

**Numerical Methods of  
Electromagnetic Field Theory I (NFT I)  
Numerische Methoden der  
Elektromagnetischen Feldtheorie I (NFT I) /**

**6th Lecture / 6. Vorlesung**

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# FDTD and FIT / FDTD und FIT

**FDTD** : Finite Difference Time Domain / Finite Differenzen im Zeitbereich  
**FIT** : Finite Integration Technique / Finite Integrationstechnik

## FDTD

Maxwell's equations in differential form /  
 Maxwell'sche Gleichungen in Differentialform

$$\frac{\partial}{\partial t} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) = -\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) - \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t)$$

$$\frac{\partial}{\partial t} \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) = \nabla \times \underline{\mathbf{H}}(\underline{\mathbf{R}}, t) - \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t)$$

$$\nabla \cdot \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) = \rho_e(\underline{\mathbf{R}}, t)$$

$$\nabla \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) = \rho_m(\underline{\mathbf{R}}, t)$$

 FD approximation of spatial and temporal derivatives / FD-Approximation von räumlichen und zeitlichen Ableitungen

Central difference approximation /  
 Zentrale Differenzen Approximation

$$\left. \frac{\partial}{\partial z} f(z, t) \right|_{z=z_0} \approx \frac{f\left(z_0 + \frac{\Delta z}{2}, t\right) - f\left(z_0 - \frac{\Delta z}{2}, t\right)}{\Delta z}$$

## FIT

Maxwell's equations in integral form /  
 Maxwell'sche Gleichungen in Integralform

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}} = -\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}} - \iint_S \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}$$

$$\frac{d}{dt} \iint_S \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}} = \oint_{C=\partial S} \underline{\mathbf{H}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}} - \iint_S \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}$$

$$\oint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}} = \iiint_V \rho_e(\underline{\mathbf{R}}, t) dV$$

$$\oint_{S=\partial V} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}} = \iiint_V \rho_m(\underline{\mathbf{R}}, t) dV$$

 FIT approximation of spatial and temporal integrals / FIT-Approximation von räumlichen und zeitlichen Integralen

Mid point rule approximation of a 1-D integral /  
 Mittelpunktsregel-Approximation eines 1D-Integrals

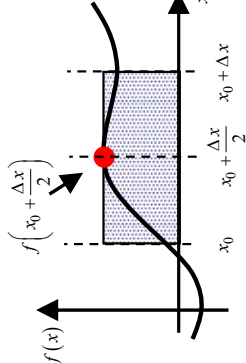
$$\int_{z=z_0}^{z_0+\Delta z} f(z, t) dz \approx f\left(z_0 + \frac{\Delta z}{2}, t\right) \Delta z$$

## FIT Approximations Based on the Mid Point Rule in 1-D, 2-D, and 3-D / FIT-Approximationen basierend auf der Mittelpunktsregel in 1D, 2D und 3D

Cartesian coordinate system; homogeneous dual-orthogonal grid system with rectangular grid cells /  
Kartesisches Koordinatensystem; homogenes dual-orthogonales Gittersystem mit rechteckförmigen  
**Gitterzellen**

**1-D:**

$$\int_{x=x_0}^{x_0+\Delta x} f(x) dx = f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x + O\left[(\Delta x)^3\right]$$

$$\approx f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x$$


**2-D:**

$$\int_{y=y_0}^{y_0+\Delta y} \int_{x=x_0}^{x_0+\Delta x} f(x, y) dx dy = f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta y}{2}\right) \Delta x \Delta y + O\left[(\Delta x)^3 \Delta y + \Delta x (\Delta y)^3\right]$$

$$\approx f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta y}{2}\right) \Delta x \Delta y$$

**3-D:**

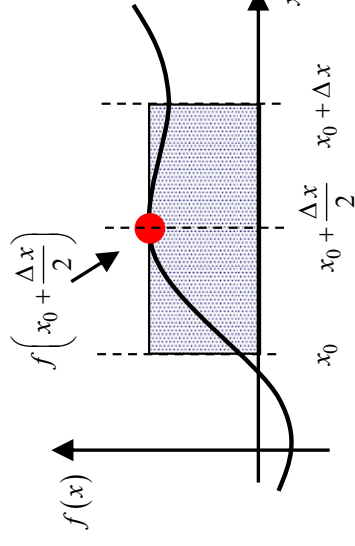
$$\int_{z=z_0}^{z_0+\Delta z} \int_{y=y_0}^{y_0+\Delta y} \int_{x=x_0}^{x_0+\Delta x} f(x, y, z) dx dy dz = f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta y}{2}, z_0 + \frac{\Delta z}{2}\right) \Delta x \Delta y \Delta z$$

$$+ O\left[(\Delta x)^3 \Delta y \Delta z + \Delta x (\Delta y)^3 \Delta z + \Delta x \Delta y (\Delta z)^3\right]$$

$$\approx f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta y}{2}, z_0 + \frac{\Delta z}{2}\right) \Delta x \Delta y \Delta z$$

## FIT Approximation of a 1-D Integral Based on the Mid Point Rule / FIT-Approximation eines 1D-Integrals basierend auf der Mittelpunktsregel

Cartesian coordinate system; homogeneous dual-orthogonal grid system with rectangular grid cells /  
Kartesisches Koordinatensystem; homogenes dual-orthogonales Gittersystem mit rechteckförmigen Gitterzellen



$$\int_{x=x_0}^{x_0+\Delta x} f(x) dx = f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x + O\left[(\Delta x)^3\right]$$

$$\approx f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x$$

**Taylor series are expansions of a function  $f(x)$  in a finite distance  $\Delta x: f(x+\Delta x/2)$  /  
Taylor-Reihen sind Entwicklungen einer Funktion  $f(x)$  in einer endlichen Distanz  $\Delta x: f(x+\Delta x/2)$**

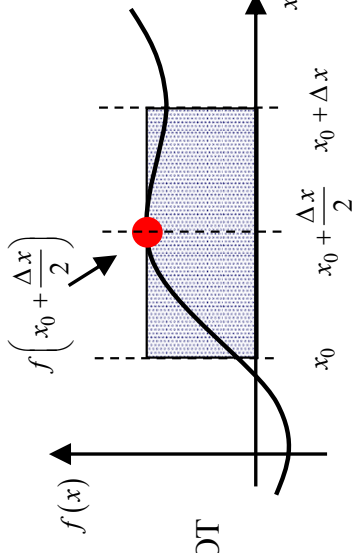
$$f(x \pm \Delta x) = \sum_{n=0}^{\infty} \frac{1}{n!} (\pm \Delta x)^n \frac{d^n}{dx^n} f(x)$$

$$f(x) = \sum_{n=0}^{\infty} \frac{1}{n!} \left( \frac{d}{dx} \right)^n f(x) \Big|_{x=x_1} (x - x_1)^n$$

## FIT Approximation of a 1-D Integral Based on the Mid Point Rule / FIT-Approximation eines 1D-Integrals basierend auf der Mittelpunktsregel

$$f(x) = \sum_{n=0}^{\infty} \frac{1}{n!} \left( \frac{d}{dx} \right)^n f(x) \Big|_{x=x_1} (x-x_1)^n$$

$$= f(x) \Big|_{x=x_1} + \frac{d}{dx} f(x) \Big|_{x=x_1} (x-x_1) + \frac{1}{2!} \frac{d^2}{dx^2} f(x) \Big|_{x=x_1} (x-x_1)^2 + \text{HOT}$$



$$x_1 = x_0 + \frac{\Delta x}{2}$$

$$f(x) = f\left(x_0 - \frac{\Delta x}{2}\right) + \underbrace{\frac{d}{dx} f(x) \Big|_{x=x_0 - \frac{\Delta x}{2}}}_{=f^{(1x)}\left(x_0 - \frac{\Delta x}{2}\right)} \left[ x - \left(x_0 - \frac{\Delta x}{2}\right) \right] + \frac{1}{2!} \frac{d^2}{dx^2} f(x) \Big|_{x=x_0 - \frac{\Delta x}{2}} \left[ x - \left(x_0 - \frac{\Delta x}{2}\right) \right]^2 + \text{HOT}$$

$$= f\left(x_0 + \frac{\Delta x}{2}\right) + f^{(1x)}\left(x_0 + \frac{\Delta x}{2}\right) \left[ x - \left(x_0 + \frac{\Delta x}{2}\right) \right] + \frac{1}{2!} f^{(2x)}\left(x_0 + \frac{\Delta x}{2}\right) \left[ x - \left(x_0 + \frac{\Delta x}{2}\right) \right]^2 + \text{HOT}$$

**FIT Approximation of a 1-D Integral Based on the Mid Point Rule /  
FIT-Approximation eines 1D-Integrals basierend auf der Mittelpunktsregel**

$$\begin{aligned}
 f(x) &= f\left(x_0 + \frac{\Delta x}{2}\right) + f^{(x)}\left(x_0 + \frac{\Delta x}{2}\right)\left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right] + \frac{1}{2!}f^{(xx)}\left(x_0 + \frac{\Delta x}{2}\right)\left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right]^2 + \text{HOT} \\
 \int_{x=x_0}^{x_0+\Delta x} f(x) \, dx &= \int_{x=x_0}^{x_0+\Delta x} \left\{ f\left(x_0 + \frac{\Delta x}{2}\right) + f^{(x)}\left(x_0 + \frac{\Delta x}{2}\right)\left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right] + \frac{1}{2!}f^{(xx)}\left(x_0 + \frac{\Delta x}{2}\right)\left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right]^2 + \text{HOT} \right\} dx \\
 &= \underbrace{\int_{x=x_0}^{x_0+\Delta x} f\left(x_0 + \frac{\Delta x}{2}\right) dx}_{f\left(x_0 + \frac{\Delta x}{2}\right) \int_{x=x_0}^{x_0+\Delta x} dx} + \underbrace{\int_{x=x_0}^{x_0+\Delta x} f^{(x)}\left(x_0 + \frac{\Delta x}{2}\right)\left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right] dx}_{=f^{(x)}\left(x_0 + \frac{\Delta x}{2}\right) \int_{x=x_0}^{x_0+\Delta x} \left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right] dx} \\
 &\quad + \underbrace{\int_{x=x_0}^{x_0+\Delta x} \frac{1}{2!}f^{(xx)}\left(x_0 + \frac{\Delta x}{2}\right)\left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right]^2 dx}_{= \frac{1}{2}f^{(xx)}\left(x_0 + \frac{\Delta x}{2}\right) \int_{x=x_0}^{x_0+\Delta x} \left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right]^2 dx} + \text{HOT}
 \end{aligned}$$

**FIT Approximation of a 1-D Integral Based on the Mid Point Rule /  
FIT-Approximation eines 1D-Integrals basierend auf der Mittelpunktsregel**

$$\begin{aligned}
 \int_{x=x_0}^{x_0+\Delta x} f(x) dx &= f\left(x_0 + \frac{\Delta x}{2}\right) \underbrace{\int_{x=x_0}^{x_0+\Delta x} dx}_{=\Delta x} \\
 &+ f^{(x)}\left(x_0 + \frac{\Delta x}{2}\right) \underbrace{\int_{x=x_0}^{x_0+\Delta x} \left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right] dx}_{=0} \\
 &+ \frac{1}{2} f^{(xx)}\left(x_0 + \frac{\Delta x}{2}\right) \underbrace{\int_{x=x_0}^{x_0+\Delta x} \left[x - \left(x_0 + \frac{\Delta x}{2}\right)\right]^2 dx}_{=\frac{1}{12}(\Delta x)^3} + \text{HOT} \\
 &= f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x + \frac{1}{24} f^{(xx)}\left(x_0 + \frac{\Delta x}{2}\right) (\Delta x)^3 + \text{HOT} \\
 &= f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x + \mathcal{O}\left[(\Delta x)^3\right]
 \end{aligned}$$

