

Elektromagnetische Feldtheorie I (EFT I) / Electromagnetic Field Theory I (EFT I)

4th Lecture / 4. Vorlesung

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1

Faraday's Induction Law in Integral Form / Faradaysches Induktionsgesetz in Integralform (1)

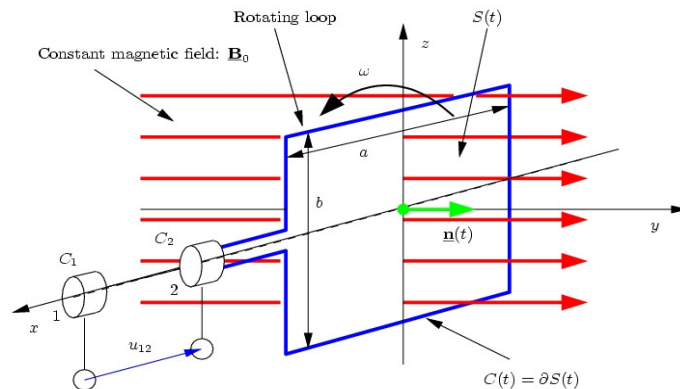
Faraday's Induction Law / Faradaysches Induktionsgesetz

$$\oint_{C(t)=\partial S(t)} \mathbf{E}(\mathbf{R}, t) \cdot d\mathbf{R} = -\frac{d}{dt} \iint_{S(t)} \mathbf{B}(\mathbf{R}, t) \cdot d\mathbf{S} - \iint_{S(t)} \mathbf{J}_m(\mathbf{R}, t) \cdot d\mathbf{S}$$

Time Dependent Surface /
Zeitabhängige Fläche

$$S(t) \quad C(t) = \partial S(t)$$

Time Dependent Contour /
Zeitabhängige Kontur



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2

Faraday's Induction Law in Integral Form / Faradaysches Induktionsgesetz in Integralform (2)

Faraday's Induction Law / Faradaysches Induktionsgesetz

$$\oint_{C(t)=\partial S(t)} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} = -\frac{d}{dt} \iint_{S(t)} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} - \iint_{S(t)} \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$\oint_{C(t)=\partial S(t)} \int d\underline{\mathbf{R}}$	[m]	Closed Contour Integral / Geschlossenes Kurvenintegral
$\underline{\mathbf{E}}(\underline{\mathbf{R}}, t)$	[V/m]	Electric Field Strength / Elektrische Feldstärke
$d\underline{\mathbf{R}}$	[m]	Vectorial Differential Line Element / Vektoriell-differentielles Linienelement
$\underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}}$	[V]	Scalar Product of E and dR = tangential projection of E onto dR / Skalarprodukt von E auf dR = Tangentialprojektion von E auf dR

Vectorial Differential Line Element /
Vektoriell-differentielles Linienelement

$$d\underline{\mathbf{R}} = \underline{\mathbf{s}} dR$$

Tangential Unit Vector /
Tangentialer Einheitsvektor
Scalar Differential Line Element / Skalares
differentielles Linienelement

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3

Different Products / Verschiedene Produkte

Scalar Product / Skalarprodukt $\underline{\mathbf{C}} = \underline{\mathbf{A}} \cdot \underline{\mathbf{B}}$

Vector Product / Vektorprodukt $\underline{\mathbf{C}} = \underline{\mathbf{A}} \times \underline{\mathbf{B}}$

Dyadic Product / Dyadisches Produkt $\underline{\underline{\mathbf{C}}} = \underline{\mathbf{A}} \underline{\mathbf{B}}$

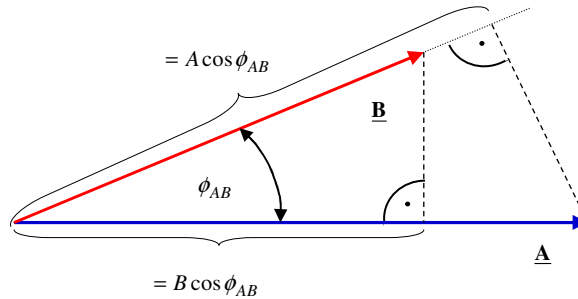
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4

Scalar Product (Dot or Inner Product) / Skalarprodukt (Punktprodukt oder inneres Produkt) (1)

$$\begin{aligned} \underline{\mathbf{A}} \cdot \underline{\mathbf{B}} &= |\underline{\mathbf{A}}| |\underline{\mathbf{B}}| \cos \underbrace{\angle(\underline{\mathbf{A}}, \underline{\mathbf{B}})}_{\phi_{AB}} \\ &= AB \cos \phi_{AB} \end{aligned}$$

**Enclosed Angle /
Eingeschlossener Winkel** ϕ_{AB}



$$\begin{aligned} \underline{\mathbf{A}} \cdot \underline{\mathbf{B}} &= \underline{\mathbf{B}} \cdot \underline{\mathbf{A}} \\ &= BA \cos \phi_{BA} \\ &= AB \cos \phi_{AB} \end{aligned}$$

$$\cos \phi_{AB} = \frac{\underline{\mathbf{A}} \cdot \underline{\mathbf{B}}}{|\underline{\mathbf{A}}| |\underline{\mathbf{B}}|}$$

$$\cos(\phi_{AB}) = \cos(-\phi_{AB})$$

$$\phi_{AB} = \arccos\left(\frac{\underline{\mathbf{A}} \cdot \underline{\mathbf{B}}}{|\underline{\mathbf{A}}| |\underline{\mathbf{B}}|}\right)$$

Scalar Product (Dot or Inner Product) / Skalarprodukt (Punktprodukt oder inneres Produkt) (2)

$$\begin{aligned} \underline{\mathbf{A}} \cdot \underline{\mathbf{B}} &= (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z) \\ &= A_x B_x \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_x}_{=1} + A_x B_y \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_y}_{=0} + A_x B_z \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_z}_{=0} \\ &\quad + A_y B_x \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_x}_{=0} + A_y B_y \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_y}_{=1} + A_y B_z \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_z}_{=0} \\ &\quad + A_z B_x \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_x}_{=0} + A_z B_y \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_y}_{=0} + A_z B_z \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_z}_{=1} \\ &= A_x B_x + A_y B_y + A_z B_z \end{aligned}$$

**Orthonormal Unit Vectors /
Orthonormale Einheitsvektoren**

$$\underline{\mathbf{e}}_x \perp \underline{\mathbf{e}}_y \perp \underline{\mathbf{e}}_z$$

$$\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_x = 1 \quad \underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_x = 0 \quad \underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_x = 0$$

$$\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_y = 0 \quad \underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_y = 1 \quad \underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_y = 0$$

$$\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_z = 0 \quad \underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_z = 0 \quad \underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_z = 1$$

**Cartesian Coordinates /
Kartesische Koordinaten**

$$x = x_1$$

$$y = x_2$$

$$z = x_3$$

$$\begin{aligned} \underline{\mathbf{A}} \cdot \underline{\mathbf{B}} &= (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z) \\ &= A_x B_x + A_y B_y + A_z B_z \\ &= (A_{x_1} \underline{\mathbf{e}}_{x_1} + A_{x_2} \underline{\mathbf{e}}_{x_2} + A_{x_3} \underline{\mathbf{e}}_{x_3}) \cdot (B_{x_1} \underline{\mathbf{e}}_{x_1} + B_{x_2} \underline{\mathbf{e}}_{x_2} + B_{x_3} \underline{\mathbf{e}}_{x_3}) \\ &= A_{x_1} B_{x_1} + A_{x_2} B_{x_2} + A_{x_3} B_{x_3} \\ &= \sum_{i=1}^3 A_{x_i} B_{x_i} \end{aligned}$$

Scalar Product (Dot or Inner Product) / Skalarprodukt (Punktprodukt oder inneres Produkt) (3)

$$\underline{\mathbf{A}} \cdot \underline{\mathbf{B}} = (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z)$$

$$= \sum_{i=1}^3 A_{x_i} \underline{\mathbf{e}}_{x_i} \cdot \sum_{j=1}^3 B_{x_j} \underline{\mathbf{e}}_{x_j}$$

$$= \sum_{i=1}^3 \sum_{j=1}^3 A_{x_i} \underline{\mathbf{e}}_{x_i} \cdot B_{x_j} \underline{\mathbf{e}}_{x_j}$$

$$= \sum_{i=1}^3 \sum_{j=1}^3 A_{x_i} B_{x_j} \underbrace{\underline{\mathbf{e}}_{x_i} \cdot \underline{\mathbf{e}}_{x_j}}_{=\delta_{ij}}$$

$$= A_{x_i} B_{x_j} \underbrace{\underline{\mathbf{e}}_{x_i} \cdot \underline{\mathbf{e}}_{x_j}}_{=\delta_{ij}}$$

$$= A_{x_i} \underbrace{B_{x_j} \delta_{ij}}_{=B_{x_i}} \quad \left(\text{or/oder} \quad \underbrace{A_{x_i} \delta_{ij}}_{=A_{x_j}} B_{x_j} \right)$$

$$= A_{x_i} B_{x_i}$$

**Kronecker Delta /
Kronecker-Delta**

$$\delta_{ij} = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

**with Einstein's Summation Convention /
mit Einsteinscher Summationskonvention**

Einstein's Summation Convention: If a index appears two times at one side of an equation (and not at the other side), the index is automatically summed over 1 to 3. /
Einsteinsche Summenkonvention: Wenn ein Index auf einer Seite einer Gleichung zweimal vorkommt (und auf der anderen nicht), wird darüber von 1 bis 3 summiert.

