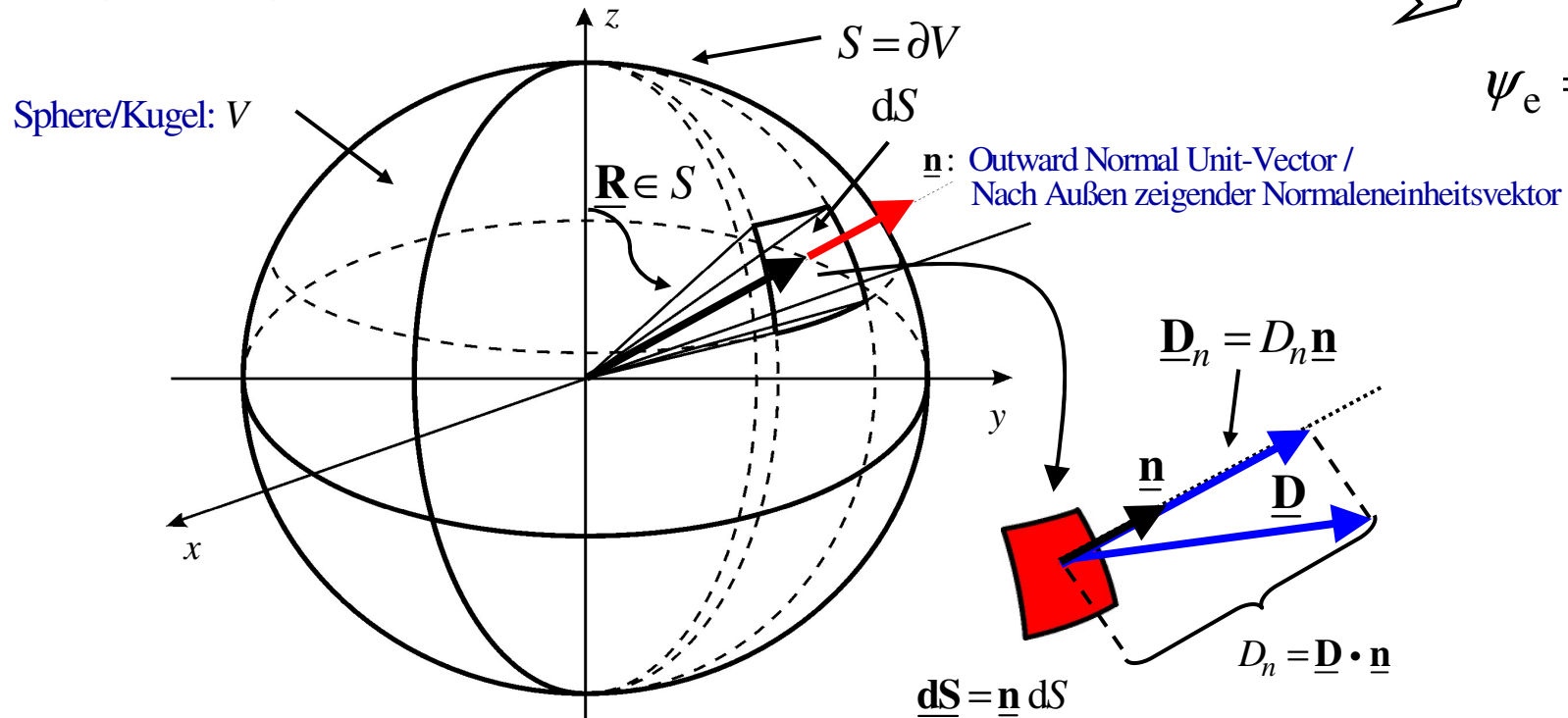
$$\underbrace{\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{dS}}}_{\text{Closed Surface Integral / Geschlossenes Flächenintegral}} = \underbrace{\oiint_{S=\partial V} \underbrace{\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}}_{=D_n(\underline{\mathbf{R}})} dS}_{\substack{\text{Summation of all Normal Components of } \underline{\mathbf{D}} \\ \text{at the Closed Surface } S=\partial V \text{ of} \\ \text{the Volume } V / \\ \text{Summation aller Normalkomponenten von } \underline{\mathbf{D}} \\ \text{auf der geschlossenen Oberfläche } S=\partial V \text{ des} \\ \text{Volumens } V}} = \underbrace{\iiint_V \rho_e(\underline{\mathbf{R}}) dV}_{\substack{\text{Volume Integral /} \\ \text{Volumenintegral}}}$$

$=\psi_e$   $=Q_e$   
 Flux Through the Closed Surface / Summation of all charges  
 Fluss durch die geschlossene Oberfläche inside the Volume  $V$  /  
Summation aller Ladungen in  
dem Volumen  $V$

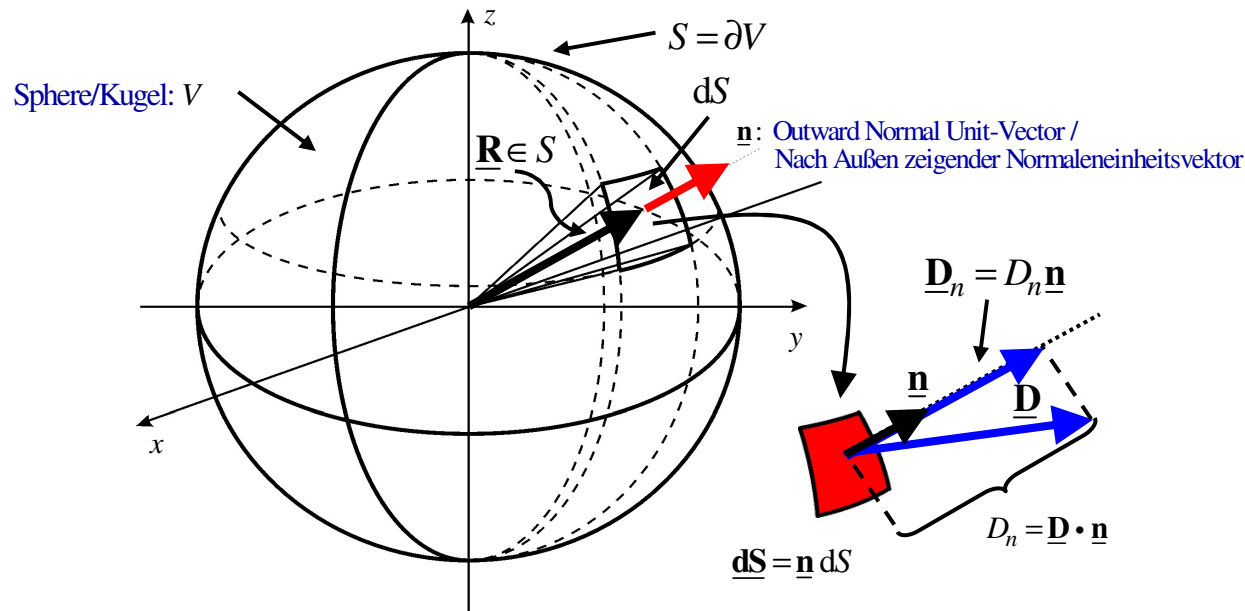


$$\psi_e = Q_e$$

## Example / Beispiel:



# Example: Sphere with Radius $a$ / Beispiel: Kugel mit Radius $a$ (1)



$$\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS$$

$$= \iiint_V \rho_e(\mathbf{R}) dV$$

$$\underline{dS} = \underline{n} dS \quad (= \underline{n}_{\vartheta\varphi} h_{\vartheta} h_{\varphi} d\vartheta d\varphi)$$

$$= \underbrace{\underline{e}_R(\vartheta, \varphi)}_{\underline{n}} \underbrace{R^2 \sin \vartheta d\vartheta d\varphi}_{dS} \Big|_{R=a} = \underbrace{\underline{e}_R(\vartheta, \varphi)}_{\underline{n}} \underbrace{a^2 \sin \vartheta d\vartheta d\varphi}_{dS}$$