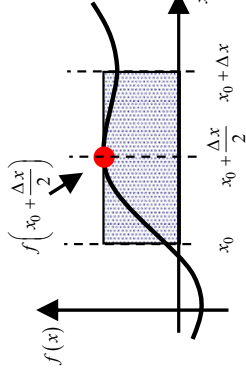
## FIT Approximations Based on the Mid Point Rule in 1-D, 2-D, and 3-D / FIT-Approximationen basierend auf der Mittelpunktsregel in 1D, 2D und 3D

Cartesian coordinate system; homogeneous dual-orthogonal grid system with **cubic grid cells** /  
Kartesisches Koordinatensystem; homogenes dual-orthogonales Gittersystem mit **kubischen Gitterzellen**

**1-D:**

$$\int_{x_0}^{x_0+\Delta x} f(x) dx = f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x + O\left[(\Delta x)^3\right]$$

$$\approx f\left(x_0 + \frac{\Delta x}{2}\right) \Delta x$$



**2-D:**

$$\int_{y_0}^{y_0+\Delta x} \int_{x_0}^{x_0+\Delta x} f(x, y) dx dy = f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta x}{2}\right) (\Delta x)^2 + O\left[(\Delta x)^4\right]$$

$$\approx f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta x}{2}\right) (\Delta x)^2$$

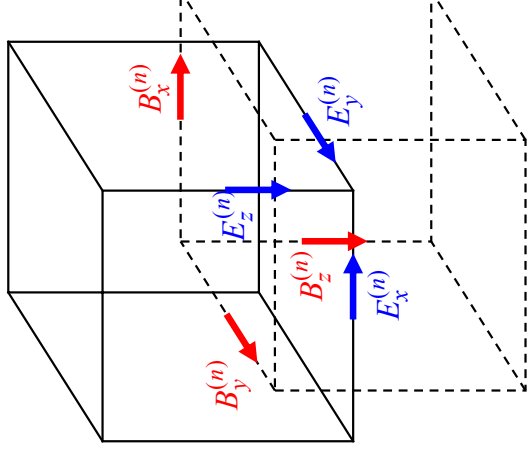
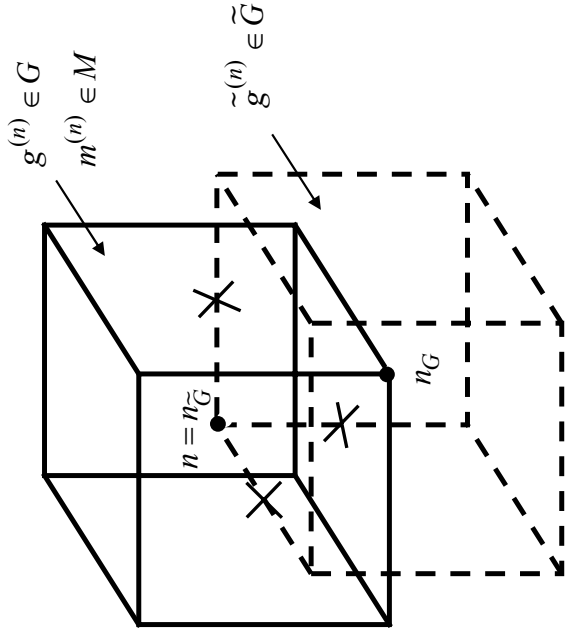
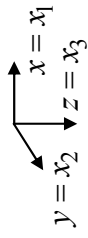
**3-D:**

$$\int_{z_0}^{z_0+\Delta x} \int_{y_0}^{y_0+\Delta x} \int_{x_0}^{x_0+\Delta x} f(x, y, z) dx dy dz = f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta x}{2}, z_0 + \frac{\Delta x}{2}\right) (\Delta x)^3 + O\left[(\Delta x)^5\right]$$

$$\approx f\left(x_0 + \frac{\Delta x}{2}, y_0 + \frac{\Delta x}{2}, z_0 + \frac{\Delta x}{2}\right) (\Delta x)^3$$

# Dual-Orthogonal Grid System in Space / Dual-orthogonales Gittersystem im Raum

3-D / 3D



Global node numbering / Globale Gitternummerierung

$$n = 1 + M_x (n_x - 1) + M_y (n_y - 1) + M_z (n_z - 1)$$

$$n = 1, 2, \dots, N = N_x N_y N_z$$

$$M_x = 1$$

$$M_y = N_x$$

$$M_z = N_x N_y$$

Primary grid / Primäres Gitter	$G \perp \tilde{G}$	Secondary (dual) grid Sekundäres (duales) Gitter
Primary grid / Primäres Gitter	$G = M$	Material grid Materialgitter

## FIT – 3-D Electromagnetic Wave Propagation / FIT – 3D elektromagnetische Wellenausbreitung

**Continuous spatial and temporal space /  
Kontinuierlicher räumlicher und zeitlicher Raum**

Maxwell's equations in integral form /  
Maxwell'sche Gleichungen in Integralform

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_S \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$$\frac{d}{dt} \iint_S \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = \oint_{C=\partial S} \underline{\mathbf{H}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_S \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = \iiint_V \rho_e(\underline{\mathbf{R}}, t) dV$$

$$\oiint_{S=\partial V} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = \iiint_V \rho_m(\underline{\mathbf{R}}, t) dV$$

Continuity equations in integral form /  
Kontinuitätsgleichungen in Integralform

$$\iint_S \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \frac{d}{dt} \iiint_V \rho_m(\underline{\mathbf{R}}, t) dV$$

$$\iint_S \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \frac{d}{dt} \iiint_V \rho_e(\underline{\mathbf{R}}, t) dV$$

**Discrete spatial and temporal space /  
Diskreter räumlicher und zeitlicher Raum**

Maxwell's grid equations /  
Maxwell'sche Gittergleichungen

$$[\mathbf{S}] \frac{d}{dt} \{\mathbf{B}\}(t) = - [\mathbf{curl}] [\mathbf{R}] \{\mathbf{E}\}(t) - [\mathbf{S}] \{\mathbf{J}_m\}(t)$$

$$[\widetilde{\mathbf{S}}] \frac{d}{dt} \{\mathbf{D}\}(t) = [\widetilde{\mathbf{curl}}] [\widetilde{\mathbf{R}}] \{\mathbf{H}\}(t) - [\widetilde{\mathbf{S}}] \{\mathbf{J}_e\}(t)$$

$$[\mathbf{S}] [\mathbf{div}] \{\mathbf{B}\}(t) = [\mathbf{V}] \{\rho_m\}(t)$$

$$[\widetilde{\mathbf{S}}] [\widetilde{\mathbf{div}}] \{\mathbf{D}\}(t) = [\widetilde{\mathbf{V}}] \{\rho_e\}(t)$$

Continuity grid equations / Kontinuitätsgittergleichungen

$$[\mathbf{S}] [\mathbf{div}] \{\mathbf{J}_m\}(t) = - [\mathbf{V}] \frac{d}{dt} \{\rho_m\}(t)$$

$$[\widetilde{\mathbf{S}}] [\widetilde{\mathbf{div}}] \{\mathbf{J}_e\}(t) = - [\widetilde{\mathbf{V}}] \frac{d}{dt} \{\rho_e\}(t)$$

# FIT Formulation / FIT-Formulierung

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_{S_m} \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$$\frac{d}{dt} \iint_S \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = \oint_{C=\partial S} \underline{\mathbf{H}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_{S_e} \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = \iiint_V \rho_e(\underline{\mathbf{R}}, t) dV$$

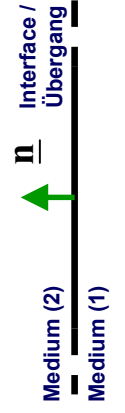
$$\oiint_{S=\partial V} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = \iiint_V \rho_m(\underline{\mathbf{R}}, t) dV$$

$\underline{\mathbf{E}}(\underline{\mathbf{R}}, t), \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)$   
 $\underline{\mathbf{E}}(\underline{\mathbf{R}}, t), \underline{\mathbf{H}}(\underline{\mathbf{R}}, t)$   
 $\underline{\mathbf{D}}(\underline{\mathbf{R}}, t), \underline{\mathbf{H}}(\underline{\mathbf{R}}, t)$   
 $\underline{\mathbf{D}}(\underline{\mathbf{R}}, t), \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)$

Which field quantities should we use in our formulation / Welche Feldgrößen sollten wir in unserer FIT-Formulierung verwenden ?



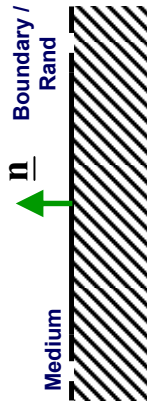
Transition conditions for a source-free interface /  
Übergangsbedingungen für einen quellenfreien Übergang



$$\underline{\mathbf{n}} \times [\underline{\mathbf{E}}^{(2)}(\underline{\mathbf{R}}, t) - \underline{\mathbf{E}}^{(1)}(\underline{\mathbf{R}}, t)] = \underline{\mathbf{0}} \rightarrow E_t^{(2)}(\underline{\mathbf{R}}, t) = E_t^{(1)}(\underline{\mathbf{R}}, t) \quad \underline{\mathbf{R}} \in \text{Interface} / \text{Übergang}$$

$$\underline{\mathbf{n}} \cdot [\underline{\mathbf{B}}^{(2)}(\underline{\mathbf{R}}, t) - \underline{\mathbf{B}}^{(1)}(\underline{\mathbf{R}}, t)] = 0 \rightarrow B_n^{(2)}(\underline{\mathbf{R}}, t) = B_n^{(1)}(\underline{\mathbf{R}}, t) \quad \underline{\mathbf{R}} \in \text{Interface} / \text{Übergang}$$

Boundary conditions for a PEC boundary /  
Randbedingungen für einen IEL-Rand



$$\underline{\mathbf{n}} \times \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) = \underline{\mathbf{0}} \rightarrow E_t(\underline{\mathbf{R}}, t) = 0 \quad \underline{\mathbf{R}} \in \text{Boundary} / \text{Rand}$$

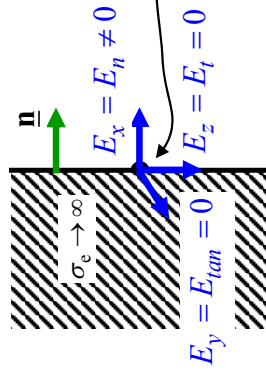
$$\underline{\mathbf{n}} \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) = 0 \rightarrow B_n(\underline{\mathbf{R}}, t) = 0 \quad \underline{\mathbf{R}} \in \text{Boundary} / \text{Rand}$$

# Problems of a Node-Based Formulation – Boundary Conditions / Probleme einer Knotenbasierten Formulierung – Randbedingungen

## Node-Based Grid System / Knotenbasiertes Gittersystem

Perfectly electrically conducting (PEC) material in the  $xz$  plane / Ideal elektrisch leitendes (IEL) Material in der  $xz$ -Ebene

Boundary conditions for perfectly electrically conducting (PEC) material / Randbedingungen für ein ideal elektrisch leitendes (IEL) Material

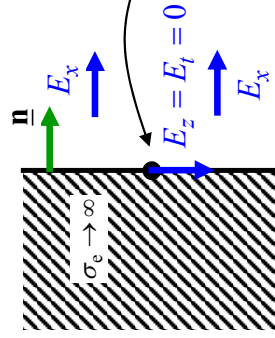


$$\mathbf{n} \times \underline{\mathbf{E}}(\mathbf{R}, t) = \underline{\mathbf{0}} \quad \rightarrow \quad E_{tan}(\mathbf{R}, t) = E_t(\mathbf{R}, t) = 0$$

$$\mathbf{n} \cdot \underline{\mathbf{B}}(\mathbf{R}, t) = 0 \quad \rightarrow \quad B_n(\mathbf{R}, t) = 0$$

Node-based formulation: all vector components are placed at the same one node / Knotenbasierte Formulierung: alle Vektorkomponenten sind an dem selben Knoten platziert