Magnitude of a Vector / Betrag eines Vektors

$$|\underline{\mathbf{A}}| = \sqrt{\underline{\mathbf{A}} \cdot \underline{\mathbf{A}}}$$

$$= \sqrt{(A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \cdot (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z)}$$

$$= \left(\begin{aligned} & A_x A_x \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_x}_{=1} + A_x A_y \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_y}_{=0} + A_x A_z \underbrace{\underline{\mathbf{e}}_x \cdot \underline{\mathbf{e}}_z}_{=0} \\ & + A_y A_x \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_x}_{=0} + A_y A_y \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_y}_{=1} + A_y A_z \underbrace{\underline{\mathbf{e}}_y \cdot \underline{\mathbf{e}}_z}_{=0} \\ & + A_z A_x \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_x}_{=0} + A_z A_y \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_y}_{=0} + A_z A_z \underbrace{\underline{\mathbf{e}}_z \cdot \underline{\mathbf{e}}_z}_{=1} \end{aligned} \right)^{\frac{1}{2}}$$

$$= \sqrt{A_x A_x + A_y A_y + A_z A_z}$$

$$= \sqrt{A_x^2 + A_y^2 + A_z^2}$$

$$= A$$

$$|\underline{\mathbf{A}}| = \sqrt{\underline{\mathbf{A}} \cdot \underline{\mathbf{A}}}$$

$$= \sqrt{\sum_{i=1}^3 A_{x_i} \underline{\mathbf{e}}_{x_i} \cdot \sum_{j=1}^3 B_{x_j} \underline{\mathbf{e}}_{x_j}}$$

$$= \sqrt{A_{x_i} \underline{\mathbf{e}}_{x_i} \cdot A_{x_j} \underline{\mathbf{e}}_{x_j}}$$

$$= \sqrt{A_{x_i} A_{x_j} \underbrace{\underline{\mathbf{e}}_{x_i} \cdot \underline{\mathbf{e}}_{x_j}}_{=\delta_{ij}}}$$

$$= \sqrt{A_{x_i}^2}$$

Example: Position Vector and Electric Field Strength Vector / Beispiel: Ortsvektor und elektrischer Feldstärkevektor

Cartesian Coordinate System / Kartesisches Koordinatensystem

**Position Vector /
Ortsvektor**

$$\begin{aligned}\underline{\mathbf{R}}(x, y, z) &= R_x(x, y, z)\underline{\mathbf{e}}_x + R_y(x, y, z)\underline{\mathbf{e}}_y + R_z(x, y, z)\underline{\mathbf{e}}_z \\ &= x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z\end{aligned}$$

**Magnitude of the Position Vector (Distance) /
Betrag des Ortsvektors (Abstand)**

$$\begin{aligned}|\underline{\mathbf{R}}(x, y, z)| &= \sqrt{\underline{\mathbf{R}}(x, y, z) \cdot \underline{\mathbf{R}}(x, y, z)} \\ &= \sqrt{(x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z) \cdot (x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z)} \\ &= \sqrt{x^2 + y^2 + z^2}\end{aligned}$$

**Position Unit Vector (Direction) /
Orts Einheitsvektor (Richtung)**

$$\begin{aligned}\hat{\underline{\mathbf{R}}}(x, y, z) &= \frac{\underline{\mathbf{R}}(x, y, z)}{|\underline{\mathbf{R}}(x, y, z)|} \\ &= \frac{x\underline{\mathbf{e}}_x + y\underline{\mathbf{e}}_y + z\underline{\mathbf{e}}_z}{\sqrt{x^2 + y^2 + z^2}}\end{aligned}$$

**Electric Field Strength Vector /
Elektrische Feldstärkevektor**

$$\begin{aligned}\underline{\mathbf{E}}(\underline{\mathbf{R}}, t) &= \underline{\mathbf{E}}(x, y, z, t) \\ &= E_x(x, y, z, t)\underline{\mathbf{e}}_x + E_y(x, y, z, t)\underline{\mathbf{e}}_y + E_z(x, y, z, t)\underline{\mathbf{e}}_z\end{aligned}$$

**Magnitude of the Electric Field Strength Vector
(Strength) / Betrag des elektrischen Feldstärkevektors
(Stärke)**

$$\begin{aligned}|\underline{\mathbf{E}}(x, y, z)| &= \sqrt{\underline{\mathbf{E}}(x, y, z) \cdot \underline{\mathbf{E}}(x, y, z)} \\ &= \sqrt{(E_x\underline{\mathbf{e}}_x + E_y\underline{\mathbf{e}}_y + E_z\underline{\mathbf{e}}_z) \cdot (E_x\underline{\mathbf{e}}_x + E_y\underline{\mathbf{e}}_y + E_z\underline{\mathbf{e}}_z)} \\ &= \sqrt{E_x^2 + E_y^2 + E_z^2}\end{aligned}$$

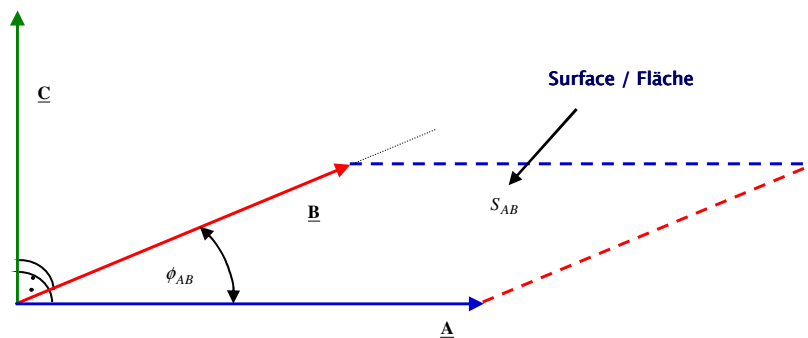
**Electric Field Strength Unit Vector (Direction) /
Elektrische Feldstärkeeinheitsvektor (Richtung)**

$$\begin{aligned}\hat{\underline{\mathbf{E}}}(x, y, z) &= \frac{\underline{\mathbf{E}}(x, y, z)}{|\underline{\mathbf{E}}(x, y, z)|} \\ &= \frac{E_x\underline{\mathbf{e}}_x + E_y\underline{\mathbf{e}}_y + E_z\underline{\mathbf{e}}_z}{\sqrt{E_x^2 + E_y^2 + E_z^2}}\end{aligned}$$

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9

Vector Product (Cross or Outer Product) / Vektorprodukt (Kreuzprodukt oder äußeres Produkt) (1)



$$\begin{aligned}\underline{\mathbf{C}} &= \underline{\mathbf{A}} \times \underline{\mathbf{B}} \\ C &= |\underline{\mathbf{A}}| |\underline{\mathbf{B}}| \sin \underbrace{\angle(\underline{\mathbf{A}}, \underline{\mathbf{B}})}_{\phi_{AB}} \\ &= AB \sin \phi_{AB} \\ &= S_{AB}\end{aligned}$$

$$\underline{\mathbf{C}} \perp \underline{\mathbf{A}} \quad \text{and /} \quad \underline{\mathbf{C}} \perp \underline{\mathbf{B}}$$

und

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10

Vector Product (Cross or Outer Product) / Vektorprodukt (Kreuzprodukt oder äußeres Produkt) (2)

Orthonormal Unit Vectors / Orthonormale Einheitsvektoren

$$\begin{aligned}
 \underline{\mathbf{A}} \times \underline{\mathbf{B}} &= (A_x \underline{\mathbf{e}}_x + A_y \underline{\mathbf{e}}_y + A_z \underline{\mathbf{e}}_z) \times (B_x \underline{\mathbf{e}}_x + B_y \underline{\mathbf{e}}_y + B_z \underline{\mathbf{e}}_z) \\
 &= A_x B_x \underbrace{\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_x}_{=0} + A_x B_y \underbrace{\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_y}_{=\underline{\mathbf{e}}_z} + A_x B_z \underbrace{\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_z}_{=-\underline{\mathbf{e}}_y} \\
 &\quad + A_y B_x \underbrace{\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_x}_{=-\underline{\mathbf{e}}_z} + A_y B_y \underbrace{\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_y}_{=0} + A_y B_z \underbrace{\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_z}_{=\underline{\mathbf{e}}_x} \\
 &\quad + A_z B_x \underbrace{\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_x}_{=\underline{\mathbf{e}}_y} + A_z B_y \underbrace{\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_y}_{=-\underline{\mathbf{e}}_x} + A_z B_z \underbrace{\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_z}_{=0} \\
 &= (A_y B_z \underline{\mathbf{e}}_x - A_z B_y) \underline{\mathbf{e}}_x + (A_z B_x - A_x B_z) \underline{\mathbf{e}}_y + (A_x B_y - A_y B_x) \underline{\mathbf{e}}_z
 \end{aligned}$$

$$\underline{\mathbf{A}} \times \underline{\mathbf{B}} = -\underline{\mathbf{B}} \times \underline{\mathbf{A}} \quad \underline{\mathbf{A}} \times \underline{\mathbf{A}} = \underline{\mathbf{0}}$$

$$\underline{\mathbf{e}}_x \perp \underline{\mathbf{e}}_y \perp \underline{\mathbf{e}}_z$$

$$\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_x = \underline{\mathbf{0}}$$

$$\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_y = \underline{\mathbf{e}}_z$$

$$\underline{\mathbf{e}}_x \times \underline{\mathbf{e}}_z = -\underline{\mathbf{e}}_y$$

$$\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_x = -\underline{\mathbf{e}}_z$$

$$\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_y = \underline{\mathbf{0}}$$

$$\underline{\mathbf{e}}_y \times \underline{\mathbf{e}}_z = \underline{\mathbf{e}}_x$$

$$\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_x = \underline{\mathbf{e}}_y$$

$$\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_y = -\underline{\mathbf{e}}_x$$

$$\underline{\mathbf{e}}_z \times \underline{\mathbf{e}}_z = \underline{\mathbf{0}}$$

