

**Numerical Methods of
Electromagnetic Field Theory I (NFT I)
Numerische Methoden der
Elektromagnetischen Feldtheorie I (NFT I) /**

2nd Lecture / 2. Vorlesung

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1-D Electromagnetic Wave Propagation / 1D elektromagnetische Wellenausbreitung

**Constitutive Equations for Vacuum /
Konstituierende Gleichungen
(Materialgleichungen) für Vakuum**

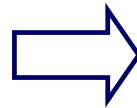
$$\underline{\mathbf{B}}(\underline{\mathbf{R}}, t) = \mu_0 \underline{\mathbf{H}}(\underline{\mathbf{R}}, t)$$

$$\underline{\mathbf{D}}(\underline{\mathbf{R}}, t) = \varepsilon_0 \underline{\mathbf{E}}(\underline{\mathbf{R}}, t)$$

Ansatz / Ansatz

$$\underline{\mathbf{E}}(\underline{\mathbf{R}}, t) = E_x(z, t) \underline{\mathbf{e}}_x$$

$$\underline{\mathbf{H}}(\underline{\mathbf{R}}, t) = H_y(z, t) \underline{\mathbf{e}}_y$$



**The first two Maxwell's Equations are: /
Die ersten beiden Maxwell'schen Gleichungen lauten:**

$$\frac{\partial}{\partial t} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) = -\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) - \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t)$$

$$\frac{\partial}{\partial t} \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) = \nabla \times \underline{\mathbf{H}}(\underline{\mathbf{R}}, t) - \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t)$$



$$\frac{\partial}{\partial t} H_y(z, t) = -\frac{1}{\mu_0} \frac{\partial}{\partial z} E_x(z, t) - \frac{1}{\mu_0} J_{my}(z, t)$$

$$\frac{\partial}{\partial t} E_x(z, t) = -\frac{1}{\varepsilon_0} \frac{\partial}{\partial z} H_y(z, t) - \frac{1}{\varepsilon_0} J_{ex}(z, t)$$

$$\frac{\partial^2}{\partial z^2} H_y(z, t) - \frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} H_y(z, t) = \begin{cases} -\frac{\partial}{\partial z} J_{ex}(z, t) + \varepsilon_0 \frac{\partial}{\partial t} J_{my}(z, t) & \text{Inhomogeneous 1-D Wave Equation /} \\ & \text{Inhomogene 1-D Wellengleichung} \\ 0 & \text{Homogeneous 1-D Wave Equation /} \\ & \text{Homogene 1-D Wellengleichung} \end{cases}$$

$$\frac{\partial^2}{\partial z^2} E_x(z, t) - \frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} E_x(z, t) = \begin{cases} -\frac{\partial}{\partial z} J_{my}(z, t) + \mu_0 \frac{\partial}{\partial t} J_{ex}(z, t) & \text{Inhomogeneous 1-D Wave Equation /} \\ & \text{Inhomogene 1-D Wellengleichung} \\ 0 & \text{Homogeneous 1-D Wave Equation /} \\ & \text{Homogene 1-D Wellengleichung} \end{cases}$$

Finite Difference (FD) Method / Finite Differenzen (FD) Methode

1-D FD Operators / 1D-FD-Operatoren

**Backward FD Operator /
Rückwärts-FD-Operator**

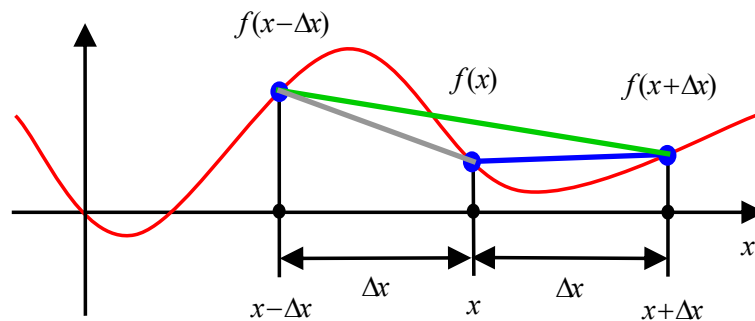
$$\frac{d}{dx} f(x) = \frac{f(x) - f(x - \Delta x)}{\Delta x} + O(\Delta x) \approx \frac{f(x) - f(x - \Delta x)}{\Delta x}$$

**Forward FD Operator /
Vorwärts-FD-Operator**

$$\frac{d}{dx} f(x) = \frac{f(x + \Delta x) - f(x)}{\Delta x} + O(\Delta x) \approx \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

**Central FD Operator /
Zentraler FD-Operator**

$$\frac{d}{dx} f(x) = \frac{f(x + \Delta x) - f(x - \Delta x)}{2\Delta x} + O[(\Delta x)^2] \approx \frac{f(x + \Delta x) - f(x - \Delta x)}{2\Delta x}$$



$$O(\Delta x), O[(\Delta x)^2]$$

**Asymptotic
approximation error /
Asymptotischer
Approximationsfehler**

**Landau symbol "O", big "oh" /
Landau-Symbol „O“, großes „oh“**

FD Method - 1-D FD Operator of Second Order / FD-Methode - 1D-FD-Operator zweiter Ordnung

**Derivative of the second order /
Ableitung der zweiten Ordnung**

$$\frac{d^2}{dx^2} f(x) \approx \frac{f(x + \Delta x) - 2f(x) + f(x - \Delta x)}{(\Delta x)^2} \quad (1)$$

Taylor series expansions / Taylor-Reihenentwicklungen

$$f(x + \Delta x) = f(x) + \Delta x \frac{df(x)}{dx} + \frac{(\Delta x)^2}{2!} \frac{d^2 f(x)}{dx^2} + \frac{(\Delta x)^3}{3!} \frac{d^3 f(x)}{dx^3} + \frac{(\Delta x)^4}{4!} \frac{d^4 f(x)}{dx^4} + \mathcal{O}[(\Delta x)^5] \quad (2)$$

$$f(x) = f(x) \quad (3)$$

$$f(x - \Delta x) = f(x) - \Delta x \frac{df(x)}{dx} + \frac{(\Delta x)^2}{2!} \frac{d^2 f(x)}{dx^2} - \frac{(\Delta x)^3}{3!} \frac{d^3 f(x)}{dx^3} + \frac{(\Delta x)^4}{4!} \frac{d^4 f(x)}{dx^4} + \mathcal{O}[(\Delta x)^5] \quad (4)$$