## Staggered Grid System / Versetztes Gittersystem



Only tangential components are allocated at the PEC boundary / Nur Tangentialkomponenten sind am IEL-Rand allokiert

# Problems of a Node-Based Formulation – Boundary Conditions / Probleme einer knotenbasierten Formulierung – Randbedingungen

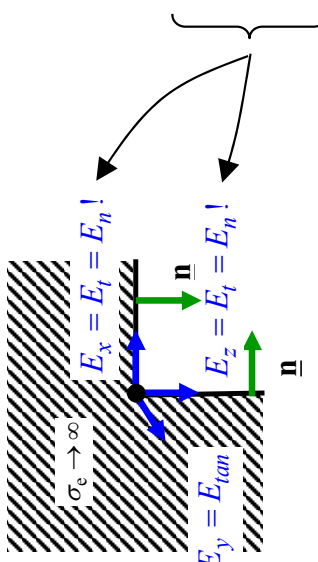
## Node-Based Grid System / Knotenbasiertes Gittersystem

Perfectly electrically conducting (PEC)  
material in the  $xz$  plane /  
Ideal elektrisch leitendes (IEL)  
Material in der  $xz$ -Ebene

Boundary conditions for perfectly  
electrically conducting (PEC) material /  
Randbedingungen für ein ideal  
elektrisch leitendes (IEL) Material

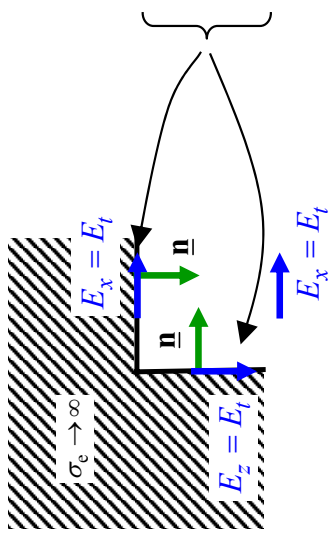
$$\underline{n} \times \underline{E}(\underline{R}, t) = \underline{0} \quad \rightarrow \quad E_{tan}(\underline{R}, t) = E_t(\underline{R}, t) = 0$$

$$\underline{n} \cdot \underline{B}(\underline{R}, t) = 0 \quad \rightarrow \quad B_n(\underline{R}, t) = 0$$



These components are tangential and normal either  
to the vertical or to the horizontal boundary /  
Diese Komponenten sind tangential und normal  
entweder zum vertikalen oder zum horizontalen Rand

## Staggered Grid System / Versetztes Gittersystem



In this case only tangential components are allocated  
at the PEC boundary /  
In diesem Fall sind nur Tangentialkomponenten  
am IEL-Rand allokiert

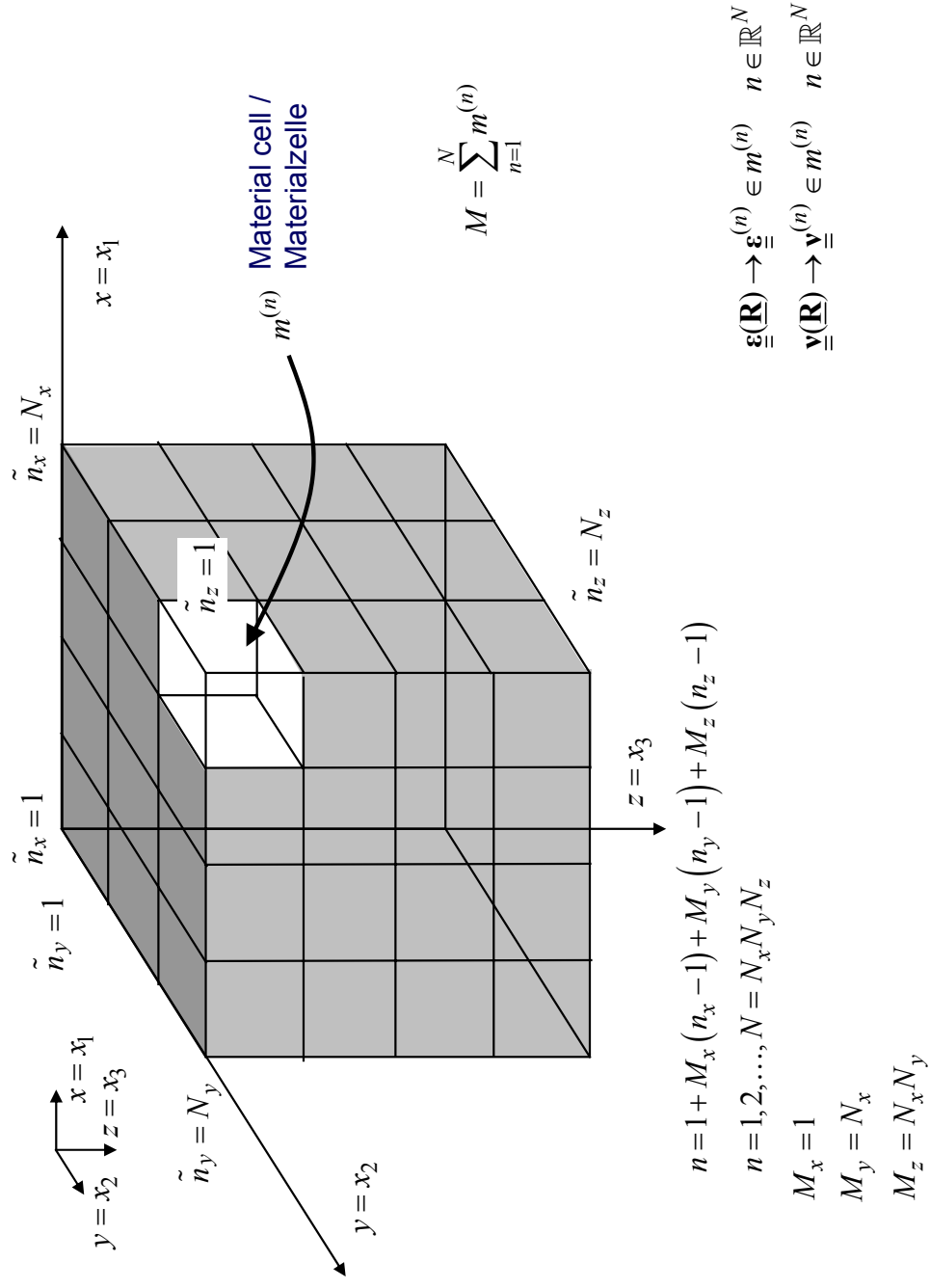


## FIT – 3-D Electromagnetic Wave Propagation / FIT – 3D elektromagnetische Wellenausbreitung

$$\begin{aligned}
 \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) &= \underline{\underline{\boldsymbol{\varepsilon}}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \\
 &= \begin{bmatrix} \varepsilon_{xx}(\underline{\mathbf{R}}) & 0 & 0 \\ 0 & \varepsilon_{yy}(\underline{\mathbf{R}}) & 0 \\ \text{sym} & 0 & \varepsilon_{zz}(\underline{\mathbf{R}}) \end{bmatrix} \cdot \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \\
 &= \left[ \varepsilon_{xx}(\underline{\mathbf{R}}) \underline{\mathbf{e}}_x \underline{\mathbf{e}}_x + \varepsilon_{yy}(\underline{\mathbf{R}}) \underline{\mathbf{e}}_y \underline{\mathbf{e}}_y + \varepsilon_{zz}(\underline{\mathbf{R}}) \underline{\mathbf{e}}_z \underline{\mathbf{e}}_z \right] \cdot \left[ E_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + E_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + E_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z \right] \\
 &= \underbrace{\varepsilon_{xx}(\underline{\mathbf{R}}) E_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + \varepsilon_{yy}(\underline{\mathbf{R}}) E_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + \varepsilon_{zz}(\underline{\mathbf{R}}) E_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z}_{D_x(\underline{\mathbf{R}}, t)} + \underbrace{\phantom{\varepsilon_{xx}(\underline{\mathbf{R}}) E_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + \varepsilon_{yy}(\underline{\mathbf{R}}) E_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + \varepsilon_{zz}(\underline{\mathbf{R}}) E_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z}}_{D_y(\underline{\mathbf{R}}, t)} + \underbrace{\phantom{\varepsilon_{xx}(\underline{\mathbf{R}}) E_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + \varepsilon_{yy}(\underline{\mathbf{R}}) E_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + \varepsilon_{zz}(\underline{\mathbf{R}}) E_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z}}_{D_z(\underline{\mathbf{R}}, t)} \\
 &= D_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + D_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + D_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z
 \end{aligned}$$

$$\begin{aligned}
 \underline{\mathbf{H}}(\underline{\mathbf{R}}, t) &= \underline{\underline{\mathbf{v}}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \\
 &= \begin{bmatrix} v_{xx}(\underline{\mathbf{R}}) & & \\ & v_{yy}(\underline{\mathbf{R}}) & \\ \text{sym} & & v_{zz}(\underline{\mathbf{R}}) \end{bmatrix} \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \\
 &= \left[ v_{xx}(\underline{\mathbf{R}}) \underline{\mathbf{e}}_x \underline{\mathbf{e}}_x + v_{yy}(\underline{\mathbf{R}}) \underline{\mathbf{e}}_y \underline{\mathbf{e}}_y + v_{zz}(\underline{\mathbf{R}}) \underline{\mathbf{e}}_z \underline{\mathbf{e}}_z \right] \cdot \left[ B_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + B_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + B_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z \right] \\
 &= \underbrace{v_{xx}(\underline{\mathbf{R}}) B_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + v_{yy}(\underline{\mathbf{R}}) B_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + v_{zz}(\underline{\mathbf{R}}) B_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z}_{H_x(\underline{\mathbf{R}}, t)} + \underbrace{\phantom{v_{xx}(\underline{\mathbf{R}}) B_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + v_{yy}(\underline{\mathbf{R}}) B_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + v_{zz}(\underline{\mathbf{R}}) B_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z}}_{H_y(\underline{\mathbf{R}}, t)} + \underbrace{\phantom{v_{xx}(\underline{\mathbf{R}}) B_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + v_{yy}(\underline{\mathbf{R}}) B_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + v_{zz}(\underline{\mathbf{R}}) B_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z}}_{H_z(\underline{\mathbf{R}}, t)} \\
 &= H_x(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_x + H_y(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_y + H_z(\underline{\mathbf{R}}, t) \underline{\mathbf{e}}_z
 \end{aligned}$$

## Definition of Material Cells / Definition der Materialzellen



### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_{S^m} \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$$d\underline{\mathbf{S}} = \underline{\mathbf{n}} dS = \underline{\mathbf{e}}_x dS$$

$$d\underline{\mathbf{R}} = \underline{\mathbf{s}} dR$$

$$\iint_S \underline{\mathbf{n}} \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) dS = \iint_{S^m} \underline{\mathbf{e}}_x \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) dS$$

$$= \iint_S B_x(\underline{\mathbf{R}}, t) dS$$

$$= B_x^{(m)}(t) \underbrace{\iint_S dS}_{=\Delta y \Delta z} + O\left[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3\right]$$