Vector Product (Cross or Outer Product) / Vektorprodukt (Kreuzprodukt oder äußeres Produkt) (3)

$$\begin{aligned}
 \underline{\mathbf{A}} \times \underline{\mathbf{B}} &= \begin{vmatrix} \underline{\mathbf{e}}_x & \underline{\mathbf{e}}_y & \underline{\mathbf{e}}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} \\
 &= \begin{vmatrix} \underline{\mathbf{e}}_x & \underline{\mathbf{e}}_y & \underline{\mathbf{e}}_z & \underline{\mathbf{e}}_x & \underline{\mathbf{e}}_y \\ A_x & A_y & A_z & A_x & A_y \\ B_x & B_y & B_z & B_x & B_y \end{vmatrix} \\
 &= (A_y B_z - A_z B_y) \underline{\mathbf{e}}_x \\
 &\quad + (A_z B_x - A_x B_z) \underline{\mathbf{e}}_y \\
 &\quad + (A_x B_y - A_y B_x) \underline{\mathbf{e}}_z
 \end{aligned}$$

Add the first two Columns /
Addiere die beiden ersten Spalten

**Sarrus Law /
Regel von Sarrus**
[Pierre Frédéric Sarrus, 1831]
http://de.wikipedia.org/wiki/Regel_von_Sarrus

Dyadic Product / Dyadisches Produkt

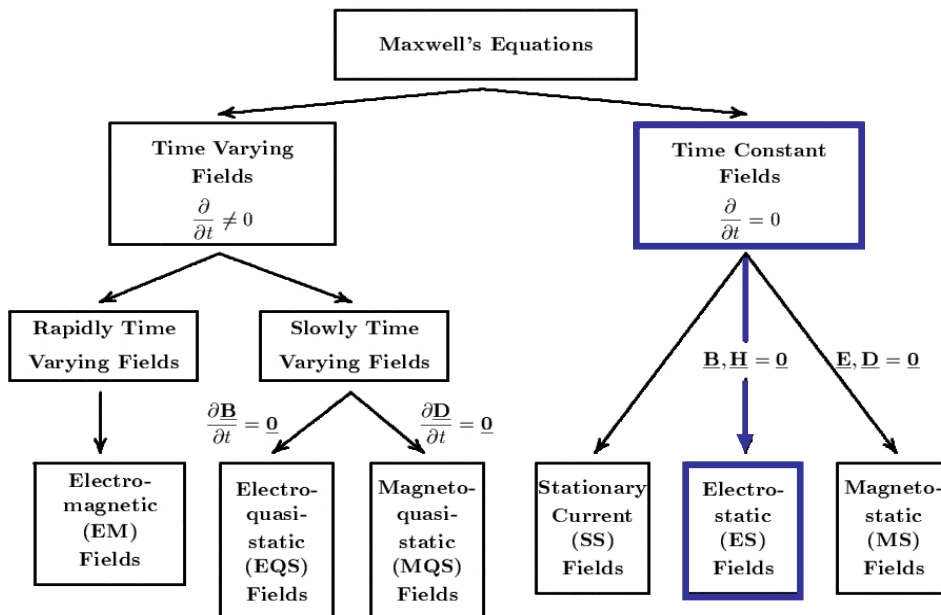
$$\begin{aligned}
 \underline{\underline{\mathbf{A} \mathbf{B}}} &= \sum_{i=1}^3 A_{x_i} \mathbf{e}_{x_i} \sum_{j=1}^3 B_{x_j} \mathbf{e}_{x_j} \\
 &= \sum_{i=1}^3 \sum_{j=1}^3 A_{x_i} \mathbf{e}_{x_i} B_{x_j} \mathbf{e}_{x_j} \\
 &= A_{x_i} \mathbf{e}_{x_i} B_{x_j} \mathbf{e}_{x_j} \\
 &= \underbrace{A_{x_i} B_{x_j}}_{=D_{x_i x_j}} \mathbf{e}_{x_i} \mathbf{e}_{x_j} \\
 &= D_{x_i x_j} \mathbf{e}_{x_i} \mathbf{e}_{x_j} \\
 &= \underline{\underline{\mathbf{D}}}
 \end{aligned}$$

$$\underline{\underline{\mathbf{B} \mathbf{A}}} \neq \underline{\underline{\mathbf{A} \mathbf{B}}}$$

$$\underline{\underline{\mathbf{D}}} = \underline{\underline{\epsilon}} \cdot \underline{\underline{\mathbf{E}}}$$

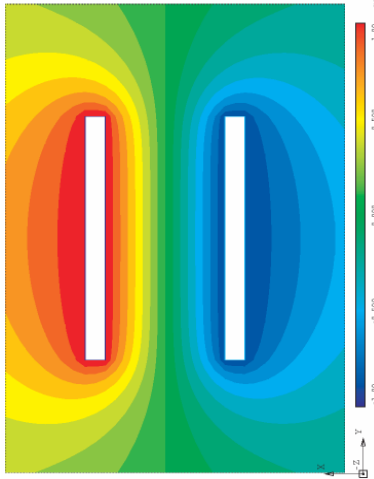
$$\underline{\underline{\mathbf{B}}} = \underline{\underline{\mu}} \cdot \underline{\underline{\mathbf{H}}}$$

Electrostatic (ES) Fields / Elektrostatische (ES) Felder

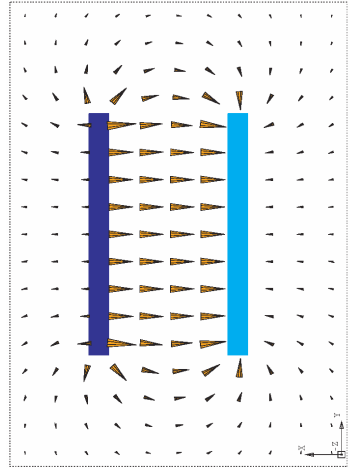


Electrostatic Field Problem – Example: Parallel Plate Capacitor / Elektrostatisches Feldproblem – Beispiel: Paralleler Plattenkondensator

**Scalar Field: Electrostatic Potential /
Skalarfeld: Elektrostatishes Potenzial**



**Vector Field: Electrostatic Field Strength /
Vektorfeld: Elektrostatishes Feldstärke**



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15

Electrostatic (ES) Fields – Governing Equations / Elektrostatishes (ES) Felder – Grundgleichungen

Electrostatic / $\frac{\partial}{\partial t} \equiv 0$ No Time Dependence and No Magnetic Field Quantities /
Elektrostatik Keine Zeitabhängigkeit und keine magnetischen Feldgrößen

$\underline{\mathbf{E}}(\underline{\mathbf{R}})$: Electric Field Strength / Elektrische Feldstärke
 $\underline{\mathbf{D}}(\underline{\mathbf{R}})$: Electric Flux Density / Elektrische Flussdichte
 $\rho_e(\underline{\mathbf{R}})$: Electric Charge Density / Elektrische Raumladungsdichte

Integral Form /
Integralform

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{R}} = 0$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{S}} = \iiint_V \rho_e(\underline{\mathbf{R}}) dV$$

Curl-Free $\underline{\mathbf{E}}$ Field /
Rotationsfreies $\underline{\mathbf{E}}$ Feld

Divergence of $\underline{\mathbf{D}}$ Represents Electric Charge Density /
Quellstärke von $\underline{\mathbf{D}}$ entspricht der elektrischen Raumladungsdichte

Differential Form /
Differentialform

$$\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}) = \underline{\mathbf{0}}$$

$$\nabla \cdot \underline{\mathbf{D}}(\underline{\mathbf{R}}) = \rho_e(\underline{\mathbf{R}})$$

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16

Electrostatic (ES) Fields – Governing Equations / Elektrostatische (ES) Felder – Grundgleichungen

Integral Form / Integralform

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{R}} = 0$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{S}} = \iiint_V \rho_e(\underline{\mathbf{R}}) dV = Q_e$$

$$\begin{aligned} \underline{\mathbf{E}}(\underline{\mathbf{R}}) & \text{ [V/m = Newton/Coulomb = N/C]} \\ \underline{\mathbf{D}}(\underline{\mathbf{R}}) & \text{ [As/m}^2\text{]} \\ \rho_e(\underline{\mathbf{R}}) & \text{ [As/m}^3\text{]} \end{aligned}$$

Vacuum / Vakuum

$$\underline{\mathbf{D}}(\underline{\mathbf{R}}) = \epsilon_0 \underline{\mathbf{E}}(\underline{\mathbf{R}})$$

Electric Field Constant / Elektrische Feldkonstante
(IEEE, VDE)
Permittivity of Free Space / Permittivität des Freiraumes

**Differential Form /
Differentialform**

$$\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}) = \underline{\mathbf{0}}$$

$$\nabla \cdot \underline{\mathbf{D}}(\underline{\mathbf{R}}) = \rho_e(\underline{\mathbf{R}})$$

**Side Remark: In some Cases /
Nebenbemerkung: In einigen Fällen**

$$\underline{\mathbf{D}}(\underline{\mathbf{R}}) = \epsilon_0 \epsilon_r \underline{\mathbf{E}}(\underline{\mathbf{R}})$$

Permittivity /
Permittivität

Material	ϵ_r
Air / Luft	1.006
Paper / Papier	2...4
Wet Earth / Nasse Erde	5...15
Gallium Arsenide / Gallium Arsenid	13
Seawater / Seewasser	70