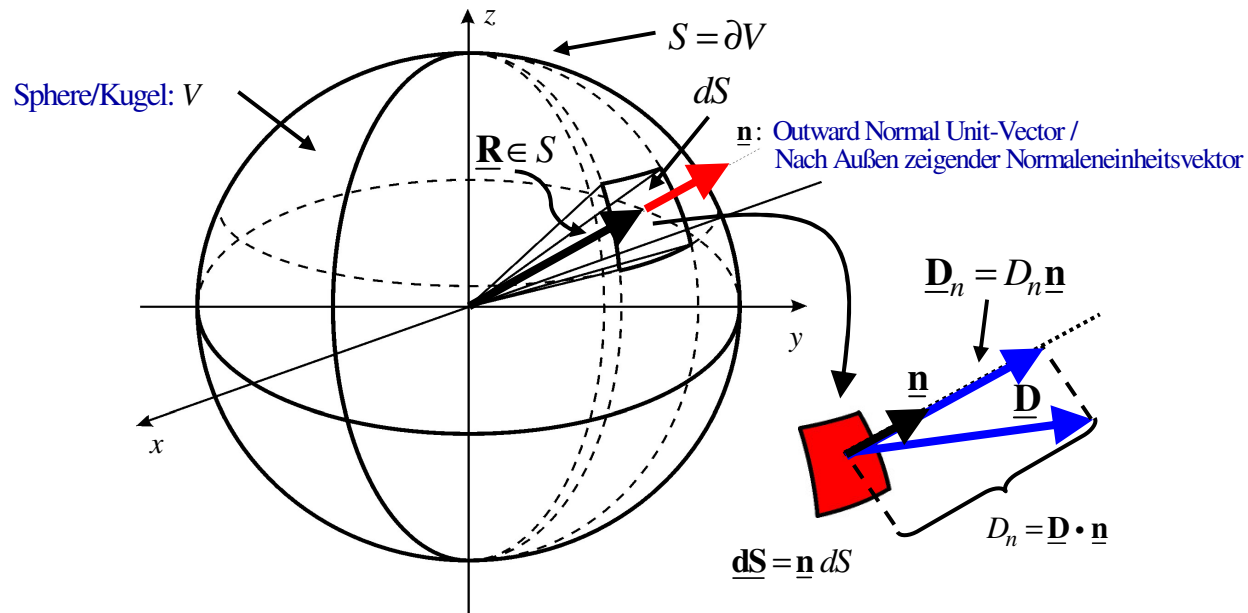
$$0 \leq \vartheta \leq \pi$$

$$0 \leq \varphi < 2\pi$$

$$\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot \underline{dS} = \oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS = \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi} \underbrace{\mathbf{D}[\mathbf{R}(R=a, \vartheta, \varphi)] \cdot \underline{e}_R(\vartheta, \varphi)}_{\substack{=D_R[\mathbf{R}(R=a, \vartheta, \varphi)] \\ =D_n[\mathbf{R}(R=a, \vartheta, \varphi)]}} a^2 \sin \vartheta d\vartheta d\varphi$$

$$= \psi_e$$

## Example: Sphere with Radius $a$ / Beispiel: Kugel mit Radius $a$ (2)



$$\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{D_n(\mathbf{R})} dS$$

$$= \iiint_V \rho_e(\mathbf{R}) dV$$

$$dV = R^2 \sin \vartheta dR d\vartheta d\varphi \quad (= h_R h_\vartheta h_\varphi dR d\vartheta d\varphi)$$

$$\iiint_V \rho_e(\mathbf{R}) dV = \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi} \int_{R=0}^a \rho_e[\mathbf{R}(R, \vartheta, \varphi)] R^2 \sin \vartheta dR d\vartheta d\varphi$$

$$= Q_e$$

$$0 \leq R \leq a$$

$$0 \leq \vartheta \leq \pi$$

$$0 \leq \varphi < 2\pi$$

# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

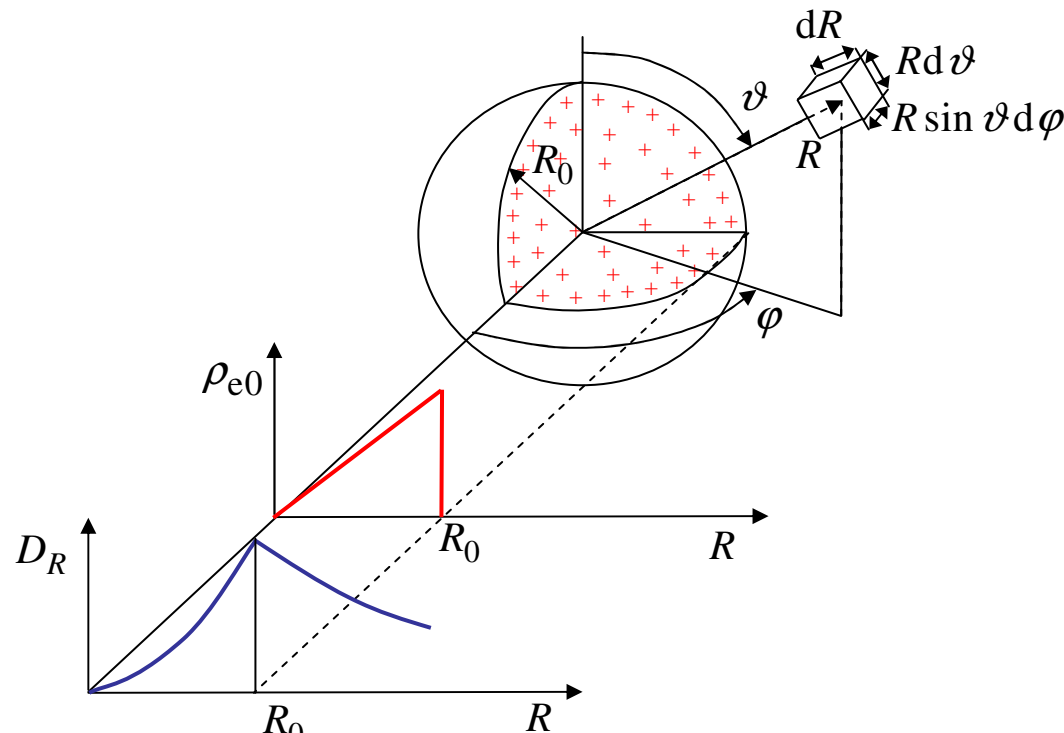
Consider the Electrostatic (ES) Case /  
 Betrachte den elektrostatischen Fall

$$\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS = \iiint_V \rho_e(\mathbf{R}) dV$$