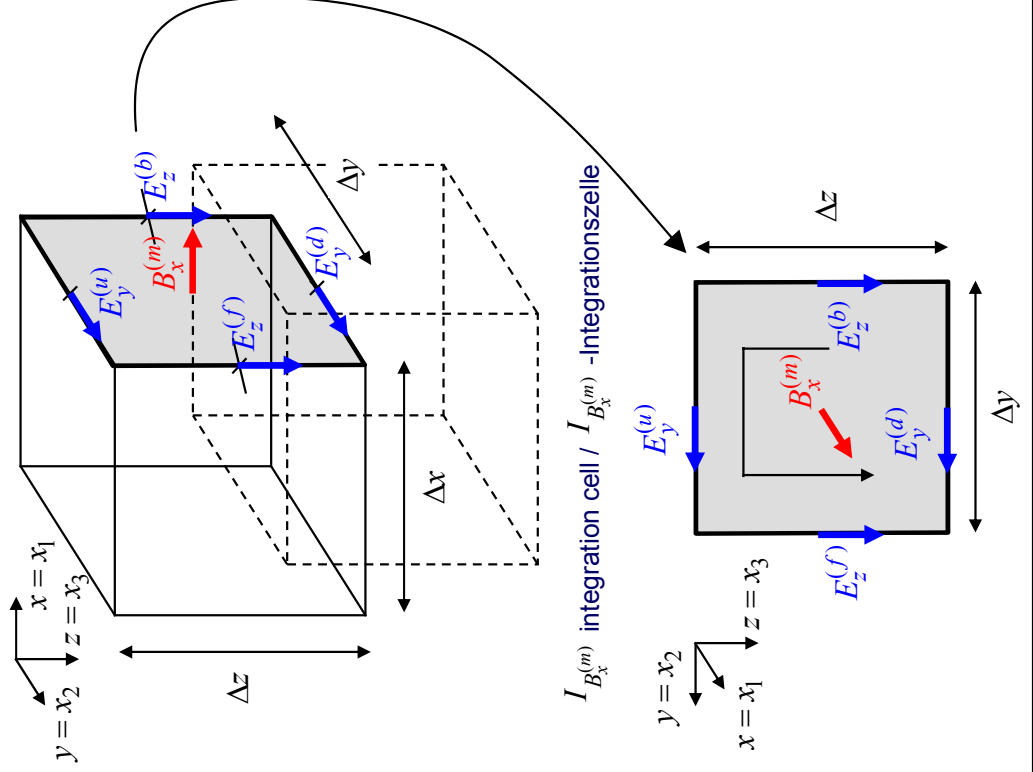
$$= B_x^{(m)}(t) \Delta y \Delta z + O\left[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3\right]$$

Field component in the middle /  
Feldkomponente in der Mitte

Approximation error /  
Approximationsfehler

$$\iint_S f(\underline{\mathbf{R}}, t) dS = f^{(m)}(t) \underbrace{\iint_S dy dz}_{=\Delta y \Delta z} + O\left[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3\right]$$

$$= f^{(m)}(t) \Delta y \Delta z + O\left[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3\right]$$



### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{S}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{R}} - \iint_{S_m} \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{S}}$$

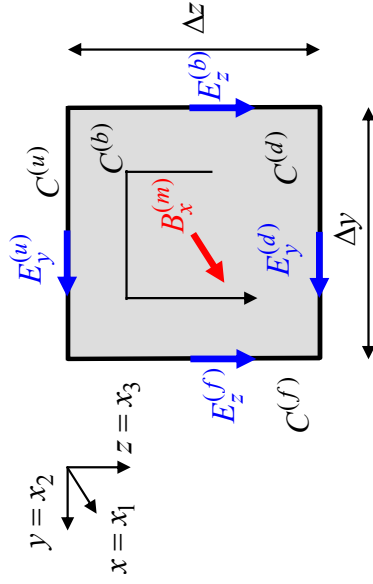
$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{R}} = ?$$

$$\underline{d\mathbf{S}} = \underline{\mathbf{n}} \, dS = \underline{\mathbf{e}}_x \, dy \, dz$$

$$\underline{d\mathbf{R}}_y = \underline{\mathbf{s}} \, dR = \underline{\mathbf{e}}_y \, dy$$

$$\underline{d\mathbf{R}}_z = \underline{\mathbf{s}} \, dR = \underline{\mathbf{e}}_z \, dz$$

$I_{B_x^{(m)}}$  integration cell /  $I_{B_x^{(m)}}$  -Integrationszelle



$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{R}} = \int_{C^{(u)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{R}} + \int_{C^{(f)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{R}} + \int_{C^{(d)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{R}} + \int_{C^{(b)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{d\mathbf{R}}$$

$$= \int_{C^{(u)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{e}}_y \, dy + \int_{C^{(f)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{e}}_z \, dz - \int_{C^{(d)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{e}}_y \, dy - \int_{C^{(b)}} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{e}}_z \, dz$$

$$= \int_{C^{(u)}} E_y(\underline{\mathbf{R}}, t) \, dy + \int_{C^{(f)}} E_z(\underline{\mathbf{R}}, t) \, dz - \int_{C^{(d)}} E_y(\underline{\mathbf{R}}, t) \, dy - \int_{C^{(b)}} E_z(\underline{\mathbf{R}}, t) \, dz$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\oint_{C=\partial S} \mathbf{E}(\mathbf{R}, t) \cdot d\mathbf{R} = \int_{C^{(u)}} E_y(\mathbf{R}, t) dy + \int_{C^{(l)}} E_z(\mathbf{R}, t) dz - \int_{C^{(b)}} E_z(\mathbf{R}, t) dz$$

$$\begin{aligned} \int_{C^{(u)}} E_y(\mathbf{R}, t) dy &= E_y^{(u)}(t) \underbrace{\int_{C^{(u)}} dy}_{=\Delta y} + \mathcal{O}[(\Delta y)^3] \\ &= E_y^{(u)}(t) \Delta y + \mathcal{O}[(\Delta y)^3] \end{aligned}$$

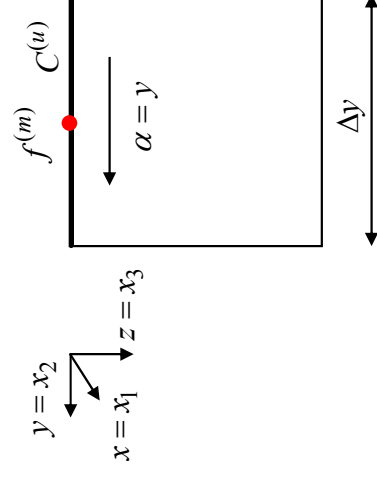
Field component in the middle /  
Feldkomponente in der Mitte

Approximation error /  
Approximationsfehler

$$\begin{aligned} \int_{C^{(l)}} E_z(\mathbf{R}, t) dz &= E_z^{(l)}(t) \underbrace{\int_{C^{(l)}} dz}_{=\Delta z} + \mathcal{O}[(\Delta z)^3] \\ &= E_z^{(l)}(t) \Delta z + \mathcal{O}[(\Delta z)^3] \end{aligned}$$

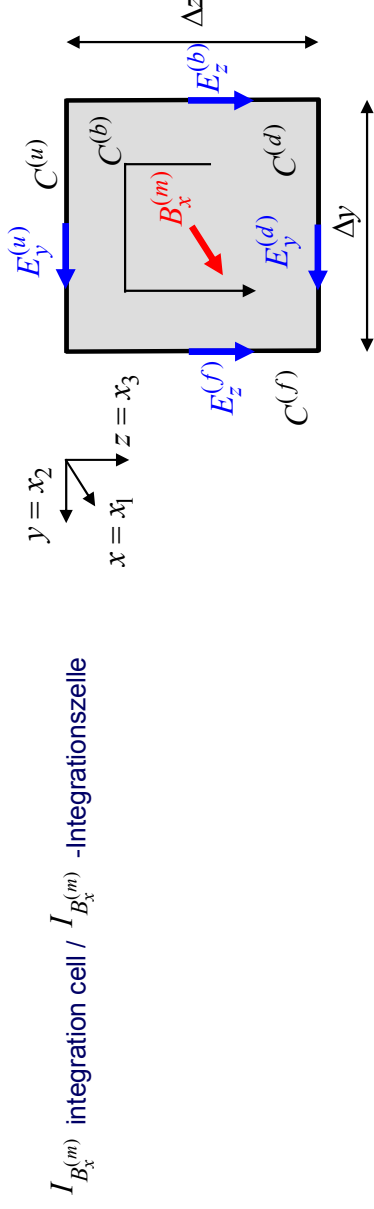
$$\begin{aligned} \int_{C^{(d)}} E_y(\mathbf{R}, t) dy &= E_y^{(d)}(t) \underbrace{\int_{C^{(d)}} dy}_{=\Delta y} + \mathcal{O}[(\Delta y)^3] \\ &= E_y^{(d)}(t) \Delta y + \mathcal{O}[(\Delta y)^3] \end{aligned}$$

$$\begin{aligned} \int_{C^{(b)}} E_z(\mathbf{R}, t) dz &= E_z^{(b)}(t) \underbrace{\int_{C^{(b)}} dz}_{=\Delta z} + \mathcal{O}[(\Delta z)^3] \\ &= E_z^{(b)}(t) \Delta z + \mathcal{O}[(\Delta z)^3] \end{aligned}$$



### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\begin{aligned} \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} &= \int_{C^{(u)}} E_y(\underline{\mathbf{R}}, t) dy + \int_{C^{(f)}} E_z(\underline{\mathbf{R}}, t) dz - \int_{C^{(a)}} E_y(\underline{\mathbf{R}}, t) dy - \int_{C^{(b)}} E_z(\underline{\mathbf{R}}, t) dz \\ &= \underbrace{E_y^{(u)}(t) \int_{C^{(u)}} dy + E_z^{(f)}(t) \int_{C^{(f)}} dz - E_y^{(d)}(t) \int_{C^{(a)}} dy - E_z^{(b)}(t) \int_{C^{(b)}} dz}_{=\Delta y} \\ &\quad + \mathcal{O}\left[(\Delta y)^3\right] + \mathcal{O}\left[(\Delta z)^3\right] \end{aligned}$$



$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} = E_y^{(u)}(t)\Delta y + E_z^{(f)}(t)\Delta z - E_y^{(d)}(t)\Delta y - E_z^{(b)}(t)\Delta z + \mathcal{O}\left[(\Delta y)^3\right] + \mathcal{O}\left[(\Delta z)^3\right]$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$I_{B_x^{(m)}}$  integration cell /  $I_{B_x^{(m)}}$  -Integrationszelle

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}} = E_y^{(u)}(t)\Delta y + E_z^{(f)}(t)\Delta z - E_y^{(d)}(t)\Delta y - E_z^{(b)}(t)\Delta z \\ + \mathcal{O}[(\Delta y)^3] + \mathcal{O}[(\Delta z)^3]$$

$I_{B_x^{(m)}}$  integration cell /  $I_{B_x^{(m)}}$  -Integrationszelle

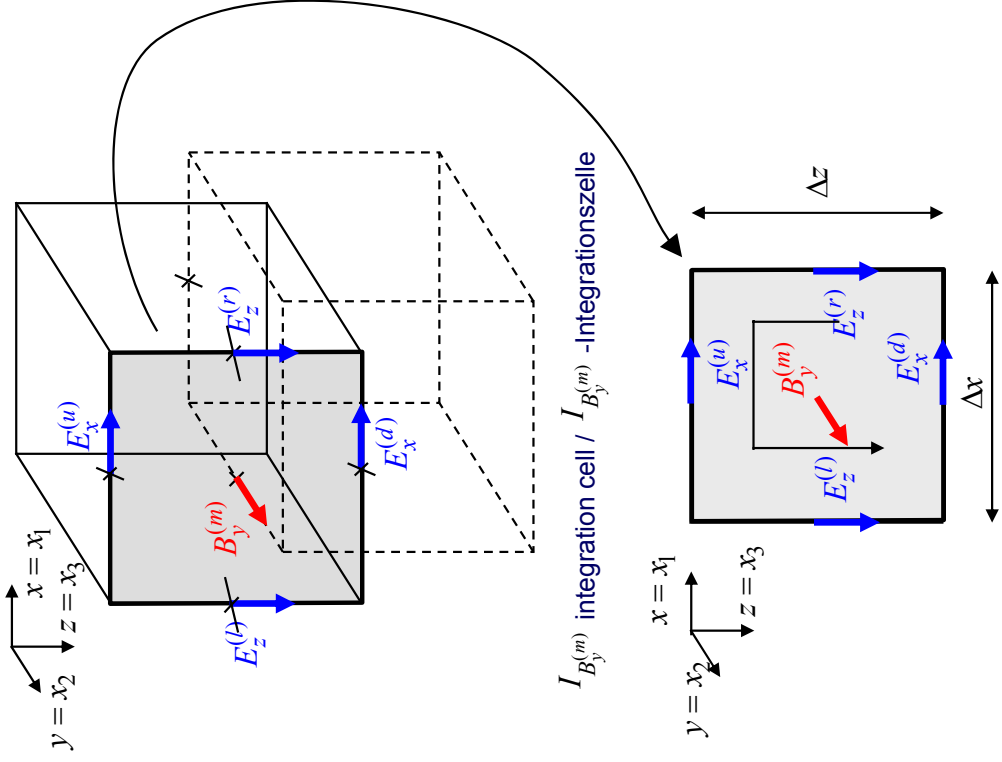
$$\iint_S \underline{\mathbf{n}} \cdot \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \, dS = \iint_S \underline{\mathbf{e}}_x \cdot \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \, dS \\ = \iint_S J_{mx}(\underline{\mathbf{R}}, t) \, dS \\ = J_{mx}^{(m)}(t) \iint_S \underbrace{dS}_{=\Delta y \Delta z} + \mathcal{O}[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3] \\ = J_{mx}^{(m)}(t) \Delta y \Delta z + \mathcal{O}[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3]$$