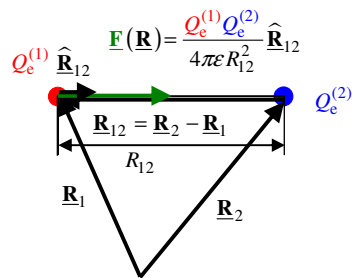
ES Fields – Electric Points Charge and Electric Field Strength – Coulomb's Law / ES Felder – Elektrische Punktladung und elektrische Feldstärke – Coulombsches Gesetz

Coulomb's Law / Coulombsches Gesetz

Charles Augustin de Coulomb (1736 - 1806)

$$\underline{\mathbf{F}}(\underline{\mathbf{R}}) = \frac{1}{4\pi\epsilon} \frac{Q_e^{(1)} Q_e^{(2)}}{R_{12}^2} \hat{\underline{\mathbf{R}}}_{12} \quad [\text{N}]$$

Force / Kraft	$\underline{\mathbf{F}}(\underline{\mathbf{R}})$	[N]
Electric Point Charge / Elektrische Punktladung	$Q_e^{(1)}$	[As]
Electric Point Charge / Elektrische PunktLadung	$Q_e^{(2)}$	[As]
Distance / Abstand	R	[m]
Distance Unit Vector / Abstandseinheitsvektor	$\hat{\underline{\mathbf{R}}}$	[1]
Permittivity of Free-Space / Permittivität des Freiraumes	ϵ	[As/Vm]



$$\hat{\underline{\mathbf{R}}} = \frac{\underline{\mathbf{R}}}{|\underline{\mathbf{R}}|} = \frac{\underline{\mathbf{R}}}{R} \quad [1] \quad R = |\underline{\mathbf{R}}| = \sqrt{\underline{\mathbf{R}} \cdot \underline{\mathbf{R}}} \quad [\text{m}]$$

$$\underline{\mathbf{R}} = x\mathbf{e}_x + y\mathbf{e}_y + z\mathbf{e}_z$$

$$R = \sqrt{\underline{\mathbf{R}} \cdot \underline{\mathbf{R}}} = \sqrt{x^2 + y^2 + z^2}$$

$$\hat{\underline{\mathbf{R}}} = \frac{x\mathbf{e}_x + y\mathbf{e}_y + z\mathbf{e}_z}{\sqrt{x^2 + y^2 + z^2}} = \mathbf{e}_R(\vartheta, \varphi)$$

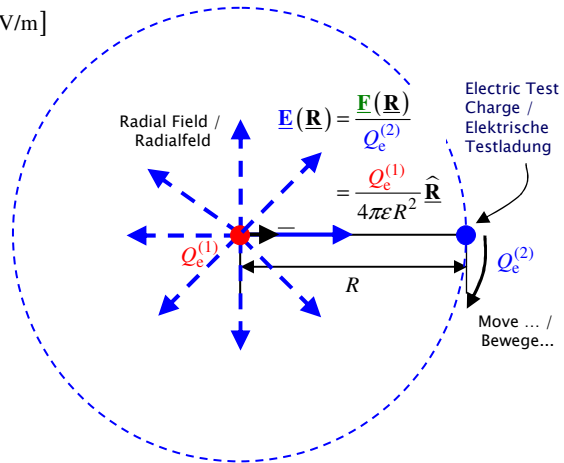
**ES Fields – Electric Charge and Electric Field Strength – Coulomb’s Law /
ES Felder – Elektrische Ladung und elektrische Feldstärke – Coulombsches Gesetz**

**Electric Field Strength: Force Per Unit Charge /
Elektrische Feldstärke: Kraft pro Einheitsladung**

$Q_e^{(2)}$ Electric Test Charge /
Elektrische Testladung

$$\underline{E}(\underline{R}) = \frac{\underline{F}(\underline{R})}{Q_e^{(2)}} = \frac{Q_e^{(1)}}{4\pi\epsilon R^2} \hat{\underline{R}} \quad [\text{N/C or V/m}]$$

Electric Field Strength / Elektrische Feldstärke	$\underline{E}(\underline{R})$	[V/m]
Force / Kraft	$\underline{F}(\underline{R})$	[N]
Electric Charge / Elektrische Ladung	$Q_e^{(1)}$	[As]
Electric Test Charge / Elektrische Testladung	$Q_e^{(2)}$	[As]
Distance / Abstand	R	[m]
Distance Unit Vector / Abstandseinheitsvektor	$\hat{\underline{R}}$	[1]
Permittivity of Free-Space / Permittivität des Freiraumes	ϵ	[As/Vm]



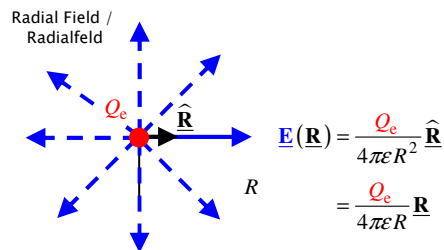
**ES Fields – Electric Charge and Electric Field Strength – Coulomb’s Law /
ES Felder – Elektrische Ladung und elektrische Feldstärke – Coulombsches Gesetz**

**Electric Field Strength: Force Per Unit Charge /
Elektrische Feldstärke: Kraft pro Einheitsladung**

$$\underline{E}(\underline{R}) = \frac{Q_e}{4\pi\epsilon R^2} \hat{\underline{R}} = \frac{Q_e}{4\pi\epsilon R} \underline{R} \quad [\text{V/m}]$$

$$\underline{R} = R \hat{\underline{R}}$$

Electric Field Strength / Elektrische Feldstärke	$\underline{E}(\underline{R})$	[V/m]
Electric Charge / Elektrische Ladung	Q_e	[As]
Distance / Abstand	R	[m]
Distance Unit Vector / Abstandseinheitsvektor	$\hat{\underline{R}}$	[1]
Permittivity of Free-Space / Permittivität des Freiraumes	ϵ	[As/Vm]



Electrostatic (ES) Fields – Governing Equations / Elektrostatische (ES) Felder – Grundgleichungen

Electrostatic / Elektrostatik $\frac{\partial}{\partial t} \equiv 0$ No Time Dependence and No Magnetic Field Quantities /
Keine Zeitabhängigkeit und keine magnetischen Feldgrößen

$\underline{E}(\underline{R})$: Electric Field Strength / Elektrische Feldstärke
 $\underline{D}(\underline{R})$: Electric Flux Density / Elektrische Flussdichte
 $\rho_e(\underline{R})$: Electric Charge Density / Elektrische Raumladungsdichte

Integral Form /
Integralform

Differential Form /
Differentialform

$$\oint_{C=\partial S} \underline{E}(\underline{R}) \cdot d\underline{R} = 0$$

$$\nabla \times \underline{E}(\underline{R}) = \underline{0}$$

$$\oiint_{S=\partial V} \underline{D}(\underline{R}) \cdot d\underline{S} = \iiint_V \rho_e(\underline{R}) dV$$

$$\nabla \cdot \underline{D}(\underline{R}) = \rho_e(\underline{R})$$

Curl-Free \underline{E} -Field /
Rotationsfreies \underline{E} -Feld

Divergence of \underline{D} Represents Electric Charge Density /
Quellstärke von \underline{D} entspricht der elektrischen Raumladungsdichte



Method of Gauss' Electric Law /
Methode des Gaußschen elektrischen Gesetzes

ES Fields – Method of Electric Gauss' Law / ES-Felder – Methode des elektrischen Gaußschen Gesetzes

Source Distribution / Quellverteilung

$$\rho_e(\underline{R}) = \begin{cases} \neq 0 & \underline{R} \in V_s \\ = 0 & \underline{R} \notin V_s \end{cases}$$

Source Volume /
Quellvolumen

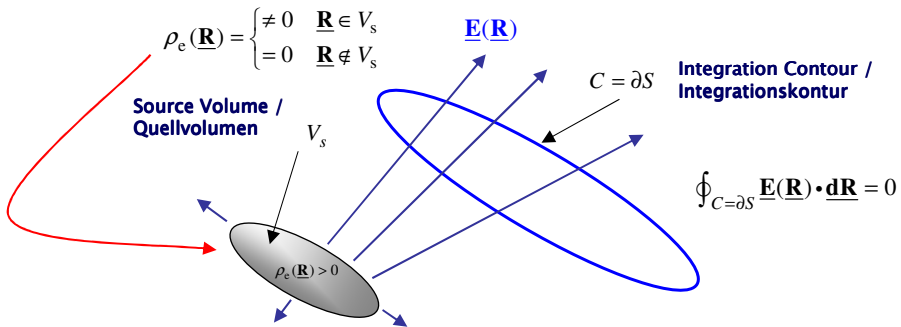
V_s

$\underline{E}(\underline{R})$

$C = \partial S$

Integration Contour /
Integrationskontur

$$\oint_{C=\partial S} \underline{E}(\underline{R}) \cdot d\underline{R} = 0$$



ES Fields - Method of Electric Gauss' Law / ES-Felder - Methode des elektrischen Gaußschen Gesetzes

Source Distribution / Quellverteilung

$$\rho_e(\mathbf{R}) = \begin{cases} \neq 0 & \mathbf{R} \in V_s \\ = 0 & \mathbf{R} \notin V_s \end{cases}$$

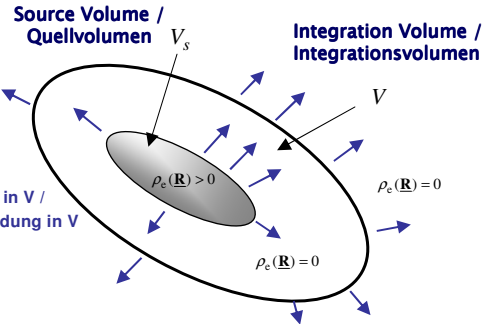
$$\psi_e = \oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot \mathbf{dS} = \iiint_V \rho_e(\mathbf{R}) dV$$



$$\mathbf{D}(\mathbf{R}) \cdot \mathbf{dS} = \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{D_n(\mathbf{R})} dS$$

$$\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot \mathbf{dS} = \oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{D_n(\mathbf{R})} dS$$