Electric Charge Density /  
 Elektrische Raumladungsdichte

$$\rho_e(\mathbf{R}) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

Radial Symmetry /  
 Radialsymmetrisch





# Metric Coefficients / Metrische Koeffizienten

Cartesian Coordinates /  
Kartesische Koordinaten

$$x, y, z = x_1, x_2, x_3$$

$$\underline{e}_x, \underline{e}_y, \underline{e}_z = \underline{e}_{x_1}, \underline{e}_{x_2}, \underline{e}_{x_3}$$

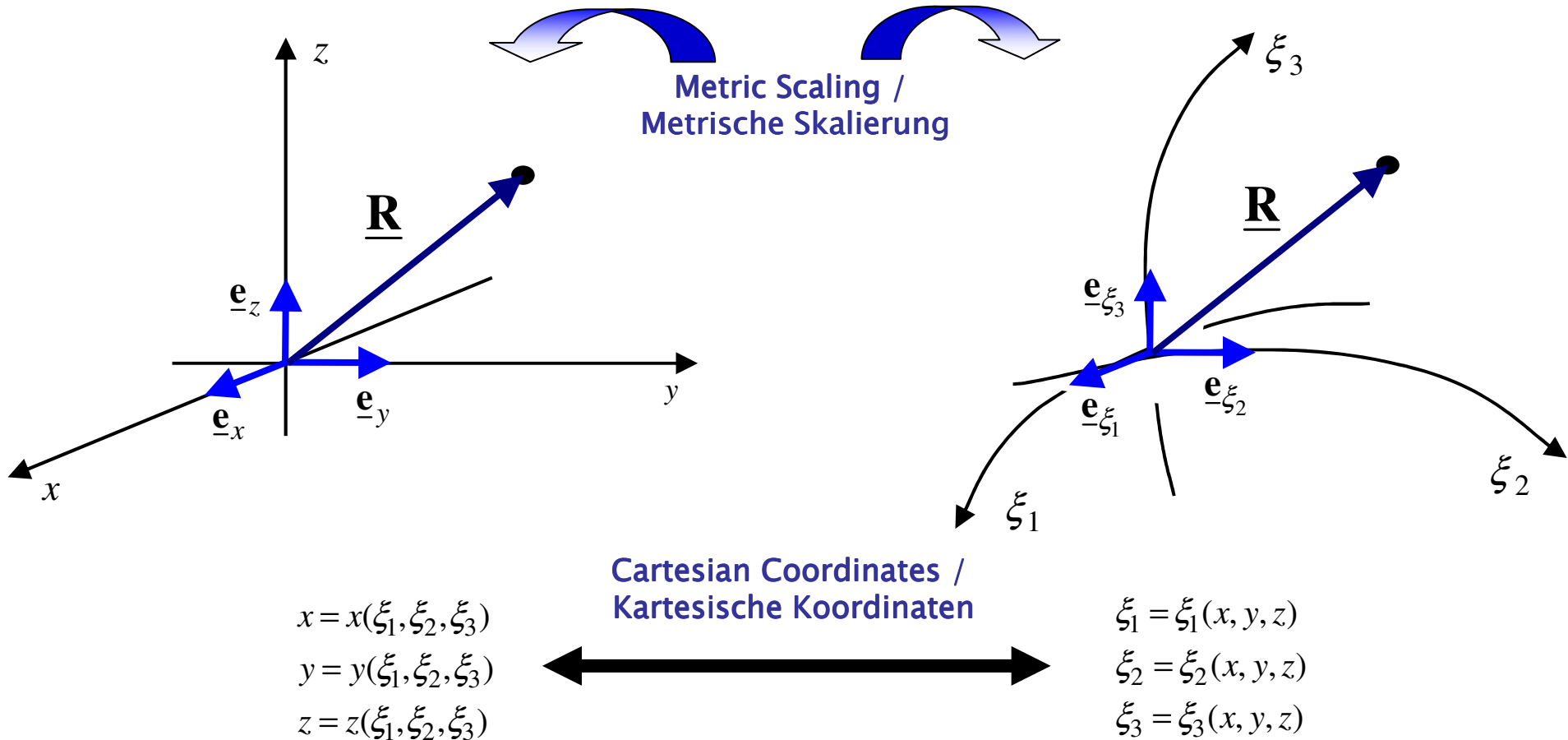
$$\underline{e}_x \perp \underline{e}_y \perp \underline{e}_z ; \underline{e}_{x_1} \perp \underline{e}_{x_2} \perp \underline{e}_{x_3}$$

Orthogonal Curvilinear Coordinates /  
Orthogonale Krummlinige Koordinaten

$$\xi_1, \xi_2, \xi_3$$

$$\underline{e}_{\xi_1}, \underline{e}_{\xi_2}, \underline{e}_{\xi_3}$$

$$\underline{e}_{\xi_1} \perp \underline{e}_{\xi_2} \perp \underline{e}_{\xi_3}$$