**Multiply (2) with α , (3) with β , and (4) with γ /
Multipliziere (2) mit α , (3) mit β und (4) mit γ**

$$\alpha f(x + \Delta x) = \alpha f(x) + \alpha \Delta x \frac{df(x)}{dx} + \alpha \frac{(\Delta x)^2}{2!} \frac{d^2 f(x)}{dx^2} + \alpha \frac{(\Delta x)^3}{3!} \frac{d^3 f(x)}{dx^3} + \alpha \frac{(\Delta x)^4}{4!} \frac{d^4 f(x)}{dx^4} + \mathcal{O}[(\Delta x)^5] \quad (5)$$

$$\beta f(x) = \beta f(x) \quad (6)$$

$$\gamma f(x - \Delta x) = \gamma f(x) - \gamma \Delta x \frac{df(x)}{dx} + \gamma \frac{(\Delta x)^2}{2!} \frac{d^2 f(x)}{dx^2} - \gamma \frac{(\Delta x)^3}{3!} \frac{d^3 f(x)}{dx^3} + \gamma \frac{(\Delta x)^4}{4!} \frac{d^4 f(x)}{dx^4} + \mathcal{O}[(\Delta x)^5] \quad (7)$$

FD Method - 1-D FD Operator of Second Order / FD-Methode - 1D-FD-Operator zweiter Ordnung

$$\begin{aligned} & \alpha f(x + \Delta x) + \beta f(x) + \gamma f(x - \Delta x) \\ &= (\alpha + \beta + \gamma)f(x) + (\alpha - \gamma)\Delta x \frac{df(x)}{dx} + (\alpha + \gamma) \frac{(\Delta x)^2}{2!} \frac{d^2 f(x)}{dx^2} \\ &+ (\alpha - \gamma) \frac{(\Delta x)^3}{3!} \frac{d^3 f(x)}{dx^3} + (\alpha + \gamma) \frac{(\Delta x)^4}{4!} \frac{d^4 f(x)}{dx^4} + \mathcal{O}[(\Delta x)^5] \end{aligned}$$

$$\begin{aligned} \alpha - \gamma = 0 & \rightarrow \gamma = \alpha \\ \alpha + \beta + \gamma = 0 & \rightarrow \beta = -2\alpha \end{aligned}$$

**With the parameters /
Mit den Parametern**

$$\begin{aligned} \alpha &= \gamma = 1 \\ \beta &= -2 \end{aligned}$$

$$\begin{aligned} f(x + \Delta x) - 2f(x) + f(x - \Delta x) &= 2 \frac{(\Delta x)^2}{2} \frac{d^2 f(x)}{dx^2} + 2 \frac{(\Delta x)^4}{\underbrace{4!}_{1 \cdot 2 \cdot 3 \cdot 4 = 24}} \frac{d^4 f(x)}{dx^4} + \mathcal{O}[(\Delta x)^5] \\ \frac{f(x + \Delta x) - 2f(x) + f(x - \Delta x)}{(\Delta x)^2} &= \frac{d^2 f(x)}{dx^2} + \frac{(\Delta x)^2}{12} \frac{d^4 f(x)}{dx^4} + \mathcal{O}[(\Delta x)^3] \\ \frac{d^2 f(x)}{dx^2} &= \frac{f(x + \Delta x) - 2f(x) + f(x - \Delta x)}{(\Delta x)^2} - \underbrace{\frac{(\Delta x)^2}{12} \frac{d^4 f(x)}{dx^4}}_{\mathcal{O}[(\Delta x)^2]} + \mathcal{O}[(\Delta x)^3] \\ \frac{d^2 f(x)}{dx^2} &= \frac{f(x + \Delta x) - 2f(x) + f(x - \Delta x)}{(\Delta x)^2} + \mathcal{O}[(\Delta x)^2] \end{aligned}$$

FD Method - 1-D FD Operators of Second Order / FD-Methode - 1D-FD-Operatoren zweiter Ordnung

Function of one variable / Funktion einer Variablen

$$\frac{d^2}{dx^2} f(x) = \frac{f(x + \Delta x) - 2f(x) + f(x - \Delta x)}{(\Delta x)^2} + O[(\Delta x)^2]$$
$$\frac{d^2}{dt^2} f(t) = \frac{f(t + \Delta t) - 2f(t) + f(t - \Delta t)}{(\Delta t)^2} + O[(\Delta t)^2]$$

Function of two variables / Funktion von zwei Variablen

$$\frac{\partial^2}{\partial x^2} f(x, t) = \frac{f(x + \Delta x, t) - 2f(x, t) + f(x - \Delta x, t)}{(\Delta x)^2} + O[(\Delta x)^2]$$
$$\frac{\partial^2}{\partial t^2} f(x, t) = \frac{f(x, t + \Delta t) - 2f(x, t) + f(x, t - \Delta t)}{(\Delta t)^2} + O[(\Delta t)^2]$$

Combined Case / Kombinerter Fall

$$\frac{\partial^2}{\partial x^2} f(x, t) + \frac{\partial^2}{\partial t^2} f(x, t)$$
$$= \frac{f(x + \Delta x, t) - 2f(x, t) + f(x - \Delta x, t)}{(\Delta x)^2} + \frac{f(x, t + \Delta t) - 2f(x, t) + f(x, t - \Delta t)}{(\Delta t)^2} + O[(\Delta x)^2] + O[(\Delta t)^2]$$

FD Method – 1-D Wave Equation / FD-Methode – 1D Wellengleichung

$$\frac{\partial^2}{\partial z^2} E_x(z,t) - \frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} E_x(z,t) = - \underbrace{\frac{\partial}{\partial z} J_{my}(z,t)}_{=0} + \mu_0 \frac{\partial}{\partial t} J_{ex}(z,t)$$

$$= \mu_0 \frac{\partial}{\partial t} J_{ex}(z,t)$$

**Central FD Operators /
Zentrale FD-Operatoren**

$$\frac{\partial^2}{\partial z^2} E_x(z,t) = \frac{E_x(z + \Delta z, t) - 2E_x(z, t) + E_x(z - \Delta z, t)}{(\Delta z)^2} + \mathcal{O}[(\Delta z)^2]$$

$$\frac{\partial^2}{\partial t^2} E_x(z,t) = \frac{E_x(z, t + \Delta t) - 2E_x(z, t) + E_x(z, t - \Delta t)}{(\Delta t)^2} + \mathcal{O}[(\Delta t)^2]$$