Summation of all $D_n = \mathbf{n} \cdot \mathbf{D}$ Contributions /
Summation aller $D_n = \mathbf{n} \cdot \mathbf{D}$ -Beiträge



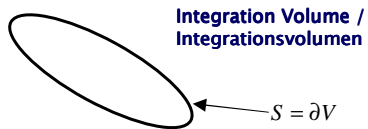
$$= \underbrace{\iiint_V \rho_e(\mathbf{R}) dV}_{Q_e}$$

Total electric charge inside the
volume V with the closed surface $S=\partial V$ /
Gesamte elektrische Ladung im Volumen
V mit der geschlossenen Oberfläche $S=\partial V$

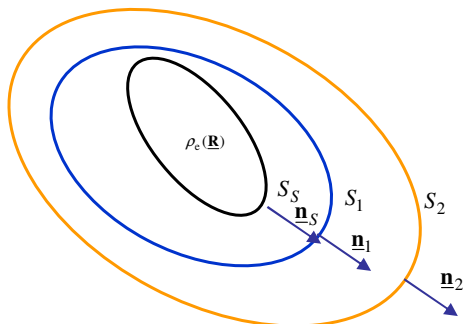
$$\text{Flux of } \mathbf{D} \text{ through } S = Q_e \text{ in } V / \\ \text{Fluss von } \mathbf{D} \text{ durch } S = Q_e \text{ in } V$$

ES Fields - Method of Electric Gauss' Law / ES-Felder - Methode des elektrischen Gaußschen Gesetzes

$$\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot \mathbf{dS} = \iiint_V \rho_e(\mathbf{R}) dV = Q_e$$

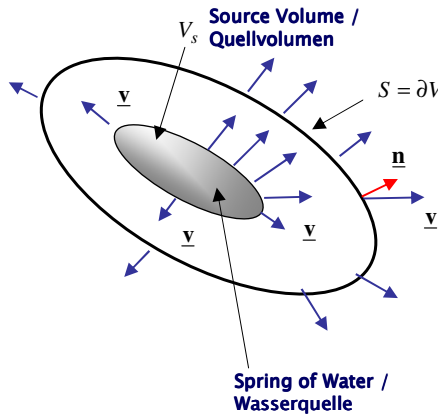


$$\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot \mathbf{dS} \begin{cases} = 0 & \text{source-free / quellenfrei} \\ > 0 & \text{Source / Quelle} \\ < 0 & \text{Sink / Senke} \end{cases}$$



$$\begin{aligned} \oiint_{S_s=\partial V_s} \mathbf{D}(\mathbf{R}) \cdot \mathbf{n}_S dS \\ = \oiint_{S_1=\partial V_1} \mathbf{D}(\mathbf{R}) \cdot \mathbf{n}_1 dS \\ = \oiint_{S_2=\partial V_2} \mathbf{D}(\mathbf{R}) \cdot \mathbf{n}_2 dS \\ = Q_e \end{aligned}$$

**Example: Fluid Mechanics – Spring of Water /
Beispiel: Strömungsmechanik – Wasserquelle**



**Integration Surface (Closed Surface) /
Integrationsfläche (geschlossene Oberfläche)**

**Total Flux through the Closed Surface /
Gesamtfluss durch die geschlossene Oberfläche**

$$\begin{aligned} \oiint_{S=\partial V} \mathbf{v}(\mathbf{R}) \cdot d\mathbf{S} &= \oiint_{S=\partial V} \underbrace{\mathbf{v}(\mathbf{R}) \cdot \mathbf{n}}_{=v_n(\mathbf{R})} dS \\ &= \oiint_{S=\partial V} v_n(\mathbf{R}) dS \\ &= \psi_v \end{aligned}$$

**Example: Electric Field Due to Spherically Symmetric Charge Distribution /
Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte**

**Consider the Electrostatic (ES) Case /
Betrachte den elektrostatischen (ES) Fall**

$$\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot d\mathbf{S} = \oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS = \underbrace{\iiint_V \rho_c(\mathbf{R}) dV}_{=Q_c}$$

**Prescribed: Electric Charge Density /
Vorgegeben: Elektrische Raumladungsdichte**

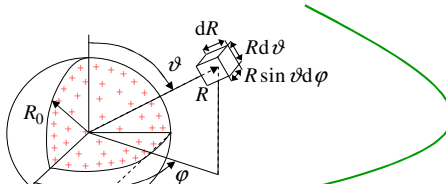
$$\rho_c(\mathbf{R}) = \rho_c(R) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

**Charged Sphere with Radius R_0 /
Geladene Kugel mit dem Radius R_0**

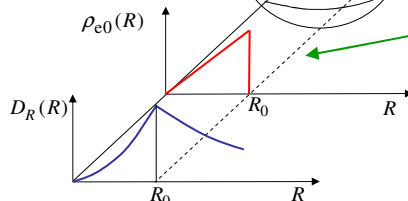
**Radial Symmetry /
Radialsymmetrie**

!

$$\begin{aligned} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} &= \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{e}_R}_{=D_R(\mathbf{R})} \\ D_n(\mathbf{R}) &= D_R(\mathbf{R}) \end{aligned}$$



**Solution for $\mathbf{D}(\mathbf{R})$ /
Lösung für $\mathbf{D}(\mathbf{R})$**



Vector Differential Surface Element / Vektorielles differentielles Flächenelement (1)

Definition: $\underline{dS} = \underline{n} dS$

Surface / Fläche

Position Vector / Ortsvektor $\underline{R}(\sigma_1, \sigma_2)$

Tangential Vectors / Tangentialvektoren

Surface Parameters / Flächenparameter σ_1, σ_2

Position Vector / Ortsvektor $\underline{R}(\sigma_1, \sigma_2)$

Position Vectors / Ortsvektoren $\underline{R}(\sigma_1 + d\sigma_1, \sigma_2)$
 $\underline{R}(\sigma_1, \sigma_2 + d\sigma_2)$

Vector Differential Line Elements / Vektorielle differentielle Linienelemente $\underline{dR}_{\sigma_1}$
 $\underline{dR}_{\sigma_2}$

Tangential Vectors / Tangentialvektoren $\underline{\sigma}_1(\sigma_1, \sigma_2) = \frac{\partial}{\partial \sigma_1} \underline{R}(\sigma_1, \sigma_2)$
 $\underline{\sigma}_2(\sigma_1, \sigma_2) = \frac{\partial}{\partial \sigma_2} \underline{R}(\sigma_1, \sigma_2)$

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27

Vector Differential Surface Element / Vektorielles differentielles Flächenelement (2)

Vector Differential Line Elements / Vektorielles differentielles Linienelement

$$\underline{dR}_{\sigma_1} = \underline{\sigma}_1(\sigma_1, \sigma_2) d\sigma_1$$

$$\underline{dR}_{\sigma_2} = \underline{\sigma}_2(\sigma_1, \sigma_2) d\sigma_2$$

Scalar Differential Surface Elements / Skalares differentielles Flächenelement

$$dS = \left| \underline{dR}_{\sigma_1} \times \underline{dR}_{\sigma_2} \right|$$

$$= \left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right| d\sigma_1 d\sigma_2$$

Normal Unit-Vector / Normaleneinheitsvektor

$$\underline{n} = \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{\left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right|}$$

Vector Differential Surface Element / Vektorielles differentielles Flächenelement

$$\underline{dS} = \underline{n} dS$$

$$= \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{\left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right|} \left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right| d\sigma_1 d\sigma_2$$

$$= \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) d\sigma_1 d\sigma_2$$

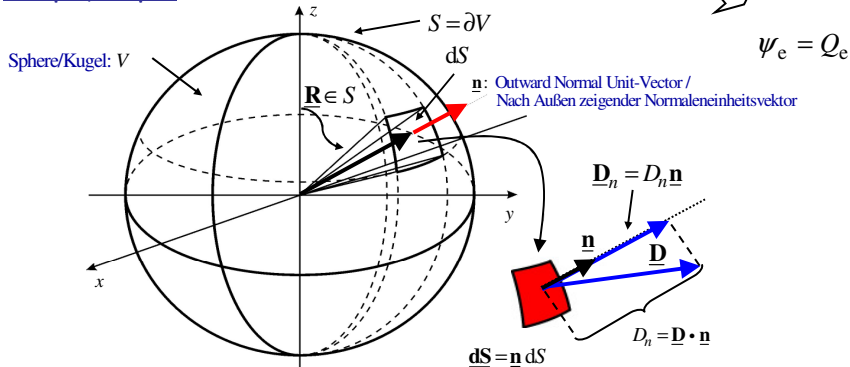
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28