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}} - \iint_S \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}$$

$I_{B_x^{(m)}}$  integration cell /  $I_{B_x^{(m)}}$  -Integrationszelle

$$\frac{d}{dt} B_x^{(m)}(t) \Delta y \Delta z = - \left[ E_y^{(u)}(t) \Delta y + E_z^{(f)}(t) \Delta z - E_y^{(d)}(t) \Delta y - E_z^{(b)}(t) \Delta z \right] - J_{mx}^{(m)}(t) \Delta y \Delta z$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

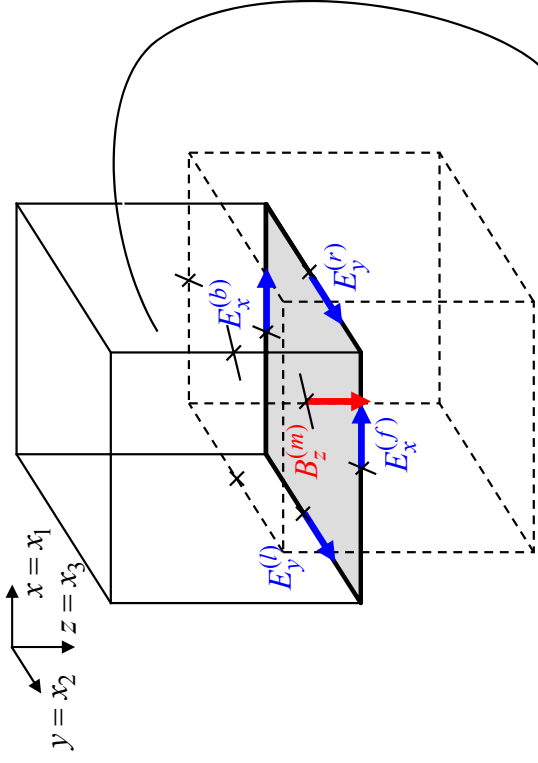


$$\frac{d}{dt} \iint_S \underline{B}(\underline{R}, t) \cdot d\underline{S} = - \oint_{C=\partial S} \underline{E}(\underline{R}, t) \cdot d\underline{R} - \iint_S \underline{J}_m(\underline{R}, t) \cdot d\underline{S}$$

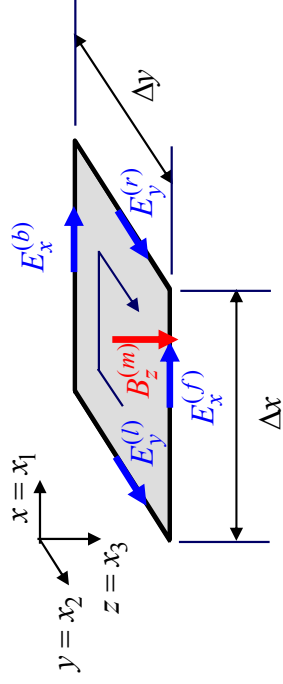
$I_{B_y^{(m)}}$  integration cell /  $I_{B_y^{(m)}}$  -Integrationszelle

$$\begin{aligned} \frac{d}{dt} B_y^{(m)}(t) \Delta y \Delta z &= - \left[ -E_x^{(u)}(t) \Delta x + E_z^{(l)}(t) \Delta z + E_x^{(d)}(t) \Delta x + E_z^{(r)}(t) \Delta z \right] \\ &\quad - J_{my}^{(m)}(t) \Delta y \Delta z \end{aligned}$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen



$I_{B_z^{(m)}}$  integration cell /  $I_{B_z^{(m)}}$  -Integrationszelle



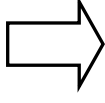
$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_{S'} \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$I_{B_z^{(m)}}$  integration cell /  $I_{B_z^{(m)}}$  -Integrationszelle

$$\begin{aligned} \frac{d}{dt} B_z^{(m)}(t) \Delta x \Delta y &= - \left[ E_x^{(b)}(t) \Delta x + E_y^{(r)}(t) \Delta y - E_x^{(f)}(t) \Delta x - E_y^{(l)}(t) \Delta y \right] \\ &\quad - J_{mz}^{(m)}(t) \Delta x \Delta y \end{aligned}$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} = - \iint_S \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$



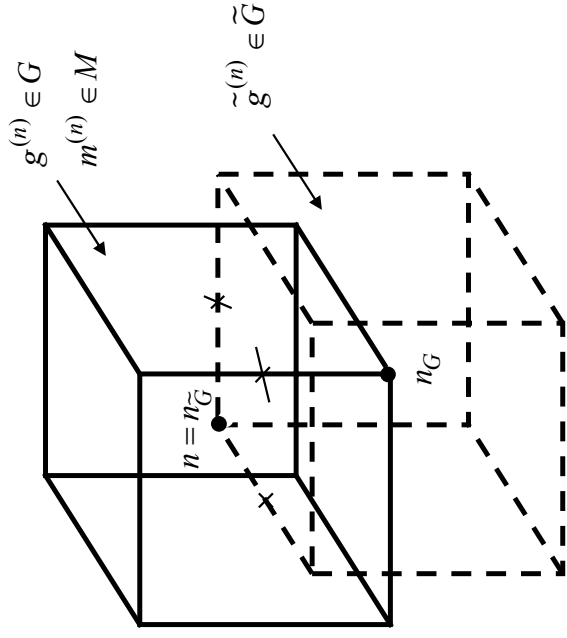
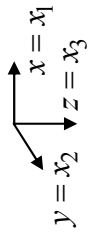
$$\frac{d}{dt} B_x^{(m)}(t) \Delta y \Delta z = - \left[ E_y^{(u)}(t) \Delta y + E_z^{(f)}(t) \Delta z - E_y^{(d)}(t) \Delta y - E_z^{(b)}(t) \Delta z \right] - J_{mx}^{(m)}(t) \Delta y \Delta z$$

$$\frac{d}{dt} B_y^{(m)}(t) \Delta y \Delta z = - \left[ -E_x^{(u)}(t) \Delta x + E_z^{(l)}(t) \Delta z + E_x^{(d)}(t) \Delta x - E_z^{(r)}(t) \Delta z \right] - J_{my}^{(m)}(t) \Delta y \Delta z$$

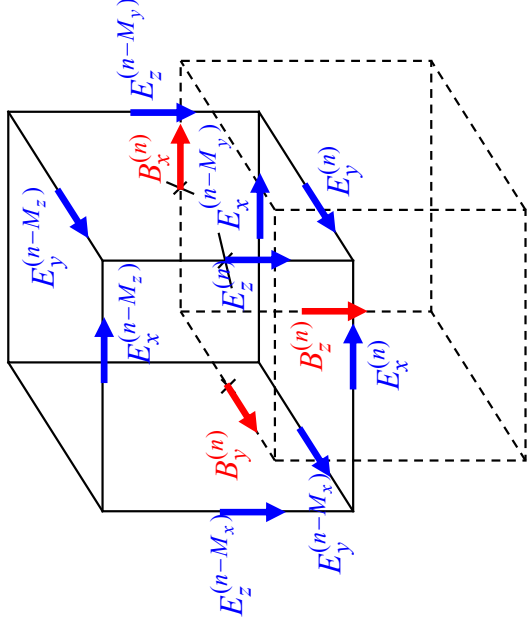
$$\frac{d}{dt} B_z^{(m)}(t) \Delta y \Delta z = - \left[ E_y^{(u)}(t) \Delta y + E_z^{(f)}(t) \Delta z - E_y^{(d)}(t) \Delta y + E_z^{(b)}(t) \Delta z \right] - J_{mz}^{(m)}(t) \Delta y \Delta z$$

# Dual-Orthogonal Grid System in Space / Dual-orthogonales Gittersystem im Raum

3-D / 3D



Primary grid /  $G \perp \tilde{G}$  Secondary (dual) grid  
 Primäres Gitter Sekundäres (duales) Gitter  
 Primary grid / Material grid  
 Primäres Gitter Materialgitter



Global node numbering / Globale Gitternummerierung

$$n = 1 + M_x(n_x - 1) + M_y(n_y - 1) + M_z(n_z - 1)$$

$$n = 1, 2, \dots, N = N_x N_y N_z$$

$$M_x = 1$$

$$M_y = N_x$$

$$M_z = N_x N_y$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

Local grid equations in local notation / Lokale Gittergleichungen in lokaler Notation

$$\begin{aligned} \frac{d}{dt} B_x^{(m)}(t) \Delta y \Delta z &= - \left[ E_y^{(u)}(t) \Delta y + E_z^{(f)}(t) \Delta z - E_y^{(d)}(t) \Delta y - E_z^{(b)}(t) \Delta z \right] - J_{\text{mx}}^{(m)}(t) \Delta y \Delta z \\ \frac{d}{dt} B_y^{(m)}(t) \Delta x \Delta z &= - \left[ -E_x^{(u)}(t) \Delta x + E_z^{(l)}(t) \Delta z + E_x^{(d)}(t) \Delta x - E_z^{(r)}(t) \Delta z \right] - J_{\text{my}}^{(m)}(t) \Delta x \Delta z \\ \frac{d}{dt} B_z^{(m)}(t) \Delta x \Delta y &= - \left[ E_x^{(b)}(t) \Delta x + E_y^{(r)}(t) \Delta y - E_x^{(f)}(t) \Delta x - E_y^{(l)}(t) \Delta y \right] - J_{\text{mz}}^{(m)}(t) \Delta x \Delta y \end{aligned}$$

Local grid equations in global grid node notation / Lokale Gittergleichungen in globaler Gitterknotennotation

$$\begin{aligned} \frac{d}{dt} B_x^{(n)}(t) \Delta y \Delta z &= - \left\{ \left[ E_y^{(n-M_z)}(t) - E_y^{(n)}(t) \right] \Delta y + \left[ E_z^{(n)}(t) - E_z^{(n-M_y)}(t) \right] \Delta z \right\} - J_{\text{mx}}^{(n)}(t) \Delta y \Delta z \\ \frac{d}{dt} B_y^{(n)}(t) \Delta x \Delta z &= - \left\{ \left[ E_x^{(n)}(t) - E_x^{(n-M_z)}(t) \right] \Delta x + \left[ E_z^{(n-M_x)}(t) - E_z^{(n)}(t) \right] \Delta z \right\} - J_{\text{my}}^{(n)}(t) \Delta x \Delta z \\ \frac{d}{dt} B_z^{(n)}(t) \Delta x \Delta y &= - \left\{ \left[ E_x^{(n-M_y)}(t) - E_x^{(n)}(t) \right] \Delta x + \left[ E_y^{(n)}(t) - E_y^{(n-M_x)}(t) \right] \Delta y \right\} - J_{\text{mz}}^{(n)}(t) \Delta x \Delta y \end{aligned}$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