**Backward FD Operator /
Rückwärts-FD-Operator**

$$\frac{\partial}{\partial t} J_{ex}(z,t) = \frac{J_{ex}(z,t) - J_{ex}(z, t - \Delta t)}{\Delta t} + \mathcal{O}(\Delta t)$$

$$\frac{E_x(z + \Delta z, t) - 2E_x(z, t) + E_x(z - \Delta z, t)}{(\Delta z)^2} - \frac{1}{c_0^2} \frac{E_x(z, t + \Delta t) - 2E_x(z, t) + E_x(z, t - \Delta t)}{(\Delta t)^2} = \mu_0 \frac{J_{ex}(z,t) - J_{ex}(z, t - \Delta t)}{\Delta t}$$

$$+ \mathcal{O}[(\Delta z)^2] + \mathcal{O}[(\Delta t)^2]$$

FD Method – 1D Wave Equation / FD-Methode – 1D Wellengleichung

Explicit FD algorithm in the time domain of 2nd order in space and time /
Expliziter FD-Algorithmus im Zeitbereich 2ter Ordnung in Raum und Zeit

$$E_x(z, t + \Delta t) = 2E_x(z, t) - E_x(z, t - \Delta t) + c_0^2 \frac{(\Delta t)^2}{(\Delta z)^2} [E_x(z + \Delta z, t) - 2E_x(z, t) + E_x(z - \Delta z, t)] \\ + c_0^2 \mu_0 \Delta t [J_{\text{ex}}(z, t) - J_{\text{ex}}(z, t - \Delta t)] + \mathcal{O}[(\Delta z)^2] + \mathcal{O}[(\Delta t)^2]$$

Marching-on-in-time algorithm /
„Marschieren in der Zeit“-Algorithmus

$$z \rightarrow n_z \Delta z, \quad n_z = 1, \dots, N_z \\ t \rightarrow n_t \Delta t, \quad n_t = 1, \dots, N_t$$

$$E_x(z, t) \rightarrow E_x^{(n_z, n_t)} \\ J_{\text{ex}}(z, t) \rightarrow J_{\text{ex}}^{(n_z, n_t)}$$

$$E_x^{(n_z, n_t+1)} = 2E_x^{(n_z, n_t)} - E_x^{(n_z, n_t-1)} + c_0^2 \frac{(\Delta t)^2}{(\Delta z)^2} [E_x^{(n_z+1, n_t)} - 2E_x^{(n_z, n_t)} + E_x^{(n_z-1, n_t)}] + c_0^2 \mu_0 \Delta t [J_{\text{ex}}^{(n_z, n_t)} - J_{\text{ex}}^{(n_z, n_t-1)}]$$

$$\Delta z = ?$$

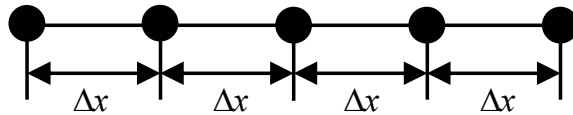
$$\Delta t = ?$$

FD Method – Properties / FD-Methode - Eigenschaften

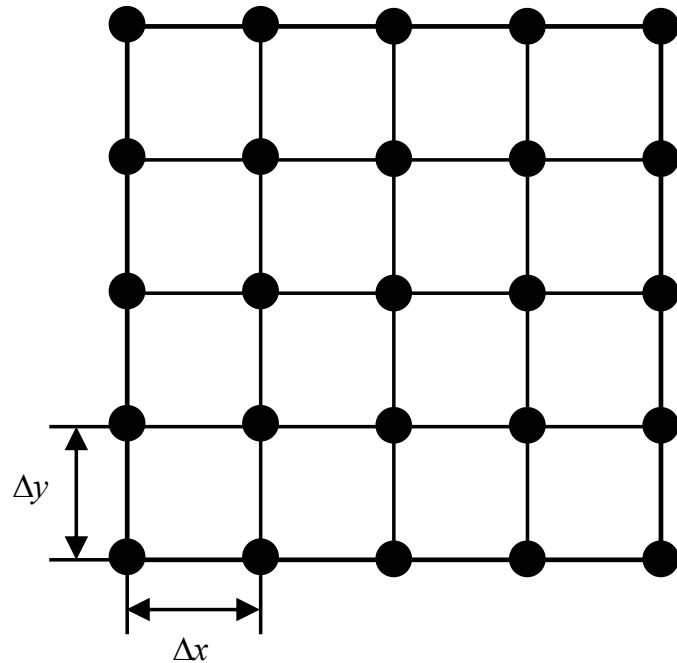
- ✚ **Spatial and Temporal Discretization /
Räumliche und zeitliche Diskretisierung** $\Delta z = ?$
 $\Delta t = ?$
- ✚ **Consistency /
Konsistenz**
- ✚ **Dissipation /
Dissipation**
- ✚ **Stability Condition /
Stabilitätsbedingung** $\Delta t = f(\Delta z)$
- ✚ **Convergence /
Konvergenz**

FD Method – 1-D, 2-D, 3-D Grid System / FD-Methode – 1D-, 2D- und 3D-Gittersystem

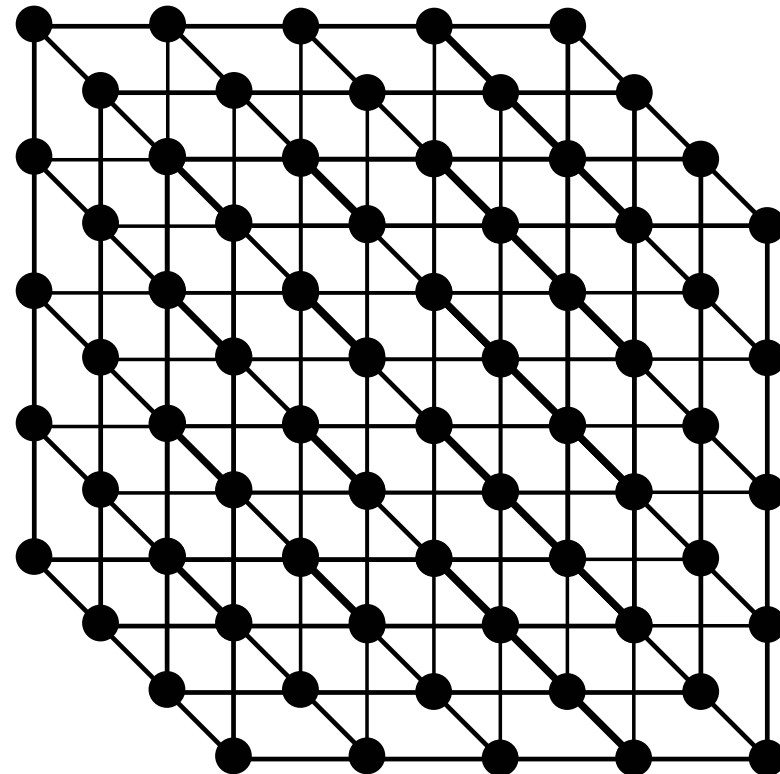
**1-D Node-Based Grid /
1D knotenbasiertes Gitter**