$$x = x(\xi_1, \xi_2, \xi_3)$$

$$y = y(\xi_1, \xi_2, \xi_3)$$

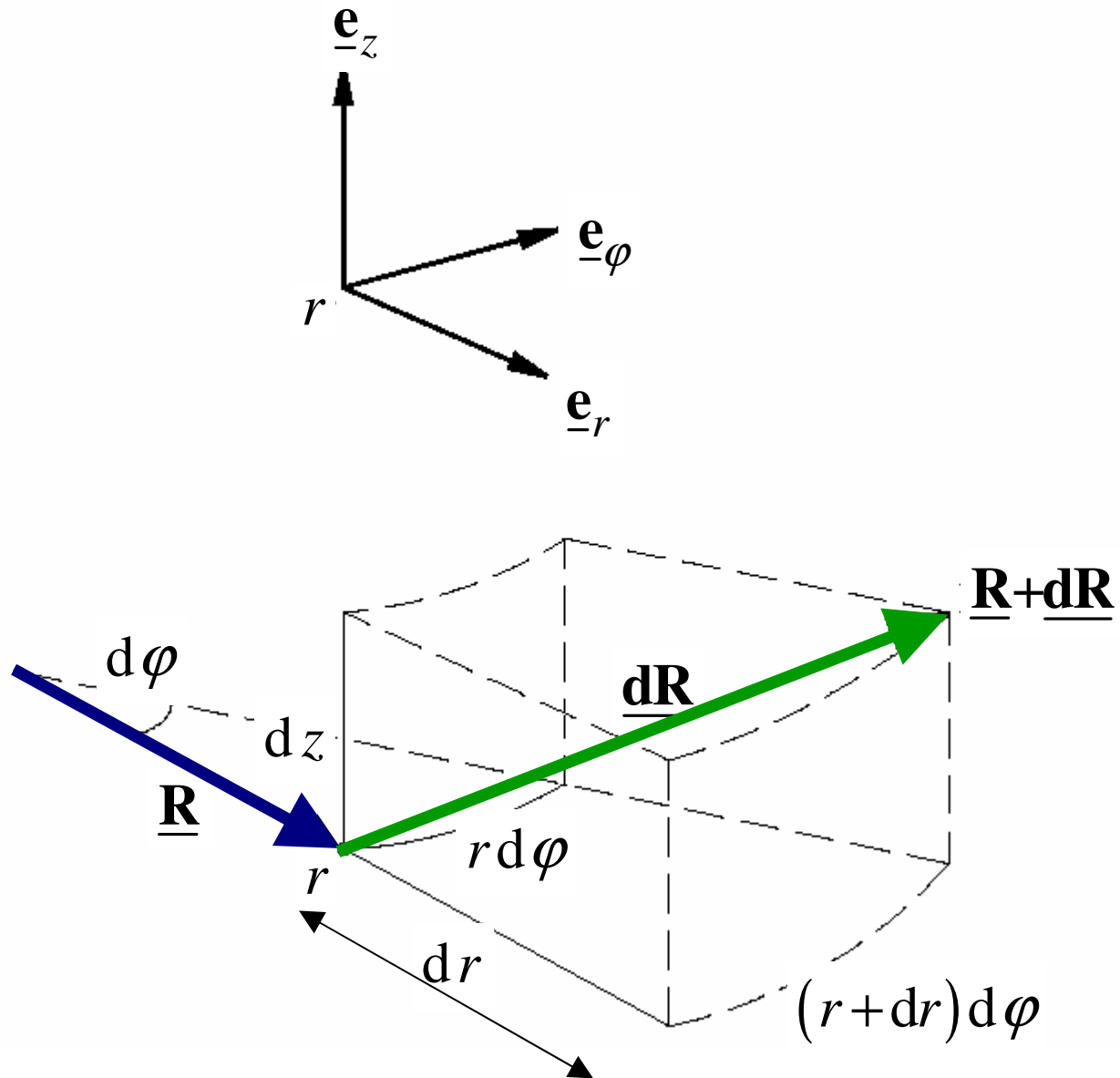
$$z = z(\xi_1, \xi_2, \xi_3)$$

$$\xi_1 = \xi_1(x, y, z)$$

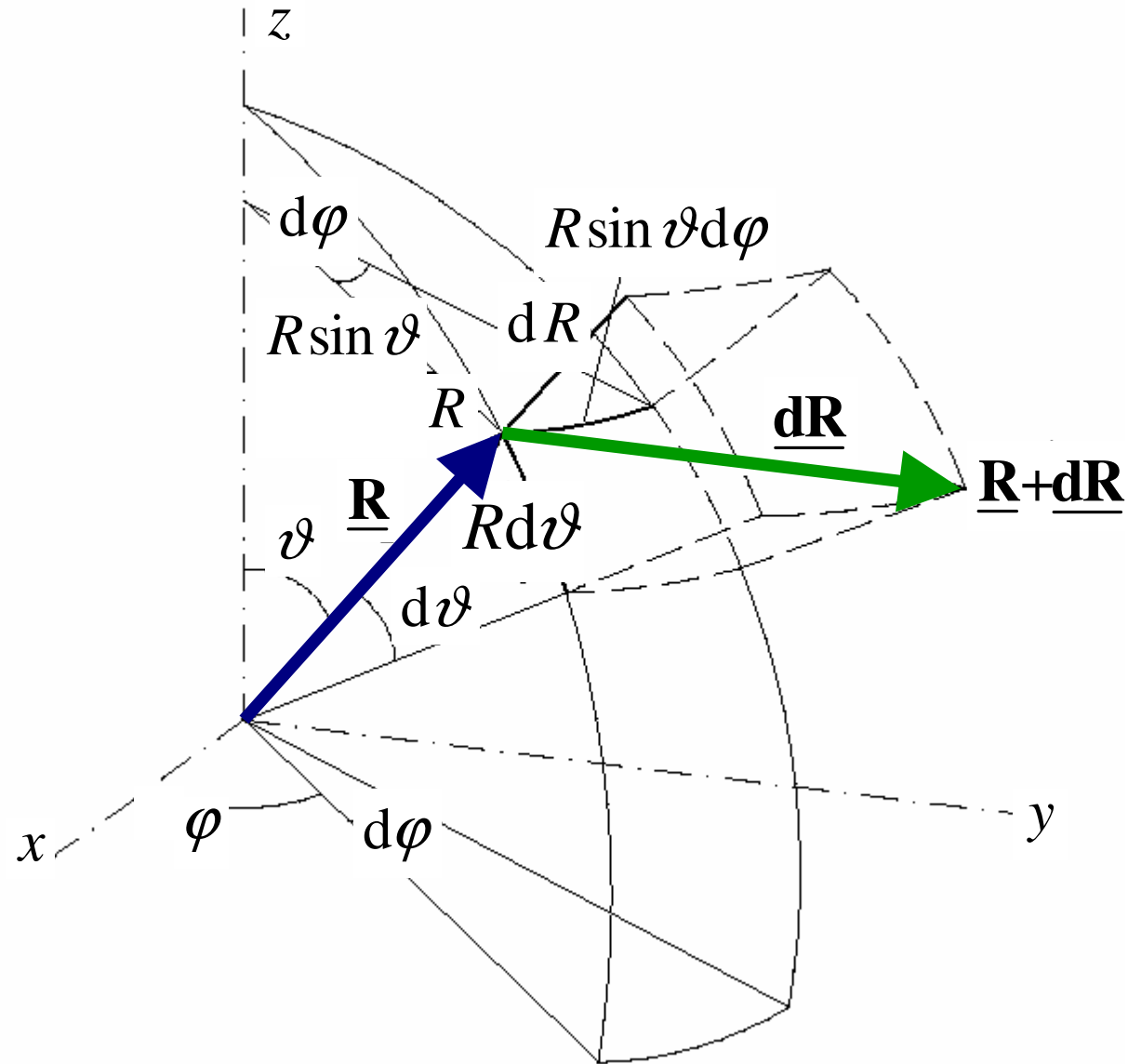
$$\xi_2 = \xi_2(x, y, z)$$

$$\xi_3 = \xi_3(x, y, z)$$

# Metric Coefficients – Cylindrical Coordinate System / Metrische Koeffizienten – Zylinderkoordinatensystem



# Metric Coefficients – Spherical Coordinate System / Metrische Koeffizienten – Kugelkoordinatensystem



# Metric Coefficients / Metrische Koeffizienten

## Cartesian Coordinates / Kartesische Koordinaten

$$x, y, z = x_1, x_2, x_3 = \xi_1, \xi_2, \xi_3$$

$$x = x(\xi_1, \xi_2, \xi_3)$$

$$y = y(\xi_1, \xi_2, \xi_3)$$

$$z = z(\xi_1, \xi_2, \xi_3)$$

$$\underline{\mathbf{R}} = x(\xi_1, \xi_2, \xi_3)\underline{\mathbf{e}}_x + y(\xi_1, \xi_2, \xi_3)\underline{\mathbf{e}}_y + z(\xi_1, \xi_2, \xi_3)\underline{\mathbf{e}}_z$$

$$\frac{\partial \underline{\mathbf{R}}}{\partial \xi_i} = \frac{\partial x(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \underline{\mathbf{e}}_x + \frac{\partial y(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \underline{\mathbf{e}}_y + \frac{\partial z(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \underline{\mathbf{e}}_z$$

$$i = 1, 2, 3$$

$$\frac{\partial \underline{\mathbf{R}}}{\partial \xi_i} = \underbrace{\left| \frac{\partial \underline{\mathbf{R}}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right|}_{\text{Magnitude / Betrag} = h_{\xi_i}} \underbrace{\frac{\frac{\partial \underline{\mathbf{R}}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i}}{\left| \frac{\partial \underline{\mathbf{R}}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right|}}_{\text{Direction / Richtung} = \underline{\mathbf{e}}_{\xi_i}}, \quad i = 1, 2, 3$$