Local grid equations in global grid node notation / Lokale Gittergleichungen in globaler Gitterknotennotation

$$\frac{d}{dt} B_x^{(n)}(t) \Delta y \Delta z = - \left\{ \left[ E_y^{(n-M_z)}(t) - E_y^{(n)}(t) \right] \Delta y + \left[ E_z^{(n-M_y)}(t) - E_z^{(n)}(t) \right] \Delta z \right\} - J_{\text{mx}}^{(n)}(t) \Delta y \Delta z$$

$$\frac{d}{dt} B_y^{(n)}(t) \Delta x \Delta z = - \left\{ \left[ E_x^{(n)}(t) - E_x^{(n-M_z)}(t) \right] \Delta x + \left[ E_z^{(n-M_x)}(t) - E_z^{(n)}(t) \right] \Delta z \right\} - J_{\text{my}}^{(n)}(t) \Delta x \Delta z$$

$$\frac{d}{dt} B_z^{(n)}(t) \Delta x \Delta y = - \left\{ \left[ E_x^{(n-M_y)}(t) - E_x^{(n)}(t) \right] \Delta x + \left[ E_y^{(n)}(t) - E_y^{(n-M_x)}(t) \right] \Delta y \right\} - J_{\text{mz}}^{(n)}(t) \Delta x \Delta y$$

Local spatial shift operators / Lokale räumliche Schiebeoperatoren

$$S_{\pm M_i} f^{(n)} = f^{(n \pm M_i)}$$

$$S_0 f^{(n)} = f^{(n)}$$

$$S_0 = I$$

$$I f^{(n)} = f^{(n)}$$

Local grid equations with local spatial shift operators in global grid node notation /  
Lokale Gittergleichungen mit lokalen räumlichen Schiebeoperatoren in globaler Gitterknotennotation

$$\frac{d}{dt} B_x^{(n)}(t) \Delta y \Delta z = - \left\{ \left[ S_{-M_z} - I \right] E_y^{(n)}(t) \Delta y + \left[ I - S_{M_y} \right] E_z^{(n)}(t) \Delta z \right\} - J_{\text{mx}}^{(n)}(t) \Delta y \Delta z$$

$$\frac{d}{dt} B_y^{(n)}(t) \Delta x \Delta z = - \left\{ \left[ I - S_{-M_z} \right] E_x^{(n)}(t) \Delta x + \left[ S_{-M_x} - I \right] E_z^{(n)}(t) \Delta z \right\} - J_{\text{my}}^{(n)}(t) \Delta x \Delta z$$

$$\frac{d}{dt} B_z^{(n)}(t) \Delta x \Delta y = - \left\{ \left[ S_{-M_y} - I \right] E_x^{(n)}(t) \Delta x + \left[ I - S_{-M_x} \right] E_y^{(n)}(t) \Delta y \right\} - J_{\text{mz}}^{(n)}(t) \Delta x \Delta y$$

## 3-D FIT – Local Spatial Shift Operators / 3D-FIT – Lokale räumliche Schiebeoperatoren

1. Simple spatial shift operation / Einfache räumliche Schiebeoperation

$$S_{\pm M_i} f^{(n)} = f^{(n \pm M_i)}$$

2. Identity operation / Identitätsoperation

$$I f^{(n)} = f^{(n)}$$

3. Multiple shift operations / Zusammengesetzte Schiebeoperationen

$$S_{\pm M_i} S_{\pm M_j} f^{(n)} = S_{\pm M_j} S_{\pm M_i} f^{(n)} = f^{(n \pm M_i \pm M_j)}$$

Special case for  $M_j = -M_i$  / Speziell folgt für  $M_j = -M_i$

$$S_{\pm M_i} S_{\mp M_i} = I$$

4. Local difference operator / Lokaler Differenzoperator

$$P_{\pm M_i} = \mp I \pm S_{\pm M_i}$$

5. Local averaging operator / Lokaler Mittelungsoperator

$$A_{\pm M_i} = \frac{1}{2} (I + S_{\pm M_i})$$

## 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

Local grid equations with local spatial shift operators in global grid node notation /  
Lokale Gittergleichungen mit lokalen räumlichen Schiebeoperatoren in globaler Gitterknotennotation

$$\begin{aligned} \frac{d}{dt} B_x^{(n)} \Delta y \Delta z &= - \left\{ \left[ S_{-M_z} - I \right] E_y^{(n)}(t) \Delta y + \left[ I - S_{M_y} \right] E_z^{(n)}(t) \Delta z \right\} - J_{mx}^{(n)}(t) \Delta y \Delta z \\ \frac{d}{dt} B_y^{(n)} \Delta x \Delta z &= - \left\{ \left[ I - S_{-M_z} \right] E_x^{(n)}(t) \Delta x + \left[ S_{-M_x} - I \right] E_z^{(n)}(t) \Delta z \right\} - J_{my}^{(n)}(t) \Delta x \Delta z \\ \frac{d}{dt} B_z^{(n)} \Delta x \Delta y &= - \left\{ \left[ S_{-M_y} - I \right] E_x^{(n)}(t) \Delta x + \left[ I - S_{-M_x} \right] E_y^{(n)}(t) \Delta y \right\} - J_{mz}^{(n)}(t) \Delta x \Delta y \end{aligned}$$

... in local matrix form / ... in lokaler Matrixform

$$\underbrace{\begin{bmatrix} \Delta y \Delta z \\ \Delta x \Delta z \\ \Delta x \Delta y \end{bmatrix}}_{=[S]} \frac{d}{dt} \underbrace{\begin{bmatrix} B_x^{(n)}(t) \\ B_y^{(n)}(t) \\ B_z^{(n)}(t) \end{bmatrix}}_{=\{B\}^{(n)}(t)} = - \underbrace{\begin{bmatrix} 0 & S_{-M_z} - I & I - S_{M_y} \\ I - S_{-M_z} & 0 & S_{-M_x} - I \\ S_{-M_y} - I & I - S_{-M_x} & 0 \end{bmatrix}}_{=[\text{curl}]} \underbrace{\begin{bmatrix} \Delta x & & \\ & \Delta y & \\ & & \Delta z \end{bmatrix}}_{=[R]} \underbrace{\begin{bmatrix} E_x^{(n)}(t) \\ E_y^{(n)}(t) \\ E_z^{(n)}(t) \end{bmatrix}}_{=\{E\}^{(n)}(t)} - \underbrace{\begin{bmatrix} \Delta y \Delta z & & \\ & \Delta x \Delta z & \\ & & \Delta x \Delta y \end{bmatrix}}_{=[S]} \underbrace{\begin{bmatrix} J_{mx}^{(n)}(t) \\ J_{my}^{(n)}(t) \\ J_{mz}^{(n)}(t) \end{bmatrix}}_{=\{J_m\}^{(n)}(t)}$$

### 3-D FIT – ... Discrete Grid Equations in Local Matrix Form / 3D-FIT – ... diskreten Gittergleichungen in lokaler Matrixform

$$\underbrace{\begin{bmatrix} \Delta y \Delta z \\ \Delta x \Delta z \\ \Delta x \Delta y \end{bmatrix}}_{=[S]} \frac{d}{dt} \underbrace{\begin{Bmatrix} B_x^{(n)}(t) \\ B_y^{(n)}(t) \\ B_z^{(n)}(t) \end{Bmatrix}}_{=\{B\}^{(n)}(t)} = - \underbrace{\begin{bmatrix} 0 & S_{-M_z} - I & I - S_{-M_y} \\ I - S_{-M_z} & 0 & S_{-M_x} - I \\ S_{-M_y} - I & I - S_{-M_x} & 0 \end{bmatrix}}_{=[\text{curl}]} \underbrace{\begin{bmatrix} \Delta x \\ \Delta y \\ \Delta z \end{bmatrix}}_{=[R]} \underbrace{\begin{Bmatrix} E_x^{(n)}(t) \\ E_y^{(n)}(t) \\ E_z^{(n)}(t) \end{Bmatrix}}_{=\{E\}^{(n)}(t)}$$
  

$$- \underbrace{\begin{bmatrix} \Delta y \Delta z \\ \Delta x \Delta z \\ \Delta x \Delta y \end{bmatrix}}_{=[S]} \underbrace{\begin{Bmatrix} J_{mx}^{(n)}(t) \\ J_{my}^{(n)}(t) \\ J_{mz}^{(n)}(t) \end{Bmatrix}}_{=\{J_m\}^{(n)}(t)}$$
  

$$\begin{bmatrix} 0 & S_{-M_z} - I & I - S_{-M_y} \\ I - S_{-M_z} & 0 & S_{-M_x} - I \\ S_{-M_y} - I & I - S_{-M_x} & 0 \end{bmatrix} \begin{bmatrix} 0 & -P_{-M_z} & P_{-M_y} \\ P_{-M_z} & 0 & -P_{-M_x} \\ -P_{-M_y} & P_{-M_x} & 0 \end{bmatrix} = [\text{curl}]$$

## 3-D FIT – ... Discrete Grid Equations in Local Matrix Form / 3D-FIT – ... diskreten Gittergleichungen in lokaler Matrixform

Faraday's induction law in local matrix form / Faradaysches Induktionsgesetz in lokaler Matrixform