**2-D Node-Based Grid /
2D knotenbasiertes Gitter**



**3-D Node-Based Grid /
3D knotenbasiertes Gitter**



● **Nodes with Assigned Field Quantities /
Knoten mit zugeordneten Feldgrößen:**

Φ [V], \underline{E} [V/m], \underline{H} [A/m], \underline{A} [Vs/m]

FD Method – Grid Size / FD-Methode - Gittergröße

Sampling Theorem in Space / Abtastkriterium im Raum

$$\Delta x \leq \frac{\lambda_{\min}}{2}$$

Δx : **Spatial grid size /
Räumliche Gittergröße**
 λ_{\min} : **Minimal wavelength /
Minimale Wellenlänge**

$$\lambda_{\min} = \frac{c_{\min}}{f_{\max}}$$

c_{\min} : **Minimal phase velocity /
Minimale Phasengeschwindigkeit**
 f_{\max} : **Maximal frequency /
Maximale Frequenz**

**Sampling Resolution /
Abtastauflösung**

$$G = \frac{\lambda_{\min}}{\Delta x} \quad G = 10, \dots, 30$$
$$\Delta x = \frac{\lambda_{\min}}{G} = \frac{\lambda_{\min}}{10}, \dots, \frac{\lambda_{\min}}{30}$$

**Rule of thumb /
Daumenregel**

FD Method – Stability Condition / FD-Methode - Stabilitätsbedingung

Stability Condition for an FD algorithm of 2nd order in space and time– CFL-Condition /
 Stabilitätsbedingung für einen FD-Algorithmus zweiter Ordnung in Raum und Zeit– CFL-Bedingung

$$\Delta t \leq \frac{1}{\sqrt{D}} \frac{\Delta x}{c}$$

$D = 1, 2, 3$: Spatial dimension of the problem /

Räumliche Dimension des Problems

c : Maximal Energy Propagation Velocity /

Maximale Energieausbreitungsgeschwindigkeit

CFL: Courant, Friedrichs, Lewy / CFL: Courant, Friedrichs, Lewy /

Courant, R., K. Friedrichs und H. Lewy: Über die partiellen Differenzengleichungen der mathematischen Physik. *Mathematische Annalen*, Vol. 100, S. 32-74, 1928.

Translation / Übersetzung:

Courant, R., K. Friedrichs, and H. Lewy: On the partial differential equations of mathematical physics. *IBM Journal*, pp. 215-324, March 1967.

1-D / 1D:	$\Delta t \leq \Delta t_{\max} = \frac{\Delta x}{c}$	$\hat{\Delta t} \leq 1$
2-D / 2D:	$\Delta t \leq \Delta t_{\max} = \frac{1}{\sqrt{2}} \frac{\Delta x}{c}$	$\hat{\Delta t} \leq \frac{1}{\sqrt{2}} \approx 0.707$
3-D / 3D:	$\Delta t \leq \Delta t_{\max} = \frac{1}{\sqrt{3}} \frac{\Delta x}{c}$	$\hat{\Delta t} \leq \frac{1}{\sqrt{3}} \approx 0.577$

$$\hat{\Delta t} = \frac{\Delta t}{\Delta t_{\text{ref}}} \quad : \quad \begin{array}{l} \text{Courant number /} \\ \text{Courant - Zahl} \end{array}$$

$$\Delta t_{\text{ref}} = \frac{\Delta x}{c}$$

FD Method – Normalization / FD-Methode – Normierung

Δx_{ref} = Reference cell width in m / Referenz-Zellenweite in m

c_{ref} = Reference propagation velocity in m/s / Referenz-Ausbreitungsgeschwindigkeit in m/s

ϵ_{ref} = Reference permittivity in As/Vm / Referenz-Permittivität in As/Vm

E_{ref} = Reference electric field strength in V/m / Elektrische Referenz-Feldstärke in V/m

$$\Delta t = \Delta t_{\text{ref}} \hat{\Delta t} \quad \Delta t_{\text{ref}} = \frac{\Delta x_{\text{ref}}}{c_{\text{ref}}}$$

$$\Delta z = \Delta x_{\text{ref}} \hat{\Delta z}$$

$$c = c_{\text{ref}} \hat{c}$$

$$\epsilon = \epsilon_{\text{ref}} \hat{\epsilon}$$

$$\mu = \mu_{\text{ref}} \hat{\mu}$$

$$\mu_{\text{ref}} = c_{\text{ref}}^2 \epsilon_{\text{ref}}$$

$$E_x = E_{\text{ref}} \hat{E}_x$$

$$J_{\text{ex}} = J_{\text{e ref}} \hat{J}_{\text{ex}} \quad J_{\text{e ref}} = \frac{\epsilon_{\text{ref}}}{\Delta t_{\text{ref}}} E_{\text{ref}}$$

FD Method – Normalization / FD-Methode – Normierung

$$E_x^{(n_z, n_t+1)} = 2E_x^{(n_z, n_t)} - E_x^{(n_z, n_t-1)} + c_0^2 \frac{(\Delta t)^2}{(\Delta z)^2} \left[E_x^{(n_z+1, n_t)} - 2E_x^{(n_z, n_t)} + E_x^{(n_z-1, n_t)} \right] + c_0^2 \mu_0 \Delta t J_{e \text{ ref}} \left[\hat{J}_{\text{ex}}^{(n_z, n_t)} - \hat{J}_{\text{ex}}^{(n_z, n_t-1)} \right]$$