## Orthogonal Curvilinear Coordinates / Orthogonale Krummlinige Koordinaten

$$\xi_1, \xi_2, \xi_3$$

$$\xi_1 = \xi_1(x, y, z)$$

$$\xi_2 = \xi_2(x, y, z)$$

$$\xi_3 = \xi_3(x, y, z)$$

## Metric Coefficients / Metrische Koeffizienten

$$h_{\xi_i} = \left| \frac{\partial \underline{\mathbf{R}}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right|$$

$$= \sqrt{\frac{\partial \underline{\mathbf{R}}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \cdot \frac{\partial \underline{\mathbf{R}}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i}}$$

$$= \sqrt{\left( \frac{\partial x(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right)^2 + \left( \frac{\partial y(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right)^2 + \left( \frac{\partial z(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right)^2}$$

$$i = 1, 2, 3$$

# Example: Metric Coefficients of the Cartesian Coordinate System / Beispiel: Metrische Koeffizienten des Kartesischen Koordinatensystems

$$\xi_1 = x; \xi_2 = y; \xi_3 = z$$

$$\begin{aligned} h_x &= \left| \frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial x} \right| = \sqrt{\frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial x} \cdot \frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial x}} \\ &= \sqrt{\left( \frac{\partial x(x, y, z)}{\partial x} \right)^2 + \left( \frac{\partial y(x, y, z)}{\partial x} \right)^2 + \left( \frac{\partial z(x, y, z)}{\partial x} \right)^2} \\ &= \sqrt{\underbrace{\left( \frac{\partial x}{\partial x} \right)^2}_{=1} + \underbrace{\left( \frac{\partial y}{\partial x} \right)^2}_{=0} + \underbrace{\left( \frac{\partial z}{\partial x} \right)^2}_{=0}} = 1 \end{aligned}$$

$$\begin{aligned} h_z &= \left| \frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial z} \right| = \sqrt{\frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial z} \cdot \frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial z}} \\ &= \sqrt{\left( \frac{\partial x(x, y, z)}{\partial z} \right)^2 + \left( \frac{\partial y(x, y, z)}{\partial z} \right)^2 + \left( \frac{\partial z(x, y, z)}{\partial z} \right)^2} \\ &= \sqrt{\underbrace{\left( \frac{\partial x}{\partial z} \right)^2}_{=0} + \underbrace{\left( \frac{\partial y}{\partial z} \right)^2}_{=0} + \underbrace{\left( \frac{\partial z}{\partial z} \right)^2}_{=1}} = 1 \end{aligned}$$

$$\begin{aligned} h_y &= \left| \frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial y} \right| = \sqrt{\frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial y} \cdot \frac{\partial \underline{\mathbf{R}}(x, y, z)}{\partial y}} \\ &= \sqrt{\left( \frac{\partial x(x, y, z)}{\partial y} \right)^2 + \left( \frac{\partial y(x, y, z)}{\partial y} \right)^2 + \left( \frac{\partial z(x, y, z)}{\partial y} \right)^2} \\ &= \sqrt{\underbrace{\left( \frac{\partial x}{\partial y} \right)^2}_{=0} + \underbrace{\left( \frac{\partial y}{\partial y} \right)^2}_{=1} + \underbrace{\left( \frac{\partial z}{\partial y} \right)^2}_{=0}} = 1 \end{aligned}$$