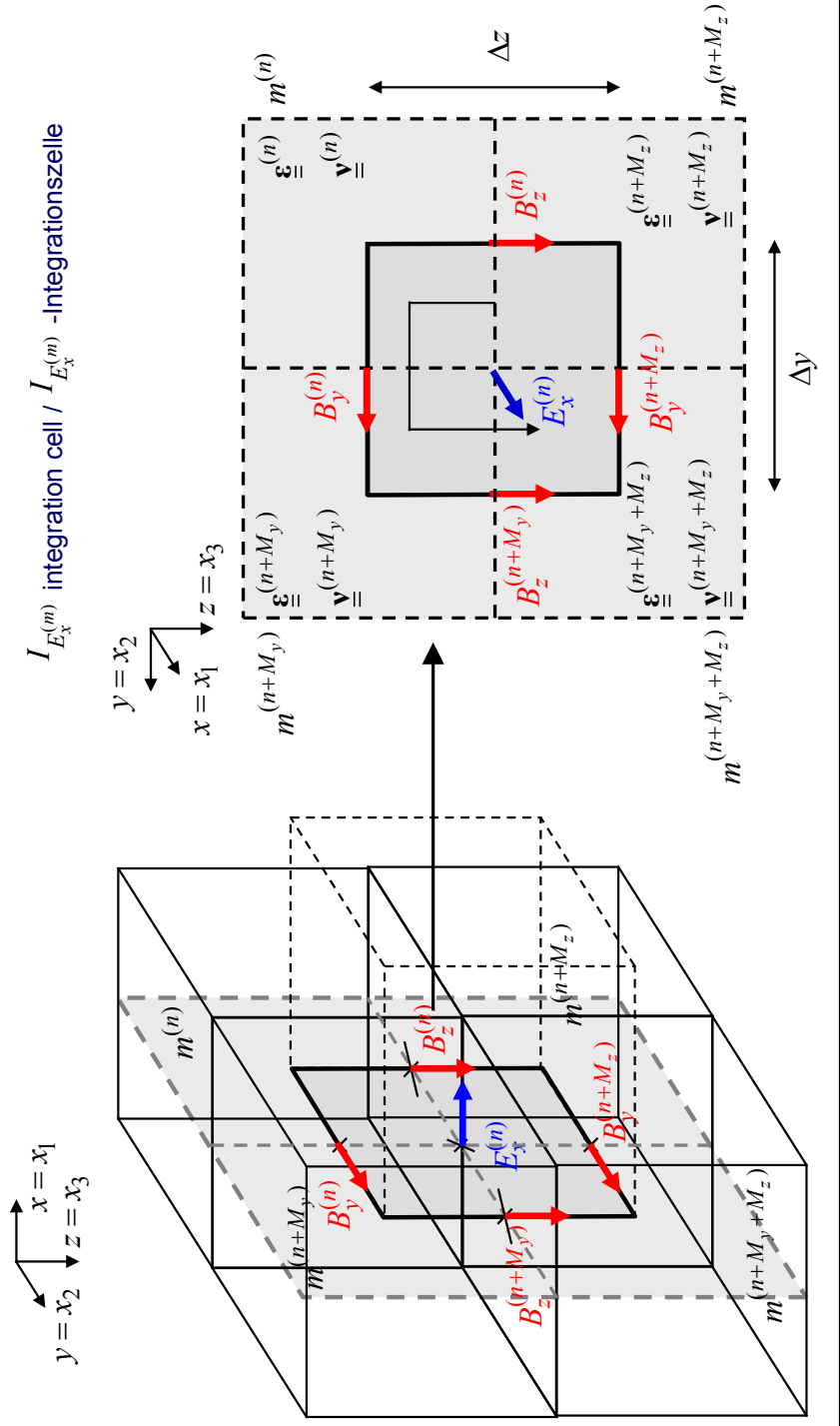
$$\underbrace{\begin{bmatrix} \Delta y \Delta z & & & \\ & \Delta x \Delta z & & \\ & & \Delta x \Delta y & \\ & & & \Delta x \Delta y \end{bmatrix}}_{=[S]} \frac{d}{dt} \underbrace{\begin{Bmatrix} B_x^{(n)}(t) \\ B_y^{(n)}(t) \\ B_z^{(n)}(t) \end{Bmatrix}}_{=\{B\}^{(n)}(t)} = - \underbrace{\begin{bmatrix} 0 & -P_{-M_z} & P_{-M_y} & \\ P_{-M_z} & 0 & -P_{-M_x} & \\ -P_{-M_y} & P_{-M_x} & 0 & \end{bmatrix}}_{=[\text{curl}]} \underbrace{\begin{bmatrix} \Delta x & & & \\ & \Delta y & & \\ & & \Delta z & \\ & & & \Delta z \end{bmatrix}}_{=[R]} \underbrace{\begin{Bmatrix} E_x^{(n)}(t) \\ E_y^{(n)}(t) \\ E_z^{(n)}(t) \end{Bmatrix}}_{=\{E\}^{(n)}(t)} - \underbrace{\begin{bmatrix} \Delta y \Delta z & & & \\ & \Delta x \Delta z & & \\ & & \Delta x \Delta y & \\ & & & \Delta x \Delta y \end{bmatrix}}_{=[S]} \underbrace{\begin{Bmatrix} J_{mx}^{(n)}(t) \\ J_{my}^{(n)}(t) \\ J_{mz}^{(n)}(t) \end{Bmatrix}}_{=\{J_m\}^{(n)}(t)}$$

$$[S] \frac{d}{dt} \{B\}^{(n)}(t) = -[\text{curl}][R] \{E\}^{(n)}(t) - [S] \{J_m\}^{(n)}(t)$$

- $[S] \in \mathbb{R}^{3 \times 3}$  Diagonal matrix of elementary surfaces on the grid  $G$  /  
Diagonalmatrix der Elementarflächen auf dem Gitter  $G$
- $\{B\}^{(n)}(t) \in \mathbb{R}^3$  Algebraic magnetic flux density vector /  
Algebraischer magnetischer Flussdichtevektor
- $[\text{curl}] \in \mathbb{R}^{3 \times 3}$  Topological curl operator in matrix form on the grid  $G$  /  
Topologischer Rotationsoperator in Matrixform auf dem Gitter  $G$
- $[R] \in \mathbb{R}^{3 \times 3}$  Diagonal matrix of elementary lines on the grid  $G$  /  
Diagonalmatrix der Elementarstrecken auf dem Gitter  $G$
- $\{E\}^{(n)}(t) \in \mathbb{R}^3$  Algebraic electric field strength vector /  
Algebraischer elektrische Feldstärkevektor
- $\{J_m\}^{(n)}(t) \in \mathbb{R}^3$  Algebraic magnetic current density vector /  
Algebraischer magnetischer Stromdichtevektor

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S [\underline{\underline{\epsilon}}(\mathbf{R}) \cdot \underline{\underline{E}}(\mathbf{R}, t)] \cdot d\underline{\underline{S}} = \oint_{C=\partial S} [\underline{\underline{v}}(\mathbf{R}) \cdot \underline{\underline{B}}(\mathbf{R}, t)] \cdot d\underline{\underline{R}} - \iint_S \underline{\underline{J}}_e(\mathbf{R}, t) \cdot d\underline{\underline{S}}$$



### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S [\underline{\varepsilon}(\mathbf{R}) \cdot \underline{\mathbf{E}}(\mathbf{R}, t)] \cdot d\mathbf{S} = \oint_{C=\partial S} [\underline{\mathbf{v}}(\mathbf{R}) \cdot \underline{\mathbf{B}}(\mathbf{R}, t)] \cdot d\mathbf{R} - \iint_S \underline{\mathbf{J}}_e(\mathbf{R}, t) \cdot d\mathbf{S}$$

$$\iint_S [\underline{\varepsilon}(\mathbf{R}) \cdot \underline{\mathbf{E}}(\mathbf{R}, t)] \cdot d\mathbf{S} = \iint_{S=x} \mathbf{e}_x \cdot [\underline{\varepsilon}(\mathbf{R}) \cdot \underline{\mathbf{E}}(\mathbf{R}, t)] \cdot d\mathbf{S}$$

$$= \iint_S \varepsilon_{xx}(\mathbf{R}) E_x(\mathbf{R}, t) \, dS$$

$$= E_x^{(n)}(t) \iint_S \varepsilon_{xx}(\mathbf{R}) \, dS$$

$$+ O\left[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3\right]$$

$$\iint_S \varepsilon_{xx}(\mathbf{R}) \, dS$$

$$= \frac{1}{4} \left[ \varepsilon_{xx}^{(n)} + \varepsilon_{xx}^{(n+M_y)} + \varepsilon_{xx}^{(n+M_z)} + \varepsilon_{xx}^{(n+M_y+M_z)} \right] \Delta y \Delta z$$

$$\stackrel{\sim}{=} \varepsilon_{xx}^{(n)}$$

$$= \tilde{\varepsilon}_{xx}^{(n)} \Delta y \Delta z$$

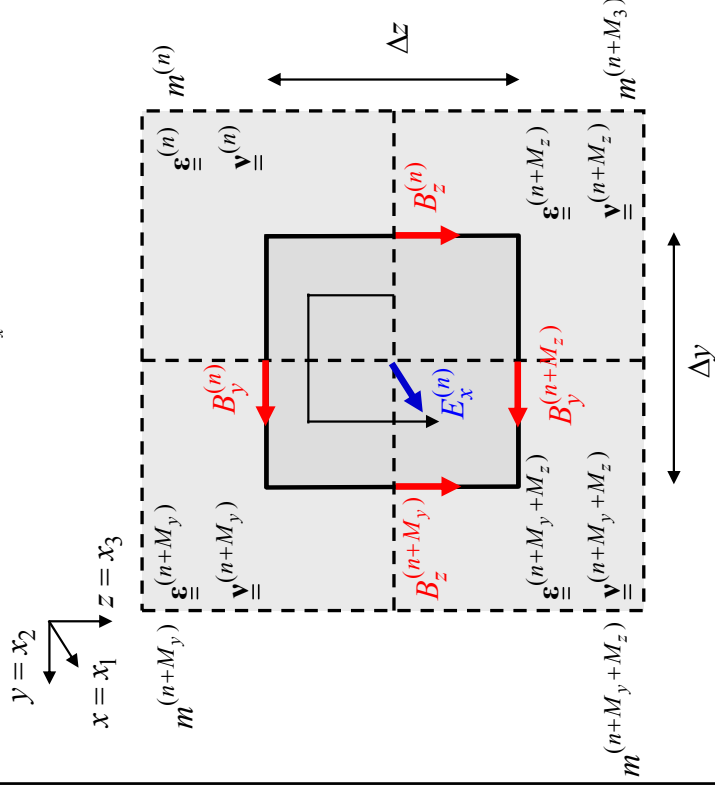
$$\iint_S [\underline{\varepsilon}(\mathbf{R}) \cdot \underline{\mathbf{E}}(\mathbf{R}, t)] \cdot d\mathbf{S}$$

$$= E_x^{(n)}(t) \tilde{\varepsilon}_{xx}^{(n)} \Delta y \Delta z + O\left[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3\right]$$

$$\iint_S \underline{\mathbf{J}}_e(\mathbf{R}, t) \cdot d\mathbf{S}$$

$$= J_{\text{ext}}^{(n)}(t) \Delta y \Delta z + O\left[(\Delta y)^3 \Delta z + \Delta y (\Delta z)^3\right]$$

$I_{E_x^{(m)}}$  integration cell /  $I_{E_x^{(m)}}$  - Integrationszelle



### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S [\underline{\epsilon}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{E}}(\underline{\mathbf{R}}, t)] \cdot \underline{dS} = \oint_{C=\partial S} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} - \iint_S \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t) \cdot \underline{dS}$$

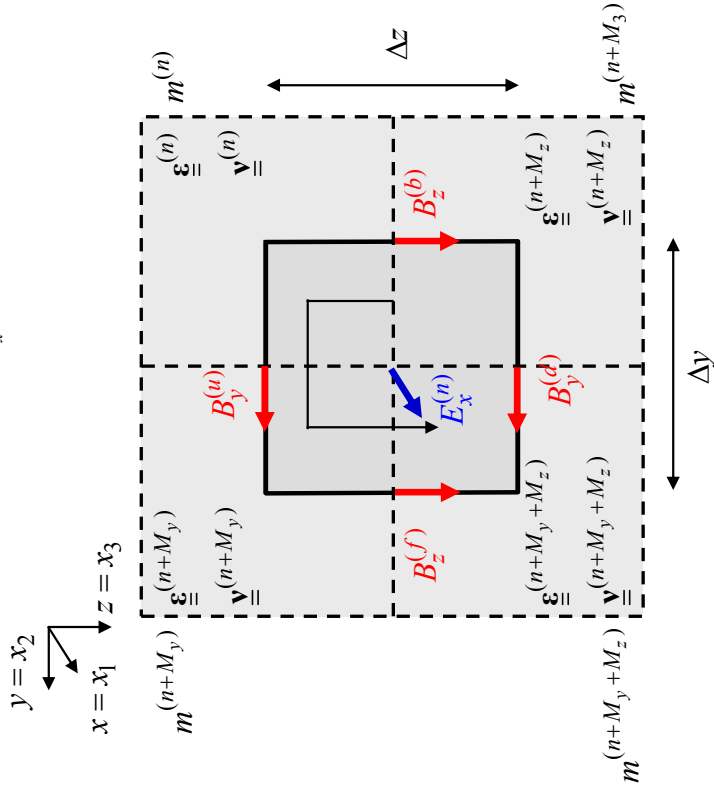
$$\oint_{C=\partial S} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} = ?$$

$$\underline{dS} = \underline{\mathbf{n}} dS = \underline{\mathbf{e}}_x dy dz$$

$$\underline{dR}_y = \underline{\mathbf{s}} dR = \underline{\mathbf{e}}_y dy$$

$$\underline{dR}_z = \underline{\mathbf{s}} dR = \underline{\mathbf{e}}_z dz$$

$I_{E_x^{(m)}}$  integration cell /  $I_{E_x^{(m)}}$  -Integrationszelle



$$\begin{aligned} \oint_{C=\partial S} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} &= \int_{C^{(u)}} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} \\ &+ \int_{C^{(f)}} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} \\ &- \int_{C^{(d)}} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} \\ &- \int_{C^{(b)}} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} \end{aligned}$$

$$\begin{aligned} \oint_{C=\partial S} [\underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)] \cdot \underline{dR} &= \int_{C^{(u)}} v_{yy}(\underline{\mathbf{R}}) B_y(\underline{\mathbf{R}}, t) dy \\ &+ \int_{C^{(f)}} v_{zz}(\underline{\mathbf{R}}) B_z(\underline{\mathbf{R}}, t) dz \\ &- \int_{C^{(d)}} v_{yy}(\underline{\mathbf{R}}) B_y(\underline{\mathbf{R}}, t) dy \\ &- \int_{C^{(b)}} v_{zz}(\underline{\mathbf{R}}) B_z(\underline{\mathbf{R}}, t) dz \end{aligned}$$