With / Mit

$$\begin{aligned} \Delta z &= \Delta x_{\text{ref}} \\ c_{\text{ref}} &= c_0 = \frac{1}{\sqrt{\epsilon_0 \mu_0}} \\ \epsilon_{\text{ref}} &= \epsilon_0 \\ E_{\text{ref}} &= 1 \text{ V/m} \end{aligned}$$

$$\begin{aligned} c_0^2 \frac{(\Delta t)^2}{(\Delta z)^2} &= c_{\text{ref}}^2 \frac{(\Delta t)^2 (\Delta t_{\text{ref}})^2}{(\Delta x_{\text{ref}})^2} \\ &= c_{\text{ref}}^2 \frac{(\hat{\Delta t})^2 \left(\frac{\Delta x_{\text{ref}}}{c_{\text{ref}}} \right)^2}{(\Delta x_{\text{ref}})^2} \\ &= (\hat{\Delta t})^2 \end{aligned}$$

$$\begin{aligned} c_0^2 \mu_0 \Delta t J_{e \text{ ref}} &= c_{\text{ref}}^2 \mu_{\text{ref}} \hat{\Delta t} \Delta t_{\text{ref}} \frac{\epsilon_{\text{ref}}}{\Delta t_{\text{ref}}} E_{\text{ref}} \\ &= \hat{\Delta t} \end{aligned}$$

$$\hat{E}_x^{(n_z, n_t+1)} = 2\hat{E}_x^{(n_z, n_t)} - \hat{E}_x^{(n_z, n_t-1)} + (\hat{\Delta t})^2 \left[\hat{E}_x^{(n_z+1, n_t)} - 2\hat{E}_x^{(n_z, n_t)} + \hat{E}_x^{(n_z-1, n_t)} \right] + \hat{\Delta t} \left[\hat{J}_{\text{ex}}^{(n_z, n_t)} - \hat{J}_{\text{ex}}^{(n_z, n_t-1)} \right]$$

FD Solution of the 1-D Wave Equation / FD-Lösung der 1D Wellengleichung

1-D wave equation / 1D Wellengleichung

$$\frac{\partial^2}{\partial z^2} E_x(z,t) - \frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} E_x(z,t) = \mu_0 \frac{\partial}{\partial t} J_{\text{ex}}(z,t) \quad \text{for / für} \quad \begin{cases} 0 \leq z \leq Z \\ 0 \leq t \leq T \end{cases}$$

Initial condition / Anfangsbedingung

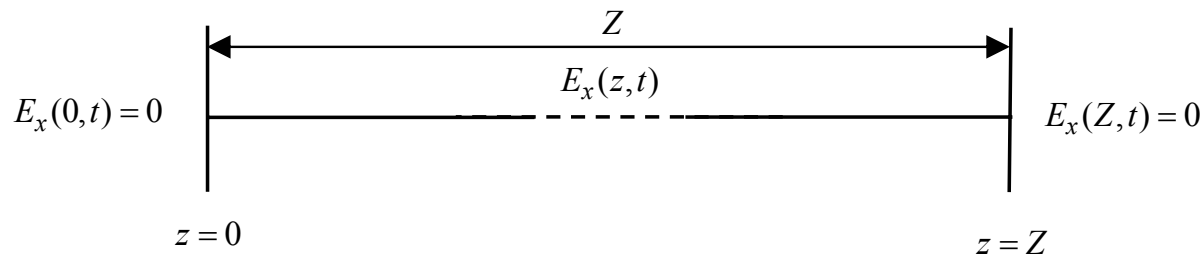
$$\begin{cases} E_x(z,t) = J_{\text{ex}}(z,t) = 0 & t \leq 0 \\ J_{\text{ex}}(z,t) = K_{e0}(z_0) \delta(z_0) f(t) & t > 0 \end{cases}$$

Causality / Kausalität

**Boundary condition for a perfectly electrically conducting (PEC) material /
Randbedingung für ein ideal elektrisch leitendes (IEL) Material**

$$\begin{cases} E_x(0,t) = 0 \\ E_x(Z,t) = 0 \end{cases} \quad \forall t$$

**Hyperbolic initial-
boundary-value problem
/
Hyperbolisches
Anfangs-Randwert-
Problem**



FD Solution of the 1-D Wave Equation / FD-Lösung der 1D Wellengleichung

Normalized 1-D FD wave equation / Normierte 1D FD Wellengleichung

$$\hat{E}_x^{(n_z, n_t+1)} = 2\hat{E}_x^{(n_z, n_t)} - \hat{E}_x^{(n_z, n_t-1)} + (\hat{\Delta t})^2 \left[\hat{E}_x^{(n_z+1, n_t)} - 2\hat{E}_x^{(n_z, n_t)} + \hat{E}_x^{(n_z-1, n_t)} \right] \quad \text{for / für } \begin{cases} 1 \leq n_z \leq N_z \\ 1 \leq n_t \leq N_t \end{cases}$$

$$+ \hat{\Delta t} \left[\hat{J}_{\text{ex}}^{(n_z, n_t)} - \hat{J}_{\text{ex}}^{(n_z, n_t-1)} \right]$$

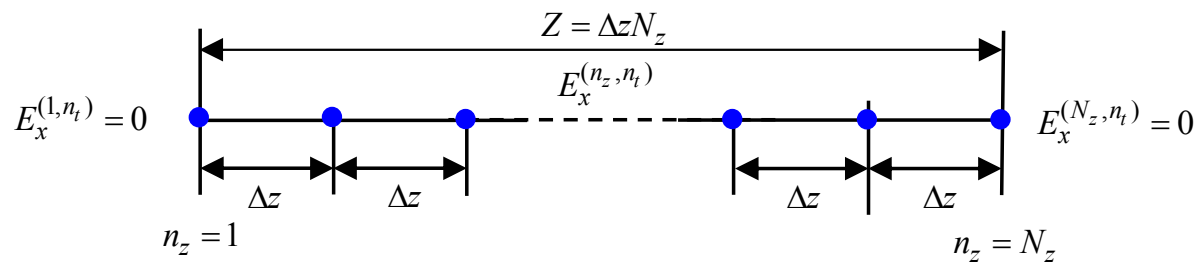
Initial condition (IC) / Anfangsbedingung (AC)

$$\begin{cases} E_x^{(n_z, n_t)} = J_{\text{ex}}^{(n_z, n_t)} = 0 & n_t \leq 1 \\ J_{\text{ex}}^{(n_z, n_t)} = K_{\text{ex}}^{(n_{z0})} \delta^{(n_{z0})} f^{(n_t)} & n_t > 1 \end{cases}$$