**Cartesian Coordinate System /  
Kartesisches Koordinatensystem**

$$h_x = 1$$

$$h_y = 1$$

$$h_z = 1$$

# Metric Coefficients / Metrische Koeffizienten

Cartesian Coordinate System /  
Kartesisches Koordinatensystem

$$h_x = 1$$

$$h_y = 1$$

$$h_z = 1$$

Cylindrical Coordinate System /  
Zylinderkoordinatensystem

$$h_r = 1$$

$$h_\varphi = r$$

$$h_z = 1$$

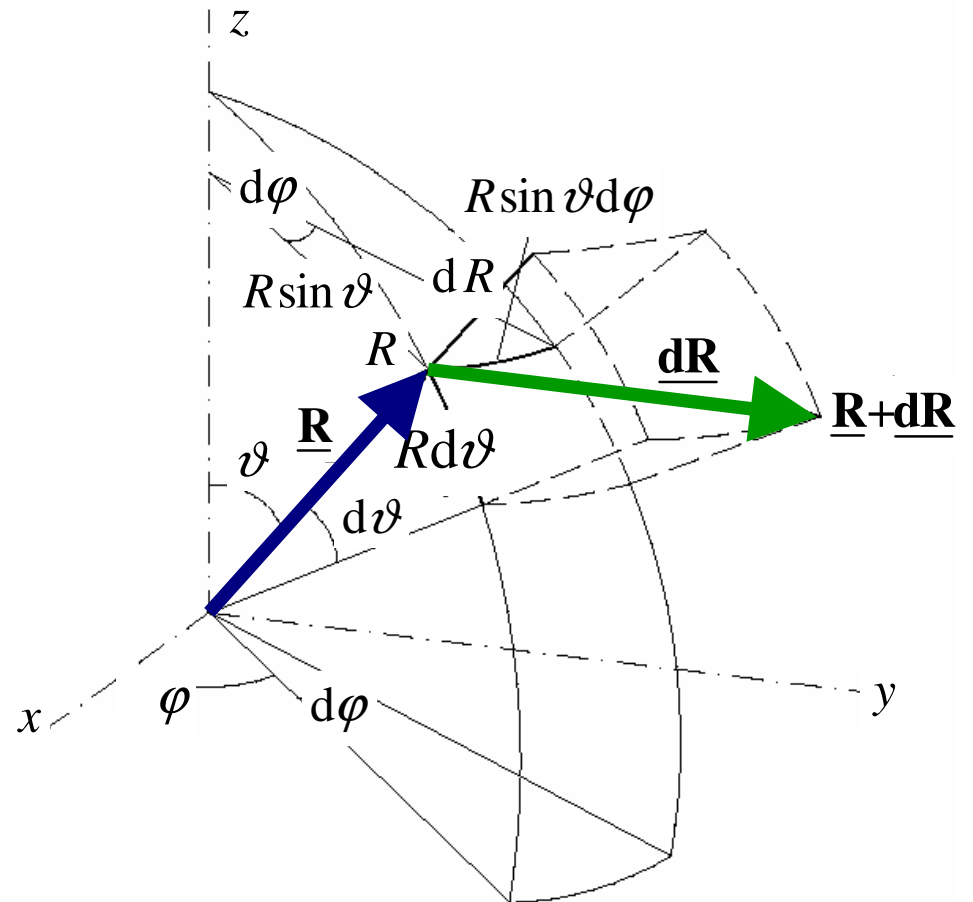
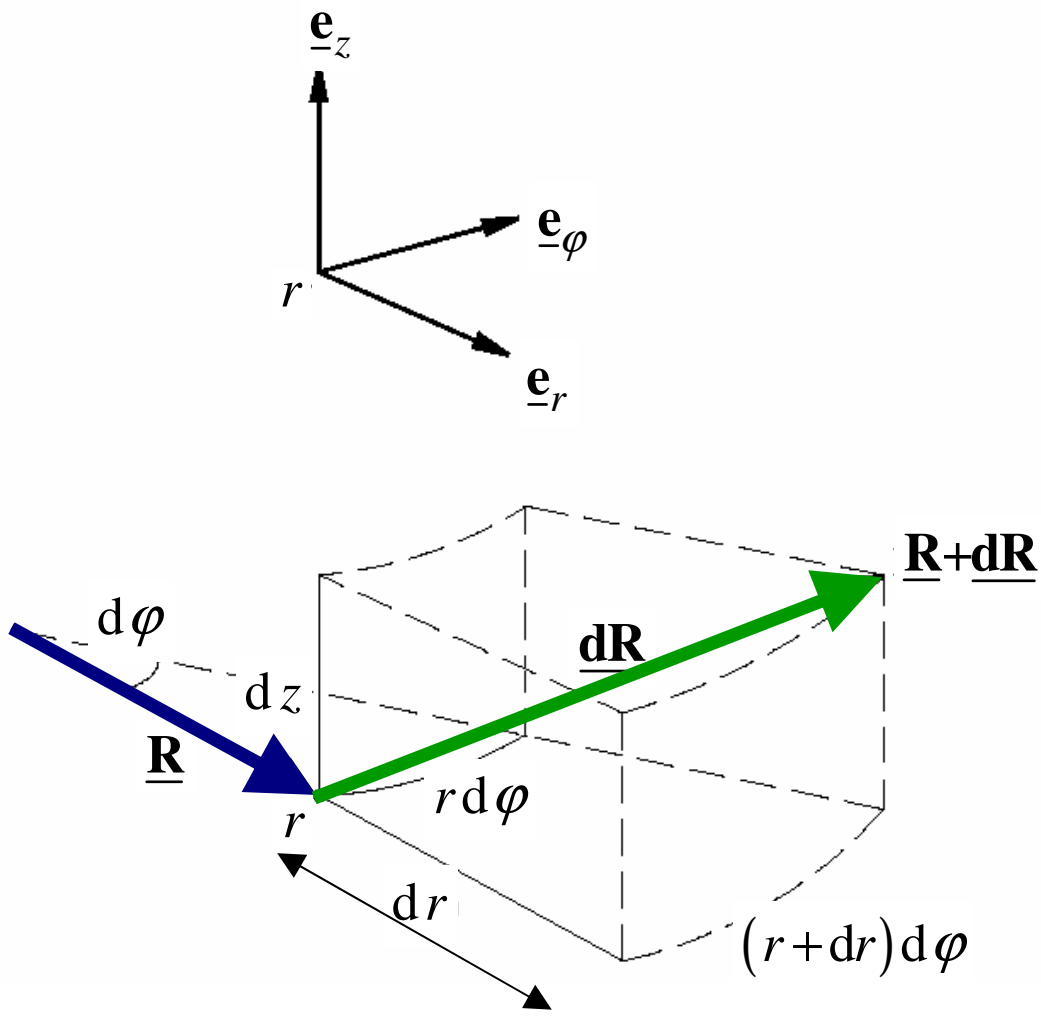
Spherical Coordinate System /  
Kugelkoordinatensystem

$$h_R = 1$$

$$h_\vartheta = R$$

$$h_\varphi = R \sin \vartheta$$

# Metric Coefficients – Cylindrical and Spherical Coordinate System / Metrische Koeffizienten – Zylinder- und Kugelkoordinatensystem



# Metric Coefficients and Vector Differential Line Elements / Metrische Koeffizienten und vektorielle differentielle Linienelemente

## Cartesian Coordinate System / Kartesisches Koordinatensystem

$$h_x = 1, \quad h_y = 1, \quad h_z = 1$$

$$\begin{aligned} \underline{dR}_x &= \underline{s} dR \\ &= \underline{e}_x h_x dx \\ &= \underline{e}_x dx \end{aligned}$$

$$\begin{aligned} \underline{dR}_y &= \underline{s} dR \\ &= \underline{e}_y h_y dy \\ &= \underline{e}_y dy \end{aligned}$$

$$\begin{aligned} \underline{dR}_z &= \underline{n} dR \\ &= \underline{e}_z h_z dz \\ &= \underline{e}_z dz \end{aligned}$$

## Cylindrical Coordinate System / Zylinderkoordinatensystem

$$h_r = 1, \quad h_\varphi = r, \quad h_z = 1$$

$$\begin{aligned} \underline{dR}_r &= \underline{s} dR \\ &= \underline{e}_r h_r dr \\ &= \underline{e}_r dr \end{aligned}$$

$$\begin{aligned} \underline{dR}_\varphi &= \underline{s} dR \\ &= \underline{e}_\varphi h_\varphi d\varphi \\ &= \underline{e}_\varphi r d\varphi \end{aligned}$$

$$\begin{aligned} \underline{dR}_z &= \underline{s} dR \\ &= \underline{e}_z h_z dz \\ &= \underline{e}_z dz \end{aligned}$$

## Spherical Coordinate System / Kugelkoordinatensystem

$$h_R = 1, \quad h_\vartheta = R, \quad h_\varphi = R \sin \vartheta$$

$$\begin{aligned} \underline{dR}_R &= \underline{s} dR \\ &= \underline{e}_R h_R dR \\ &= \underline{e}_R dR \end{aligned}$$

$$\begin{aligned} \underline{dR}_\vartheta &= \underline{s} dR \\ &= \underline{e}_\vartheta h_\vartheta d\vartheta \\ &= \underline{e}_\vartheta R d\vartheta \end{aligned}$$

$$\begin{aligned} \underline{dR}_\varphi &= \underline{s} dR \\ &= \underline{e}_\varphi h_\varphi d\varphi \\ &= \underline{e}_\varphi R \sin \vartheta d\varphi \end{aligned}$$



# Metric Coefficients and Differential Volume and Surface Elements / Metrische Koeffizienten und differentielle Volumen- und Flächenelemente