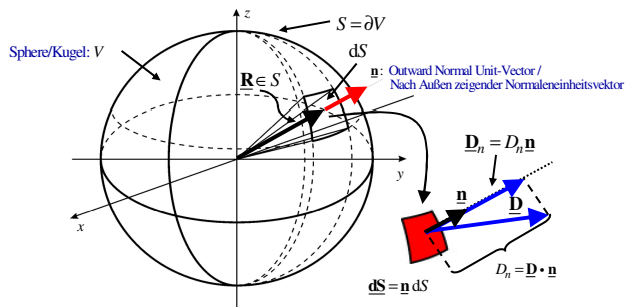
Gauss' Electric Law / Gaußsches elektrisches Gesetz

$$\underbrace{\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot d\mathbf{S}}_{\text{Closed Surface Integral / Geschlossenes Flächenintegral}} = \underbrace{\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS}_{\text{Summation of all Normal Components of } \mathbf{D} \text{ at the Closed Surface } S=\partial V \text{ of the Volume } V / \text{Summation aller Normalkomponenten von } \mathbf{D} \text{ auf der geschlossenen Oberfläche } S=\partial V \text{ des Volumens } V}}_{\text{Flux Through the Closed Surface / Fluss durch die geschlossene Oberfläche}} = \underbrace{\iiint_V \rho_e(\mathbf{R}) dV}_{\text{Volume Integral / Volumenintegral}}_{\text{Summation of all charges inside the Volume } V / \text{Summation aller Ladungen in dem Volumen } V} = Q_e$$

Example / Beispiel:



Example: Sphere with Radius a / Beispiel: Kugel mit Radius a (1)



$$\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS = \iiint_V \rho_e(\mathbf{R}) dV$$

$$d\mathbf{S} = \mathbf{n} dS \quad (= \mathbf{n}_{\vartheta\varphi} h_{\vartheta} h_{\varphi} d\vartheta d\varphi)$$

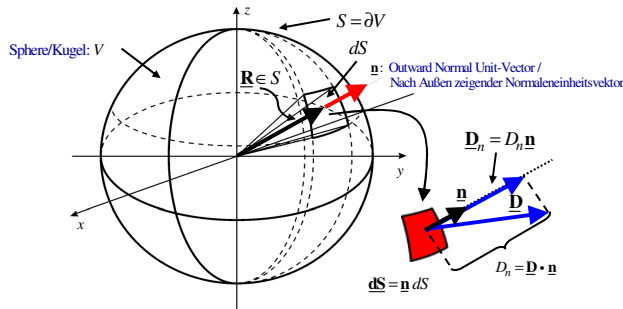
$$= \underbrace{\mathbf{e}_R(\vartheta, \varphi)}_{\mathbf{n}} \underbrace{R^2 \sin \vartheta d\vartheta d\varphi}_{dS} \Big|_{R=a} = \underbrace{\mathbf{e}_R(\vartheta, \varphi)}_{\mathbf{n}} \underbrace{a^2 \sin \vartheta d\vartheta d\varphi}_{dS}$$

$$0 \leq \vartheta \leq \pi$$

$$0 \leq \varphi < 2\pi$$

$$\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}) \cdot d\mathbf{S} = \oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS = \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi} \underbrace{\mathbf{D}[\mathbf{R}(R=a, \vartheta, \varphi)] \cdot \mathbf{e}_R(\vartheta, \varphi)}_{\substack{=D_R[\mathbf{R}(R=a, \vartheta, \varphi)] \\ =D_n[\mathbf{R}(R=a, \vartheta, \varphi)]}} a^2 \sin \vartheta d\vartheta d\varphi = \psi_e$$

Example: Sphere with Radius a / Beispiel: Kugel mit Radius a (2)



$$\oiint_{S=\partial V} \frac{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}{D_n(\mathbf{R})} dS = \iiint_V \rho_e(\mathbf{R}) dV$$

$$dV = R^2 \sin \vartheta dR d\vartheta d\varphi \quad (= h_R h_\vartheta h_\varphi dR d\vartheta d\varphi)$$

$$\iiint_V \rho_e(\mathbf{R}) dV = \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi} \int_{R=0}^a \rho_e[\mathbf{R}(R, \vartheta, \varphi)] R^2 \sin \vartheta dR d\vartheta d\varphi = Q_e$$

$$\begin{aligned} 0 &\leq R \leq a \\ 0 &\leq \vartheta \leq \pi \\ 0 &\leq \varphi < 2\pi \end{aligned}$$

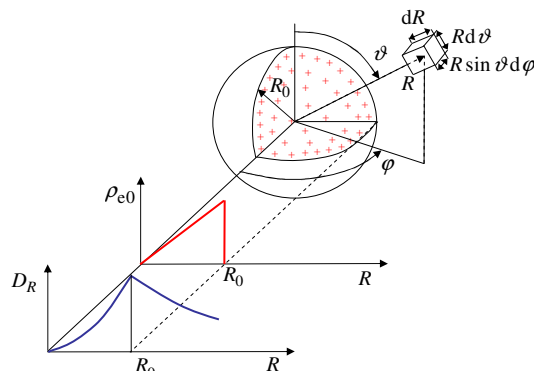
Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

Consider the Electrostatic (ES) Case / Betrachte den elektrostatischen Fall

$$\oiint_{S=\partial V} \frac{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}{=D_n(\mathbf{R})} dS = \iiint_V \rho_e(\mathbf{R}) dV$$

Electric Charge Density / Elektrische Raumladungsdichte

$$\rho_e(\mathbf{R}) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases} \quad \text{Radial Symmetry / Radialsymmetrisch !}$$



Metric Coefficients / Metrische Koeffizienten

Cartesian Coordinates / Kartesische Koordinaten

$x, y, z = x_1, x_2, x_3$

$\underline{e}_x, \underline{e}_y, \underline{e}_z = \underline{e}_{x_1}, \underline{e}_{x_2}, \underline{e}_{x_3}$

$\underline{e}_x \perp \underline{e}_y \perp \underline{e}_z ; \underline{e}_{x_1} \perp \underline{e}_{x_2} \perp \underline{e}_{x_3}$

Metric Scaling / Metrische Skalierung

Orthogonal Curvilinear Coordinates / Orthogonale Krummlinige Koordinaten

ξ_1, ξ_2, ξ_3

$\underline{e}_{\xi_1}, \underline{e}_{\xi_2}, \underline{e}_{\xi_3}$

$\underline{e}_{\xi_1} \perp \underline{e}_{\xi_2} \perp \underline{e}_{\xi_3}$

Cartesian Coordinates / Kartesische Koordinaten

$x = x(\xi_1, \xi_2, \xi_3)$

$y = y(\xi_1, \xi_2, \xi_3)$

$z = z(\xi_1, \xi_2, \xi_3)$

Orthogonal Curvilinear Coordinates / Orthogonale Krummlinige Koordinaten

$\xi_1 = \xi_1(x, y, z)$

$\xi_2 = \xi_2(x, y, z)$

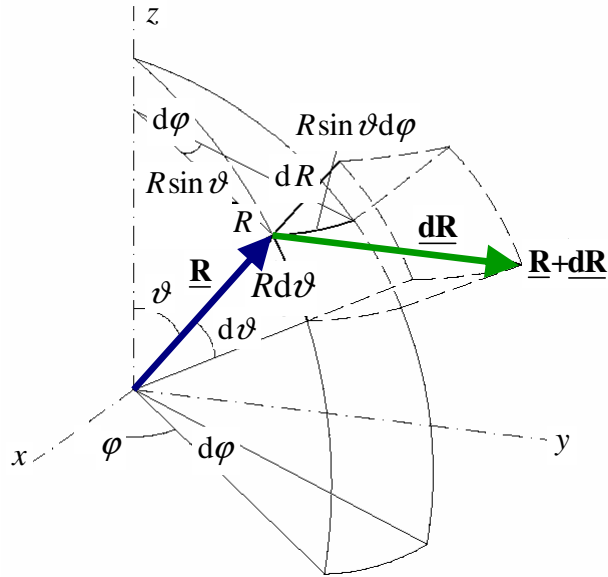
$\xi_3 = \xi_3(x, y, z)$

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Metric Coefficients - Cylindrical Coordinate System / Metrische Koeffizienten - Zylinderkoordinatensystem

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**Metric Coefficients - Spherical Coordinate System /
Metrische Koeffizienten - Kugelkoordinatensystem**



Metric Coefficients / Metrische Koeffizienten

**Cartesian Coordinates /
Kartesische Koordinaten**

$$x, y, z = x_1, x_2, x_3 = \xi_1, \xi_2, \xi_3$$

$$x = x(\xi_1, \xi_2, \xi_3)$$

$$y = y(\xi_1, \xi_2, \xi_3)$$

$$z = z(\xi_1, \xi_2, \xi_3)$$

$$\mathbf{R} = x(\xi_1, \xi_2, \xi_3)\mathbf{e}_x + y(\xi_1, \xi_2, \xi_3)\mathbf{e}_y + z(\xi_1, \xi_2, \xi_3)\mathbf{e}_z$$

$$\frac{\partial \mathbf{R}}{\partial \xi_i} = \frac{\partial x(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \mathbf{e}_x + \frac{\partial y(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \mathbf{e}_y + \frac{\partial z(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \mathbf{e}_z$$

$i = 1, 2, 3$

$$\frac{\partial \mathbf{R}}{\partial \xi_i} = \underbrace{\left| \frac{\partial \mathbf{R}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right|}_{\text{Magnitude / Betrag} = h_{\xi_i}} \underbrace{\frac{\frac{\partial \mathbf{R}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i}}{\left| \frac{\partial \mathbf{R}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right|}}_{\text{Direction / Richtung} = \mathbf{e}_{\xi_i}}, \quad i = 1, 2, 3$$

**Orthogonal Curvilinear Coordinates /
Orthogonale Krummlinige Koordinaten**

$$\xi_1, \xi_2, \xi_3$$

$$\xi_1 = \xi_1(x, y, z)$$

$$\xi_2 = \xi_2(x, y, z)$$

$$\xi_3 = \xi_3(x, y, z)$$

Metric Coefficients / Metrische Koeffizienten

$$h_{\xi_i} = \left| \frac{\partial \mathbf{R}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right|$$

$$= \sqrt{\frac{\partial \mathbf{R}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \cdot \frac{\partial \mathbf{R}(\xi_1, \xi_2, \xi_3)}{\partial \xi_i}}$$

$$= \sqrt{\left(\frac{\partial x(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right)^2 + \left(\frac{\partial y(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right)^2 + \left(\frac{\partial z(\xi_1, \xi_2, \xi_3)}{\partial \xi_i} \right)^2}$$