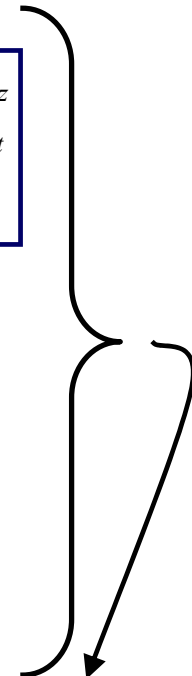
Causality / Kausalität

Boundary condition (BC) / Randbedingung (RB)

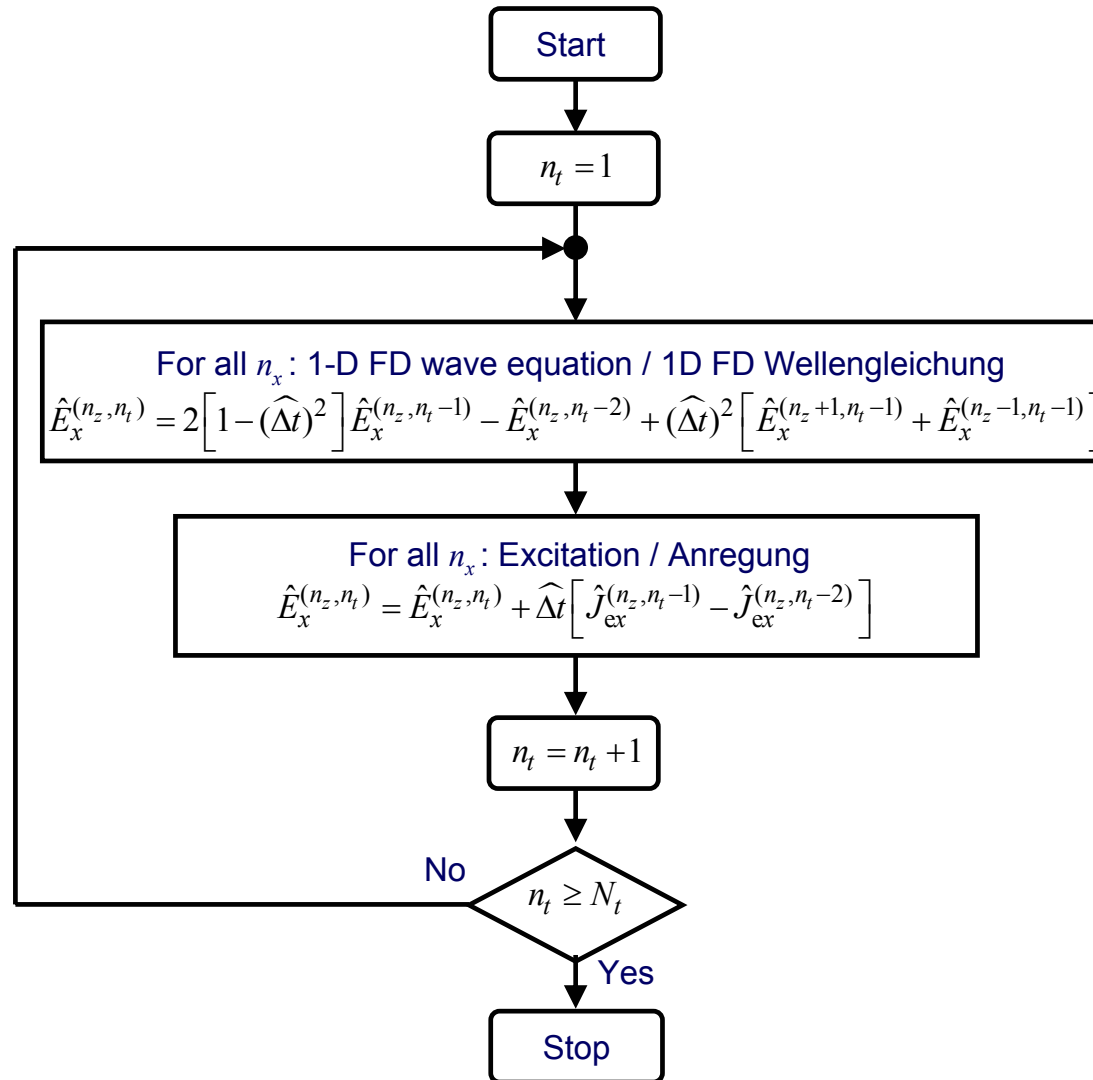
$$\begin{cases} E_x^{(1, n_t)} = 0 \\ E_x^{(N_z, n_t)} = 0 \end{cases} \quad 1 \leq n_t \leq N_t$$



**Discrete hyperbolic
initial-boundary value
problem /
Diskretes
hyperbolisches
Anfangs-Randwert-
Problem**



FD Method – 1D FD Wave Equation – Flow Chart / FD-Methode – 1D FD-Wellengleichung - Flussdiagramm



FD Method – 1D Wave Equation – Poynting Vector – Energy Flow Density / FD-Methode – 1D Wellengleichung – Poynting-Vektor – Energieflussdichte

$$\underline{S}_{\text{em}}(\mathbf{R}, t) = \underline{E}(\mathbf{R}, t) \times \underline{H}(\mathbf{R}, t)$$

$$S_{\text{em}z}(z, t) = E_x(z, t) H_y(z, t)$$

$$\frac{\partial}{\partial t} H_y(z, t) = -\frac{1}{\mu_0} \frac{\partial}{\partial z} E_x(z, t)$$

$$H_y(z, t) = \underbrace{-\frac{1}{\mu_0} \frac{\partial}{\partial z} E_x(z, t_0)}_{=H_y(z, t_0)} - \frac{1}{\mu_0} \int_{t'=t_0}^t \frac{\partial}{\partial z} E_x(z, t') dt'$$

$$= H_y(z, t_0) - \frac{1}{\mu_0} \int_{t'=t_0}^t \frac{\partial}{\partial z} E_x(z, t') dt'$$

$$H_y(z, t) = H_y(z, t_0) - \frac{1}{\mu_0} \int_{t'=t_0}^{t_0+\Delta t} \frac{\partial}{\partial z} E_x(z, t') dt'$$

$$= H_y(z, t_0) - \frac{1}{\mu_0} \frac{\partial}{\partial z} E_x\left(z, t_0 + \frac{\Delta t}{2}\right) \underbrace{\int_{t'=t_0}^{t_0+\Delta t} dt'}_{=\Delta t}$$

$$\approx H_y(z, t_0) - \frac{\Delta t}{\mu_0} \underbrace{\frac{\partial}{\partial z} E_x\left(z, t_0 + \frac{\Delta t}{2}\right)}_{=\frac{1}{2\Delta z} \left[E_x\left(z+\Delta z, t_0 + \frac{\Delta t}{2}\right) - E_x\left(z-\Delta z, t_0 + \frac{\Delta t}{2}\right) \right]}$$