## Cartesian Coordinate System / Kartesisches Koordinatensystem

$$h_x = 1, \quad h_y = 1, \quad h_z = 1$$

$$\begin{aligned} dV &= h_x dx h_y dy h_z dz \\ &= h_x h_y h_z dx dy dz \\ &= dx dy dz \end{aligned}$$

$$\begin{aligned} \underline{dS}_{yz} &= \underline{n} dS \\ &= (\underline{e}_y \times \underline{e}_z) h_y h_z dy dz \\ &= \underline{e}_x dy dz \end{aligned}$$

$$\begin{aligned} \underline{dS}_{xz} &= \underline{n} dS \\ &= (\underline{e}_z \times \underline{e}_x) h_x h_z dx dz \\ &= \underline{e}_y dx dz \end{aligned}$$

$$\begin{aligned} \underline{dS}_{xy} &= \underline{n} dS \\ &= (\underline{e}_x \times \underline{e}_y) h_x h_y dx dy \\ &= \underline{e}_z dx dy \end{aligned}$$

## Cylindrical Coordinate System / Zylinderkoordinatensystem

$$h_r = 1, \quad h_\varphi = r, \quad h_z = 1$$

$$\begin{aligned} dV &= h_r dr h_\varphi d\varphi h_z dz \\ &= h_r h_\varphi h_z dr d\varphi dz \\ &= r dr d\varphi dz \end{aligned}$$

$$\begin{aligned} \underline{dS}_{\varphi z} &= \underline{n} dS \\ &= (\underline{e}_\varphi \times \underline{e}_z) h_\varphi h_z d\varphi dz \\ &= \underline{e}_r r dy dz \end{aligned}$$

$$\begin{aligned} \underline{dS}_{rz} &= \underline{n} dS \\ &= (\underline{e}_z \times \underline{e}_r) h_r h_z dr dz \\ &= \underline{e}_\varphi dr dz \end{aligned}$$

$$\begin{aligned} \underline{dS}_{r\varphi} &= \underline{n} dS \\ &= (\underline{e}_r \times \underline{e}_\varphi) h_r h_\varphi dr d\varphi \\ &= \underline{e}_z r dr d\varphi \end{aligned}$$

## Spherical Coordinate System / Kugelkoordinatensystem

$$h_R = 1, \quad h_\vartheta = R, \quad h_\varphi = R \sin \vartheta$$

$$\begin{aligned} dV &= h_R dR h_\vartheta d\vartheta h_\varphi d\varphi \\ &= h_R h_\vartheta h_\varphi dR d\vartheta d\varphi \\ &= R^2 \sin \vartheta dR d\vartheta d\varphi \end{aligned}$$

$$\begin{aligned} \underline{dS}_{\vartheta\varphi} &= \underline{n} dS \\ &= (\underline{e}_\vartheta \times \underline{e}_\varphi) h_\vartheta h_\varphi d\vartheta d\varphi \\ &= \underline{e}_R R^2 \sin \vartheta d\vartheta d\varphi \end{aligned}$$

$$\begin{aligned} \underline{dS}_{r\varphi} &= \underline{n} dS \\ &= (\underline{e}_\varphi \times \underline{e}_R) h_R h_\varphi dR d\varphi \\ &= \underline{e}_\vartheta R \sin \vartheta dR d\varphi \end{aligned}$$

$$\begin{aligned} \underline{dS}_{R\vartheta} &= \underline{n} dS \\ &= (\underline{e}_R \times \underline{e}_\vartheta) h_R h_\vartheta dR d\vartheta \\ &= \underline{e}_\varphi R dR d\vartheta \end{aligned}$$

# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

Consider the Electrostatic (ES) Case /  
 Betrachte den elektrostatischen Fall

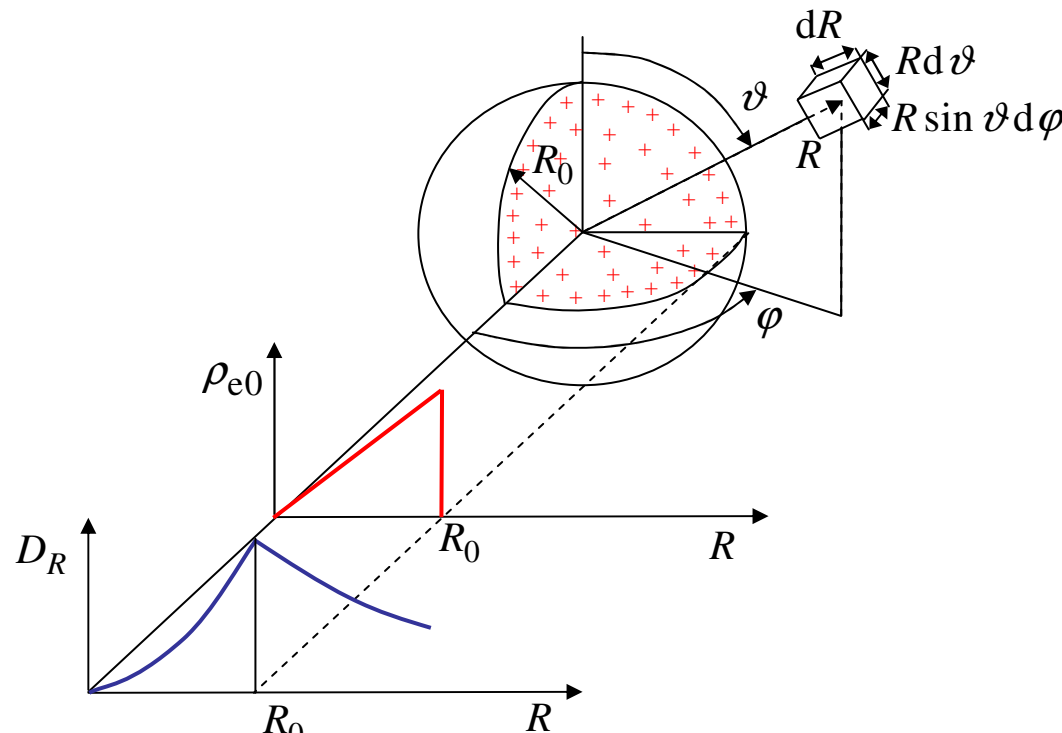
$$\oiint_{S=\partial V} \underbrace{\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}}_{=D_n(\underline{\mathbf{R}})} dS = \iiint_V \rho_e(\underline{\mathbf{R}}) dV$$

$$= D_R(\underline{\mathbf{R}})$$

Electric Charge Density /  
 Elektrische Raumladungsdichte

$$\rho_e(\underline{\mathbf{R}}) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

Radial Symmetry /  
 Radialsymmetrisch



# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

$$\oiint_{S=\partial V} \underbrace{\underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{n}}}_{=D_n(R)} dS = \iiint_V \rho_e(\underline{\mathbf{R}}) dV = Q_e$$

$$\rho_e(R) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R \leq R_0 \\ 0 & R > R_0 \end{cases}$$

2 Cases / 2 Fälle

$$0 \leq R < R_0$$

$$R > R_0$$

$$\begin{aligned} \oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} h_\varphi h_\vartheta d\varphi d\vartheta \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin\vartheta d\varphi d\vartheta \end{aligned}$$

$$\begin{aligned} \oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} h_\varphi h_\vartheta d\varphi d\vartheta \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin\vartheta d\varphi d\vartheta \end{aligned}$$