$i = 1, 2, 3$

**Example: Metric Coefficients of the Cartesian Coordinate System /
Beispiel: Metrische Koeffizienten des Kartesischen Koordinatensystems**

$$\xi_1 = x; \xi_2 = y; \xi_3 = z$$

$$\begin{aligned} h_x &= \left| \frac{\partial \mathbf{R}(x, y, z)}{\partial x} \right| = \sqrt{\frac{\partial \mathbf{R}(x, y, z)}{\partial x} \cdot \frac{\partial \mathbf{R}(x, y, z)}{\partial x}} \\ &= \sqrt{\left(\frac{\partial x(x, y, z)}{\partial x} \right)^2 + \left(\frac{\partial y(x, y, z)}{\partial x} \right)^2 + \left(\frac{\partial z(x, y, z)}{\partial x} \right)^2} \\ &= \sqrt{\underbrace{\left(\frac{\partial x}{\partial x} \right)^2}_{=1} + \underbrace{\left(\frac{\partial y}{\partial x} \right)^2}_{=0} + \underbrace{\left(\frac{\partial z}{\partial x} \right)^2}_{=0}} = 1 \end{aligned}$$

$$\begin{aligned} h_z &= \left| \frac{\partial \mathbf{R}(x, y, z)}{\partial z} \right| = \sqrt{\frac{\partial \mathbf{R}(x, y, z)}{\partial z} \cdot \frac{\partial \mathbf{R}(x, y, z)}{\partial z}} \\ &= \sqrt{\left(\frac{\partial x(x, y, z)}{\partial z} \right)^2 + \left(\frac{\partial y(x, y, z)}{\partial z} \right)^2 + \left(\frac{\partial z(x, y, z)}{\partial z} \right)^2} \\ &= \sqrt{\underbrace{\left(\frac{\partial x}{\partial z} \right)^2}_{=0} + \underbrace{\left(\frac{\partial y}{\partial z} \right)^2}_{=0} + \underbrace{\left(\frac{\partial z}{\partial z} \right)^2}_{=1}} = 1 \end{aligned}$$

$$\begin{aligned} h_y &= \left| \frac{\partial \mathbf{R}(x, y, z)}{\partial y} \right| = \sqrt{\frac{\partial \mathbf{R}(x, y, z)}{\partial y} \cdot \frac{\partial \mathbf{R}(x, y, z)}{\partial y}} \\ &= \sqrt{\left(\frac{\partial x(x, y, z)}{\partial y} \right)^2 + \left(\frac{\partial y(x, y, z)}{\partial y} \right)^2 + \left(\frac{\partial z(x, y, z)}{\partial y} \right)^2} \\ &= \sqrt{\underbrace{\left(\frac{\partial x}{\partial y} \right)^2}_{=0} + \underbrace{\left(\frac{\partial y}{\partial y} \right)^2}_{=1} + \underbrace{\left(\frac{\partial z}{\partial y} \right)^2}_{=0}} = 1 \end{aligned}$$

**Cartesian Coordinate System /
Kartesisches Koordinatensystem**

$$h_x = 1$$

$$h_y = 1$$

$$h_z = 1$$

Metric Coefficients / Metrische Koeffizienten

**Cartesian Coordinate System /
Kartesisches Koordinatensystem**

$$h_x = 1$$

$$h_y = 1$$

$$h_z = 1$$

**Cylindrical Coordinate System /
Zylinderkoordinatensystem**

$$h_r = 1$$

$$h_\varphi = r$$

$$h_z = 1$$

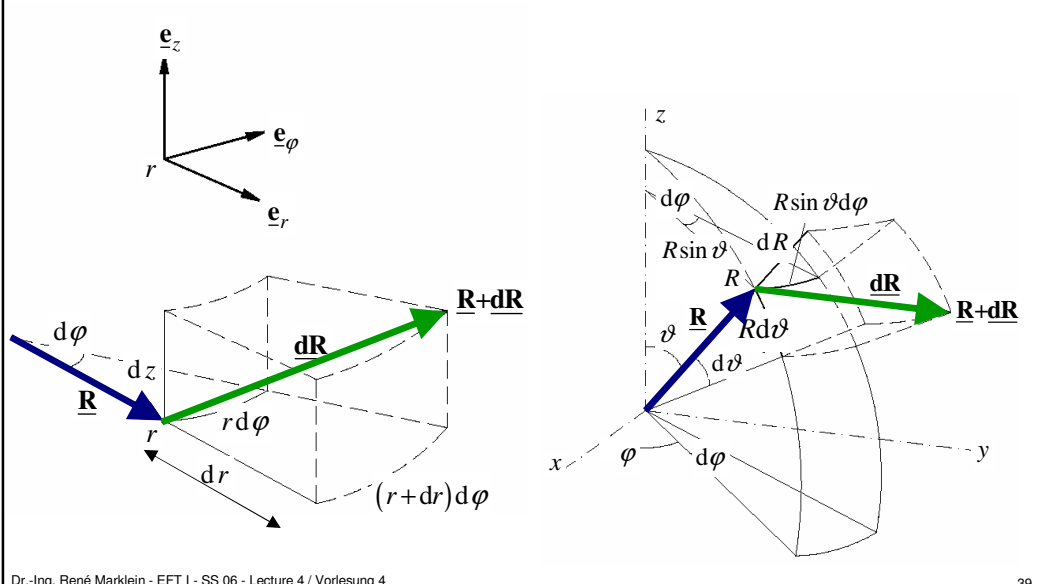
**Spherical Coordinate System /
Kugelkoordinatensystem**

$$h_R = 1$$

$$h_\vartheta = R$$

$$h_\varphi = R \sin \vartheta$$

**Metric Coefficients - Cylindrical and Spherical Coordinate System /
Metrische Koeffizienten - Zylinder- und Kugelkoordinatensystem**



Dr.-Ing. René Marklein - EFT I - SS 06 - Lecture 4 / Vorlesung 4

39

**Metric Coefficients and Vector Differential Line Elements /
Metrische Koeffizienten und vektorielle differentielle Linienelemente**

**Cartesian Coordinate System /
Kartesisches Koordinatensystem**

$$h_x = 1, \quad h_y = 1, \quad h_z = 1$$

$$\begin{aligned} \underline{dR}_x &= \underline{s} dR \\ &= \underline{e}_x h_x dx \\ &= \underline{e}_x dx \end{aligned}$$

$$\begin{aligned} \underline{dR}_y &= \underline{s} dR \\ &= \underline{e}_y h_y dy \\ &= \underline{e}_y dy \end{aligned}$$

$$\begin{aligned} \underline{dR}_z &= \underline{n} dR \\ &= \underline{e}_z h_z dz \\ &= \underline{e}_z dz \end{aligned}$$

**Cylindrical Coordinate System /
Zylinderkoordinatensystem**

$$h_r = 1, \quad h_\varphi = r, \quad h_z = 1$$

$$\begin{aligned} \underline{dR}_r &= \underline{s} dR \\ &= \underline{e}_r h_r dr \\ &= \underline{e}_r dr \end{aligned}$$

$$\begin{aligned} \underline{dR}_\varphi &= \underline{s} dR \\ &= \underline{e}_\varphi h_\varphi d\varphi \\ &= \underline{e}_\varphi r d\varphi \end{aligned}$$

$$\begin{aligned} \underline{dR}_z &= \underline{s} dR \\ &= \underline{e}_z h_z dz \\ &= \underline{e}_z dz \end{aligned}$$

**Spherical Coordinate System /
Kugelkoordinatensystem**

$$h_R = 1, \quad h_\vartheta = R, \quad h_\varphi = R \sin \vartheta$$

$$\begin{aligned} \underline{dR}_R &= \underline{s} dR \\ &= \underline{e}_R h_R dR \\ &= \underline{e}_R dR \end{aligned}$$

$$\begin{aligned} \underline{dR}_\vartheta &= \underline{s} dR \\ &= \underline{e}_\vartheta h_\vartheta d\vartheta \\ &= \underline{e}_\vartheta R d\vartheta \end{aligned}$$

$$\begin{aligned} \underline{dR}_\varphi &= \underline{s} dR \\ &= \underline{e}_\varphi h_\varphi d\varphi \\ &= \underline{e}_\varphi R \sin \vartheta d\varphi \end{aligned}$$

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40

Metric Coefficients and Differential Volume and Surface Elements / Metrische Koeffizienten und differentielle Volumen- und Flächenelemente

Cartesian Coordinate System / Kartesisches Koordinatensystem

$$h_x = 1, \quad h_y = 1, \quad h_z = 1$$

$$\begin{aligned} dV &= h_x dx h_y dy h_z dz \\ &= h_x h_y h_z dx dy dz \\ &= dx dy dz \end{aligned}$$

$$d\mathbf{S}_{yz} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_y \times \mathbf{e}_z) h_y h_z dy dz \\ &= \mathbf{e}_x dy dz \end{aligned}$$

$$d\mathbf{S}_{xz} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_z \times \mathbf{e}_x) h_x h_z dx dz \\ &= \mathbf{e}_y dx dz \end{aligned}$$

$$d\mathbf{S}_{xy} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_x \times \mathbf{e}_y) h_x h_y dx dy \\ &= \mathbf{e}_z dx dy \end{aligned}$$