**Applying the mid-point rule /
Wende die Mittelpunktsregel an**

FD Method – 1D Wave Equation – Poynting Vector – Energy Density Flow / FD-Methode – 1D Wellengleichung – Poynting-Vektor – Energiedichtefluss

$$H_y(z, t) \approx H_y(z, t_0) - \frac{1}{2} \frac{1}{\mu_0} \frac{\Delta t}{\Delta z} \left[E_x \left(z + \Delta z, t_0 + \frac{\Delta t}{2} \right) - E_x \left(z - \Delta z, t_0 - \frac{\Delta t}{2} \right) \right]$$

$\Delta z = \Delta x_{\text{ref}}$ $c_{\text{ref}} = c_0 = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$ $\epsilon_{\text{ref}} = \epsilon_0$ $E_{\text{ref}} = 1 \text{ V/m}$	$\Delta t = \Delta t_{\text{ref}} \hat{\Delta t} \quad \Delta t_{\text{ref}} = \frac{\Delta z}{c_0}$ $c = c_0 \hat{c}$ $\mu = \mu_{\text{ref}} \hat{\mu} \quad \mu_{\text{ref}} = \mu_0$ $E_x = E_{\text{ref}} \hat{E}_x$ $H_y = H_{\text{ref}} \hat{H}_y \quad H_{\text{ref}} = \frac{E_{\text{ref}}}{c_{\text{ref}} \mu_{\text{ref}}} = \frac{\sqrt{\epsilon_{\text{ref}} \mu_{\text{ref}}}}{\mu_{\text{ref}}} E_{\text{ref}} = \sqrt{\frac{\epsilon_{\text{ref}}}{\mu_{\text{ref}}}} E_{\text{ref}} = \frac{E_{\text{ref}}}{Z_{\text{ref}}}$ $S_{\text{em } z} = S_{\text{em ref}} \hat{S}_{\text{em } z} \quad S_{\text{em ref}} = E_{\text{ref}} H_{\text{ref}} = \frac{E_{\text{ref}}^2}{Z_{\text{ref}}}$
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$$\sqrt{\frac{\epsilon_{\text{ref}}}{\mu_{\text{ref}}}} E_{\text{ref}} H_y(z, t) \approx \sqrt{\frac{\epsilon_{\text{ref}}}{\mu_{\text{ref}}}} E_{\text{ref}} H_y(z, t_0) - \frac{1}{2} \frac{1}{\mu_{\text{ref}}} \frac{\hat{\Delta t}}{\Delta z} \frac{\Delta z}{c_{\text{ref}}} E_{\text{ref}} \left[\hat{E}_x \left(z + \Delta z, t_0 + \frac{\Delta t}{2} \right) - \hat{E}_x \left(z - \Delta z, t_0 - \frac{\Delta t}{2} \right) \right]$$

$$H_y(z, t) \approx H_y(z, t_0) - \frac{1}{2} \sqrt{\frac{\mu_{\text{ref}}}{\epsilon_{\text{ref}}}} \frac{1}{E_{\text{ref}}} \frac{1}{\mu_{\text{ref}}} \frac{\hat{\Delta t}}{\Delta z} \frac{\Delta z}{c_{\text{ref}}} E_{\text{ref}} \left[\hat{E}_x \left(z + \Delta z, t_0 + \frac{\Delta t}{2} \right) - \hat{E}_x \left(z - \Delta z, t_0 - \frac{\Delta t}{2} \right) \right]$$

$$H_y(z, t) \approx H_y(z, t_0) - \frac{\hat{\Delta t}}{2} \frac{1}{\sqrt{\epsilon_{\text{ref}} \mu_{\text{ref}}}} \frac{1}{c_{\text{ref}}} \left[\hat{E}_x \left(z + \Delta z, t_0 + \frac{\Delta t}{2} \right) - \hat{E}_x \left(z - \Delta z, t_0 - \frac{\Delta t}{2} \right) \right]$$

FD Method – 1D Wave Equation – Poynting Vector – Energy Density Flow / FD-Methode – 1D Wellengleichung – Poynting-Vektor – Energiedichtefluss

$$\hat{H}_y(z, t) \approx \hat{H}_y(z, t_0) - \frac{\hat{\Delta}t}{2} \frac{1}{\sqrt{\epsilon_{\text{ref}} \mu_{\text{ref}}}} \frac{1}{c_{\text{ref}}} \left[\hat{E}_x \left(z + \Delta z, t_0 + \frac{\Delta t}{2} \right) - \hat{E}_x \left(z - \Delta z, t_0 + \frac{\Delta t}{2} \right) \right]$$

$$\hat{H}_y(z, t) \approx \hat{H}_y(z, t_0) - \frac{\hat{\Delta}t}{2} \left[\hat{E}_x \left(z + \Delta z, t_0 + \frac{\Delta t}{2} \right) - \hat{E}_x \left(z - \Delta z, t_0 + \frac{\Delta t}{2} \right) \right]$$

$$\hat{H}_y^{(n_z, n_t)} = \hat{H}_y^{(n_z, n_t-1)} - \frac{\hat{\Delta}t}{2} \left[\hat{E}_x^{(n_z+1, n_t)} - \hat{E}_x^{(n_z-1, n_t)} \right]$$

$$\underline{\mathbf{S}}_{\text{em}}(\mathbf{R}, t) = \underline{\mathbf{E}}(\mathbf{R}, t) \times \underline{\mathbf{H}}(\mathbf{R}, t)$$

$$S_{\text{em}z}(z, t) = E_x(z, t) H_y(z, t)$$

$$\hat{S}_{\text{em}z}^{(n_z, n_t)} = \hat{H}_y^{(n_z, n_t)} \hat{E}_x^{(n_z, n_t)}$$