!

$$\iiint_V \rho_e(R) dV = \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^R \rho_e(R) R^2 \sin\vartheta dR d\varphi d\vartheta$$

!

$$\iiint_V \rho_e(R) dV = \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^{R_0} \rho_e(R) R^2 \sin\vartheta dR d\varphi d\vartheta$$

# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

## 2 Cases / 2 Fälle

$$R < R_0$$

$$\begin{aligned}\oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin \vartheta d\varphi d\vartheta \\ &= D_R(R) R^2 \underbrace{\int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin \vartheta d\varphi d\vartheta}_{=4\pi} \\ &= D_R(R) 4\pi R^2\end{aligned}$$

$$R > R_0$$

$$\begin{aligned}\oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin \vartheta d\varphi d\vartheta \\ &= D_R(R) R^2 \underbrace{\int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin \vartheta d\varphi d\vartheta}_{=4\pi} \\ &= D_R(R) 4\pi R^2\end{aligned}$$

# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

## 2 Cases / 2 Fälle

$$R < R_0$$

$$\begin{aligned} \iiint_V \rho_e(R) dV &= \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^R \rho_e(R) R^2 \sin \vartheta dR d\varphi d\vartheta \\ &= \rho_{e0} \int_{R=0}^R \frac{R}{R_0} R^2 \underbrace{\left[ \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin \vartheta d\varphi d\vartheta \right]}_{=4\pi} dR \\ &= \frac{4\pi\rho_{e0}}{R_0} \int_{R=0}^R R^3 dR \\ &= \frac{4\pi\rho_{e0}}{R_0} \frac{R^4}{4} \Big|_{R=0}^R \\ &= \frac{4\pi\rho_{e0}}{R_0} \frac{R^4}{4} \\ &= \pi\rho_{e0} \frac{R^4}{R_0} \end{aligned}$$

$$R > R_0$$

$$\begin{aligned} \iiint_V \rho_e(R) dV &= \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^{R_0} \rho_e(R) R^2 \sin \vartheta dR d\varphi d\vartheta \\ &= \rho_{e0} \int_{R=0}^{R_0} \frac{R}{R_0} R^2 \underbrace{\left[ \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin \vartheta d\varphi d\vartheta \right]}_{=4\pi} dR \\ &= \frac{4\pi\rho_{e0}}{R_0} \int_{R=0}^{R_0} R^3 dR \\ &= \frac{4\pi\rho_{e0}}{R_0} \frac{R^4}{4} \Big|_{R=0}^{R_0} \\ &= \frac{4\pi\rho_{e0}}{R_0} \frac{R_0^4}{4} \\ &= \pi\rho_{e0} R_0^3 \end{aligned}$$

# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

2 Cases / 2 Fälle

$$R < R_0$$

$$\underbrace{\oiint_{S=\partial V} D_R(R) dS}_{=D_R(R)4\pi R^2} = \underbrace{\iiint_V \rho_e(R) dV}_{=\pi\rho_{e0} \frac{R^4}{R_0}}$$

$$D_R(R)4\pi R^2 = \pi\rho_{e0} \frac{R^4}{R_0}$$

$$D_R(R) = \frac{\pi\rho_{e0} \frac{R^4}{R_0}}{4\pi R^2}$$

$$= \frac{\rho_{e0}}{4} \frac{R^2}{R_0}$$

$$R > R_0$$

$$\underbrace{\oiint_{S=\partial V} D_R(R) dS}_{=D_R(R)4\pi R^2} = \underbrace{\iiint_V \rho_e(R) dV}_{=\pi\rho_{e0} R_0^3}$$

$$D_R(R)4\pi R^2 = \pi\rho_{e0} R_0^3$$

$$D_R(R) = \frac{\pi\rho_{e0} R_0^3}{4\pi R^2}$$

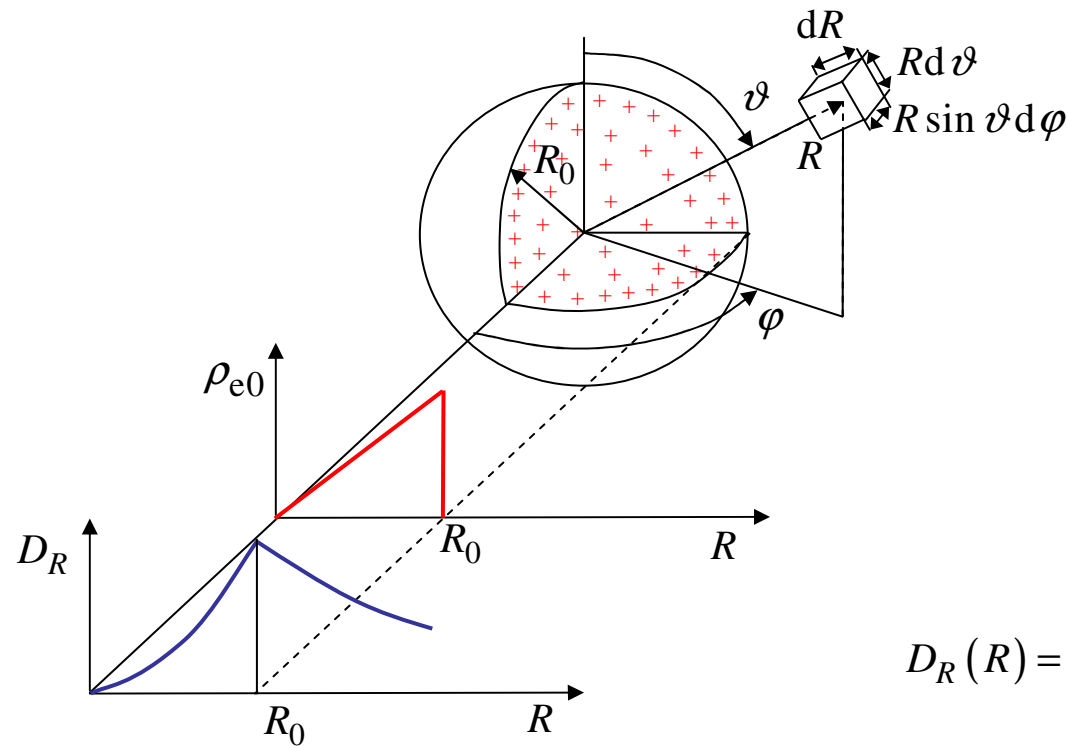
$$= \frac{\rho_{e0}}{4} \frac{R_0^3}{R^2}$$

# Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

Electric Charge Density /  
 Elektrische Raumladungsdichte

$$\rho_e(\mathbf{R}) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

Radial Symmetry /  
 Radialsymmetrisch



$$D_R(R) = \frac{\rho_{e0}}{4} \begin{cases} \frac{R^2}{R_0} & R < R_0 \\ \frac{R_0^3}{R^2} & R > R_0 \end{cases}$$

End of Lecture 4 /  
Ende der 4. Vorlesung