Cylindrical Coordinate System / Zylinderkoordinatensystem

$$h_r = 1, \quad h_\varphi = r, \quad h_z = 1$$

$$\begin{aligned} dV &= h_r dr h_\varphi d\varphi h_z dz \\ &= h_r h_\varphi h_z dr d\varphi dz \\ &= r dr d\varphi dz \end{aligned}$$

$$d\mathbf{S}_{\varphi z} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_\varphi \times \mathbf{e}_z) h_\varphi h_z d\varphi dz \\ &= \mathbf{e}_r r dy dz \end{aligned}$$

$$d\mathbf{S}_{rz} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_z \times \mathbf{e}_r) h_r h_z dr dz \\ &= \mathbf{e}_\varphi r dr dz \end{aligned}$$

$$d\mathbf{S}_{r\varphi} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_r \times \mathbf{e}_\varphi) h_r h_\varphi dr d\varphi \\ &= \mathbf{e}_z r dr d\varphi \end{aligned}$$

Spherical Coordinate System / Kugelkoordinatensystem

$$h_R = 1, \quad h_\vartheta = R, \quad h_\varphi = R \sin \vartheta$$

$$\begin{aligned} dV &= h_R dR h_\vartheta d\vartheta h_\varphi d\varphi \\ &= h_R h_\vartheta h_\varphi dR d\vartheta d\varphi \\ &= R^2 \sin \vartheta dR d\vartheta d\varphi \end{aligned}$$

$$d\mathbf{S}_{\vartheta\varphi} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_\vartheta \times \mathbf{e}_\varphi) h_\vartheta h_\varphi d\vartheta d\varphi \\ &= \mathbf{e}_R R^2 \sin \vartheta d\vartheta d\varphi \end{aligned}$$

$$d\mathbf{S}_{r\varphi} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_\varphi \times \mathbf{e}_R) h_R h_\varphi dR d\varphi \\ &= \mathbf{e}_\vartheta R \sin \vartheta dR d\varphi \end{aligned}$$

$$d\mathbf{S}_{R\vartheta} = \mathbf{n} dS$$

$$\begin{aligned} &= (\mathbf{e}_R \times \mathbf{e}_\vartheta) h_R h_\vartheta dR d\vartheta \\ &= \mathbf{e}_\varphi R dR d\vartheta \end{aligned}$$

Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

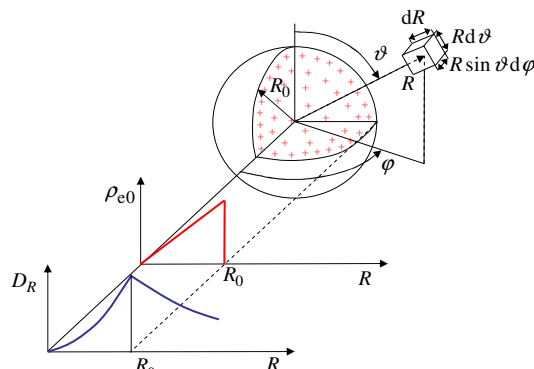
Consider the Electrostatic (ES) Case /
Betrachte den elektrostatischen Fall

$$\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{\substack{=D_n(\mathbf{R}) \\ =D_R(\mathbf{R})}} dS = \iiint_V \rho_c(\mathbf{R}) dV$$

Electric Charge Density /
Elektrische Raumladungsdichte

$$\rho_c(\mathbf{R}) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

Radial Symmetry /
Radialsymmetrisch !



**Example: Electric Field Due to Spherically Symmetric Charge Distribution /
Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte**

$$\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{\substack{=D_n(R) \\ =D_R(R)}} dS = \iiint_V \rho_e(\mathbf{R}) dV = Q_e$$

$$\rho_e(R) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R \leq R_0 \\ 0 & R > R_0 \end{cases}$$

2 Cases / 2 Fälle

$$0 \leq R < R_0$$

$$R > R_0$$

$$\begin{aligned} \oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} h_\varphi h_\vartheta d\varphi d\vartheta \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin\vartheta d\varphi d\vartheta \end{aligned}$$

$$\begin{aligned} \oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} h_\varphi h_\vartheta d\varphi d\vartheta \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin\vartheta d\varphi d\vartheta \end{aligned}$$

$$\iiint_V \rho_e(R) dV = \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^R \rho_e(R) R^2 \sin\vartheta dR d\varphi d\vartheta$$

$$\iiint_V \rho_e(R) dV = \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^{R_0} \rho_e(R) R^2 \sin\vartheta dR d\varphi d\vartheta$$

**Example: Electric Field Due to Spherically Symmetric Charge Distribution /
Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte**

2 Cases / 2 Fälle

$$R < R_0$$

$$R > R_0$$

$$\begin{aligned} \oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin\vartheta d\varphi d\vartheta \\ &= D_R(R) R^2 \underbrace{\int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin\vartheta d\varphi d\vartheta}_{=4\pi} \\ &= D_R(R) 4\pi R^2 \end{aligned}$$

$$\begin{aligned} \oiint_{S=\partial V} D_R(R) dS &= D_R(R) \oiint_{S=\partial V} dS \\ &= D_R(R) \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} R^2 \sin\vartheta d\varphi d\vartheta \\ &= D_R(R) R^2 \underbrace{\int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin\vartheta d\varphi d\vartheta}_{=4\pi} \\ &= D_R(R) 4\pi R^2 \end{aligned}$$

**Example: Electric Field Due to Spherically Symmetric Charge Distribution /
Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte**

2 Cases / 2 Fälle

$$\begin{aligned}
 R < R_0 \\
 \iiint_V \rho_e(R) dV &= \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^R \rho_e(R) R^2 \sin \vartheta dR d\varphi d\vartheta \\
 &= \rho_{e0} \int_{R=0}^R \frac{R}{R_0} R^2 \underbrace{\left[\int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin \vartheta d\varphi d\vartheta \right]}_{=4\pi} dR \\
 &= \frac{4\pi\rho_{e0}}{R_0} \int_{R=0}^R R^3 dR \\
 &= \frac{4\pi\rho_{e0}}{R_0} \frac{R^4}{4} \Big|_{R=0}^R \\
 &= \frac{4\pi\rho_{e0}}{R_0} \frac{R^4}{4} \\
 &= \pi\rho_{e0} \frac{R^4}{R_0}
 \end{aligned}$$

$$\begin{aligned}
 R > R_0 \\
 \iiint_V \rho_e(R) dV &= \int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \int_{R=0}^{R_0} \rho_e(R) R^2 \sin \vartheta dR d\varphi d\vartheta \\
 &= \rho_{e0} \int_{R=0}^{R_0} \frac{R}{R_0} R^2 \underbrace{\left[\int_{\vartheta=0}^{\pi} \int_{\varphi=0}^{2\pi} \sin \vartheta d\varphi d\vartheta \right]}_{=4\pi} dR \\
 &= \frac{4\pi\rho_{e0}}{R_0} \int_{R=0}^{R_0} R^3 dR \\
 &= \frac{4\pi\rho_{e0}}{R_0} \frac{R^4}{4} \Big|_{R=0}^{R_0} \\
 &= \frac{4\pi\rho_{e0}}{R_0} \frac{R_0^4}{4} \\
 &= \pi\rho_{e0} R_0^3
 \end{aligned}$$

**Example: Electric Field Due to Spherically Symmetric Charge Distribution /
Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte**

2 Cases / 2 Fälle

$$\begin{aligned}
 R < R_0 \\
 \underbrace{\oint_{S=\partial V} D_R(R) dS}_{=D_R(R)4\pi R^2} &= \underbrace{\iiint_V \rho_e(R) dV}_{=\pi\rho_{e0} \frac{R^4}{R_0}} \\
 D_R(R) 4\pi R^2 &= \pi\rho_{e0} \frac{R^4}{R_0} \\
 D_R(R) &= \frac{\pi\rho_{e0}}{4\pi R^2} \frac{R^4}{R_0} \\
 &= \frac{\rho_{e0}}{4} \frac{R^2}{R_0}
 \end{aligned}$$

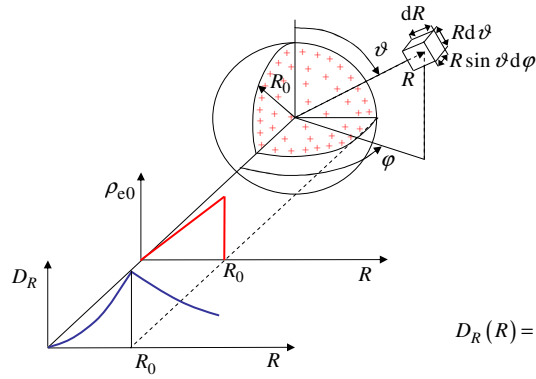
$$\begin{aligned}
 R > R_0 \\
 \underbrace{\oint_{S=\partial V} D_R(R) dS}_{=D_R(R)4\pi R^2} &= \underbrace{\iiint_V \rho_e(R) dV}_{=\pi\rho_{e0} R_0^3} \\
 D_R(R) 4\pi R^2 &= \pi\rho_{e0} R_0^3 \\
 D_R(R) &= \frac{\pi\rho_{e0} R_0^3}{4\pi R^2} \\
 &= \frac{\rho_{e0}}{4} \frac{R_0^3}{R^2}
 \end{aligned}$$

**Example: Electric Field Due to Spherically Symmetric Charge Distribution /
 Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte**

Electric Charge Density /
 Elektrische Raumladungsdichte

$$\rho_e(\mathbf{R}) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

Radial Symmetry /
 Radialsymmetrisch !



$$D_R(R) = \frac{\rho_{e0}}{4} \begin{cases} \frac{R^2}{R_0} & R < R_0 \\ \frac{R_0^3}{R^2} & R > R_0 \end{cases}$$

End of Lecture 4 /
 Ende der 4. Vorlesung