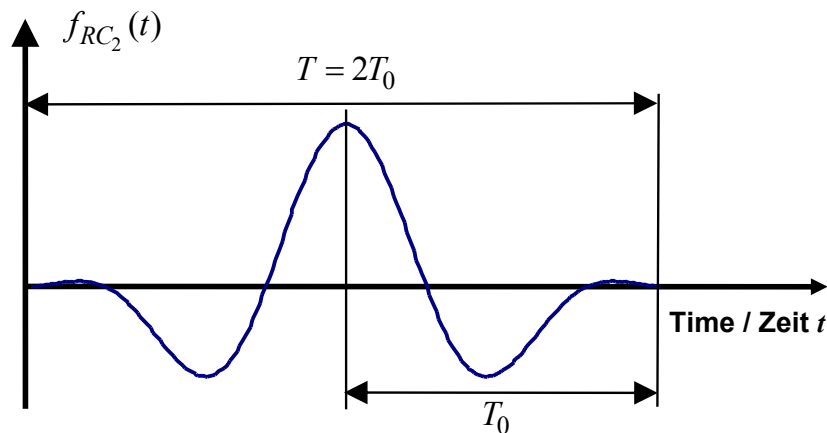
FD Method – 1D Wave Equation – Example / FD-Methode – 1D Wellengleichung – Beispiel

**Raised cosine pulse with n cycles /
Aufsteigender Kosinus-Impuls mit n Zyklen**

$$f_{RC_n}(t) = \begin{cases} \frac{(-1)^n}{2} \left[1 - \cos\left(\frac{2\pi f_0}{n} t\right) \right] \cos(2\pi f_0 t) & 0 < t < \frac{n}{f_0} = nT_0 = T \\ 0 & \text{else / sonst} \end{cases}$$

**Raised cosine pulse with 2 cycles /
Aufsteigender Kosinus-Impuls mit 2 Zyklen**

$$f_{RC_2}(t) = \begin{cases} \frac{1}{2} \left[1 - \cos(\pi f_0 t) \right] \cos(2\pi f_0 t) & 0 < t < \frac{2}{f_0} = 2T_0 = T \\ 0 & \text{else / sonst} \end{cases}$$



Frequency / Frequenz

$$f_0 = \frac{1}{T_0}$$

**Circular Frequency /
Kreisfrequenz**

$$\omega_0 = \frac{2\pi}{T_0}$$

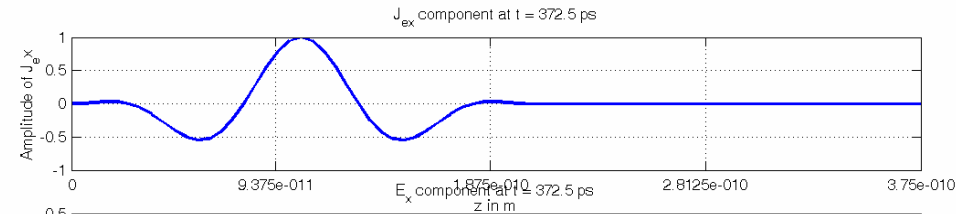
FD Method – 1-D Wave Equation – Example / FD-Methode – 1D Wellengleichung – Beispiel

Electric current density excitation: broadband pulse (RC2 pulse) /
Elektrische Stromdichteanregung: breitbandiger Impuls (RC2-Impuls)

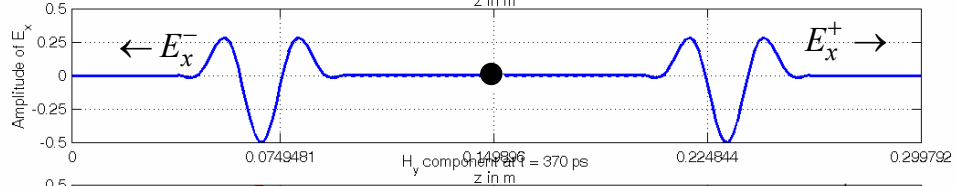
$$J_{ex}(z = z_0, t) \sim f_{RC2}(t) \rightarrow E_x(z, t) \sim f_{RC2} \left[t \mp \frac{z - z_0}{c_0} \right]$$

Snapshots / Schnappschüsse

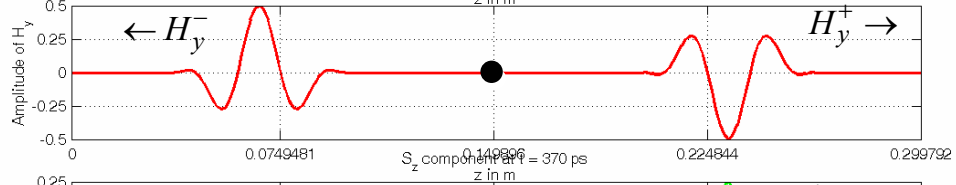
$f_{RC2}(t)$



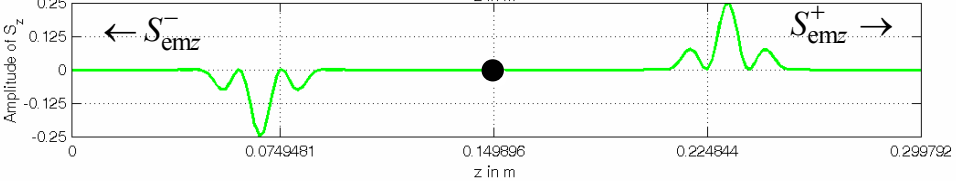
$\hat{E}_x(z, t_1)$



$\hat{H}_y(z, t_1)$



$\hat{S}_{emz}(z, t_1)$



● Source point / Quellpunkt

**Numerical Results – Validation /
Numerische Ergebnisse – Validierung**

Numerical Results / Numerische Ergebnisse



Validation / Validierung

Compare numerical results with analytical solutions or with other numerical solutions. / Vergleiche die numerischen Ergebnisse mit analytischen Lösungen oder anderen numerischen Lösungen

**End of Lecture 2 /
Ende der 2. Vorlesung**