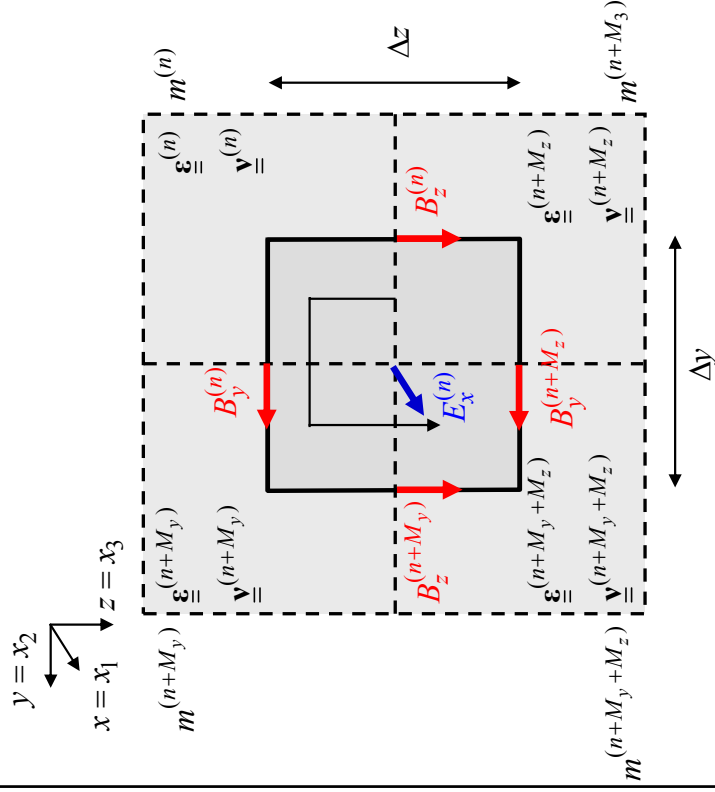
### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\begin{aligned}
 & \oint_{C=\partial S} [\underline{v}(\mathbf{R}) \cdot \underline{B}(\mathbf{R}, t)] \cdot d\mathbf{R} \\
 &= \int_{C^{(u)}} v_{yy}(\mathbf{R}) B_y(\mathbf{R}, t) dy + \int_{C^{(l)}} v_{zz}(\mathbf{R}) B_z(\mathbf{R}, t) dz - \int_{C^{(d)}} v_{yy}(\mathbf{R}) B_y(\mathbf{R}, t) dy - \int_{C^{(b)}} v_{zz}(\mathbf{R}) B_z(\mathbf{R}, t) dz \\
 \\
 & \int_{C^{(u)}} v_{yy}(\mathbf{R}) B_y(\mathbf{R}, t) dy = B_y^{(u)}(t) \int_{C^{(u)}} v_{yy}(\mathbf{R}) dy + \mathcal{O}[(\Delta y)^3] \qquad \int_{C^{(u)}} v_{yy}(\mathbf{R}) dy = \frac{1}{2} [v_{yy}^{(n)} + v_{yy}^{(n+M_y)}] \Delta y \\
 \\
 & \int_{C^{(l)}} v_{zz}(\mathbf{R}) B_z(\mathbf{R}, t) dz = B_z^{(l)}(t) \int_{C^{(l)}} v_{zz}(\mathbf{R}) dz + \mathcal{O}[(\Delta z)^3] \qquad \int_{C^{(l)}} v_{zz}(\mathbf{R}) dz = \frac{1}{2} [v_{zz}^{(n+M_z)} + v_{zz}^{(n+M_y+M_z)}] \Delta z \\
 \\
 & \int_{C^{(d)}} v_{yy}(\mathbf{R}) B_y(\mathbf{R}, t) dy = B_y^{(d)}(t) \int_{C^{(d)}} v_{yy}(\mathbf{R}) dy + \mathcal{O}[(\Delta y)^3] \qquad \int_{C^{(d)}} v_{yy}(\mathbf{R}) dy = \frac{1}{2} [v_{zz}^{(n+M_y)} + v_{zz}^{(n+M_y+M_z)}] \Delta y \\
 \\
 & \int_{C^{(b)}} v_{zz}(\mathbf{R}) B_z(\mathbf{R}, t) dz = B_z^{(b)}(t) \int_{C^{(b)}} v_{zz}(\mathbf{R}) dz + \mathcal{O}[(\Delta z)^3] \qquad \int_{C^{(b)}} v_{zz}(\mathbf{R}) dz = \frac{1}{2} [v_{zz}^{(n)} + v_{zz}^{(n+M_z)}] \Delta z
 \end{aligned}$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S [\underline{\epsilon}(\mathbf{R}) \cdot \underline{E}(\mathbf{R}, t)] \cdot \underline{dS} = \oint_{C=\partial S} [\underline{v}(\mathbf{R}) \cdot \underline{B}(\mathbf{R}, t)] \cdot \underline{dR} - \iint_S [\underline{J}_e(\mathbf{R}, t) \cdot \underline{dS}]$$

$I_{E_x^{(m)}}$  integration cell /  $I_{E_x^{(m)}}$  -Integrationszelle



$$\begin{aligned} \oint_{C=\partial S} [\underline{v}(\mathbf{R}) \cdot \underline{B}(\mathbf{R}, t)] \cdot \underline{dR} &= \frac{1}{2} \left[ \underbrace{v_{yy}^{(n)} + v_{yy}^{(n+M_y)}}_{=V_{yy}^{(n)}} \right] B_y^{(n)}(t) \Delta y \\ &\quad - \frac{1}{2} \left[ \underbrace{v_{yy}^{(n+M_z)} + v_{yy}^{(n+M_y+M_z)}}_{=V_{yy}^{(n+M_y)}} \right] B_y^{(n+M_y)}(t) \Delta y \\ &\quad + \frac{1}{2} \left[ \underbrace{v_{zz}^{(n+M_y)} + v_{zz}^{(n+M_y+M_z)}}_{=V_{zz}^{(n+M_z)}} \right] B_z^{(n+M_y)}(t) \Delta z \\ &\quad - \frac{1}{2} \left[ \underbrace{v_{zz}^{(n)} + v_{zz}^{(n+M_z)}}_{=V_{zz}^{(n)}} \right] B_z^{(n)}(t) \Delta z \\ &= v_{yy}^{(n)} B_y^{(n)}(t) \Delta y - \tilde{v}_{yy}^{(n+M_y)} B_y^{(n+M_y)}(t) \Delta y \\ &\quad + v_{zz}^{(n+M_z)} B_z^{(n+M_y)}(t) \Delta z - v_{zz}^{(n)} B_z^{(n)}(t) \Delta z \end{aligned}$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S [\underline{\mathbf{e}}(\mathbf{R}, t) \cdot \underline{\mathbf{E}}(\mathbf{R}, t)] \cdot \underline{\mathbf{dS}} = \oint_{C=\partial S} [\underline{\mathbf{v}}(\mathbf{R}, t) \cdot \underline{\mathbf{B}}(\mathbf{R}, t)] \cdot \underline{\mathbf{dR}} - \iint_S \underline{\mathbf{j}}_e(\mathbf{R}, t) \cdot \underline{\mathbf{dS}}$$

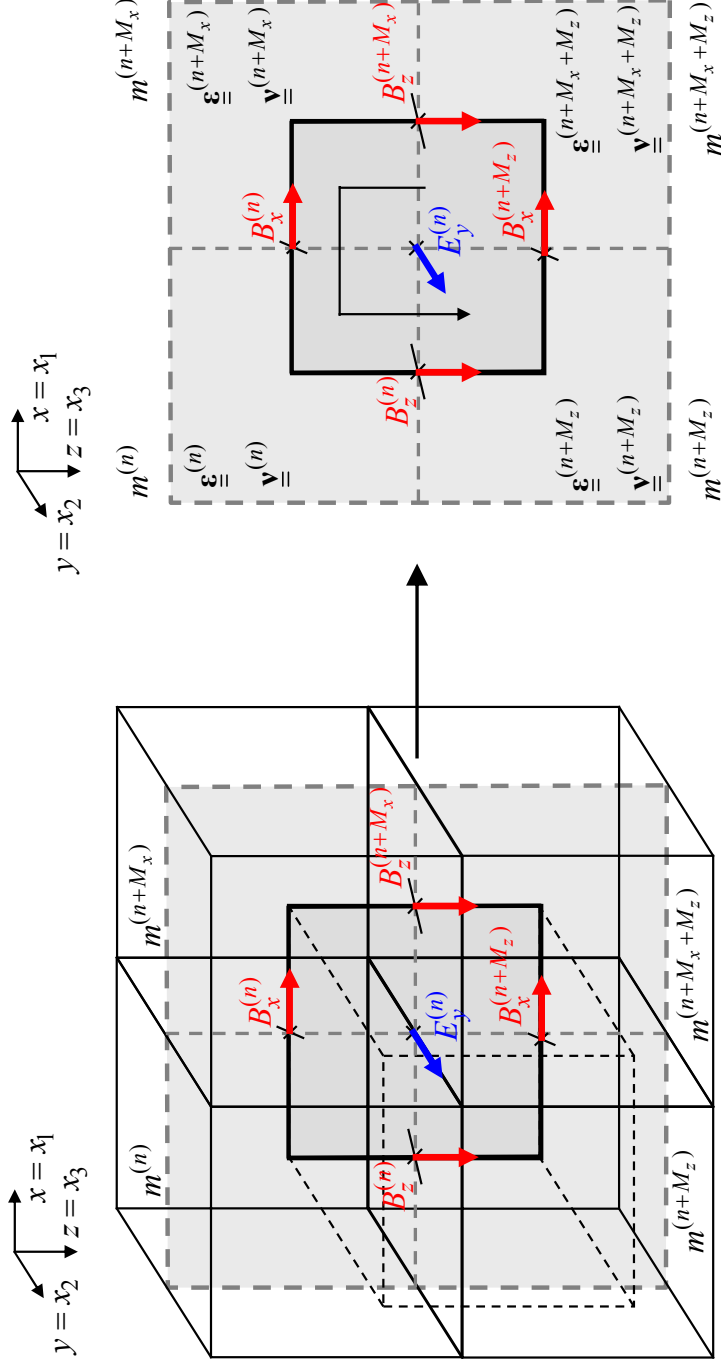
$I_{E_x^{(m)}}$  integration cell /  $I_{E_x^{(m)}}$  -Integrationszelle

$$\begin{aligned} \tilde{\varepsilon}_{xx}^{(n)} \frac{d}{dt} E_x^{(n)}(t) \Delta y \Delta z &= \tilde{v}_{yy}^{(n)} B_y^{(n)}(t) \Delta y - \tilde{v}_{yy}^{(n+M_z)} B_y^{(n+M_z)}(t) \Delta y \\ &+ \tilde{v}_{zz}^{(n+M_y)} B_z^{(n+M_y)}(t) \Delta z - \tilde{v}_{zz}^{(n)} B_z^{(n)}(t) \Delta z - J_{\text{ex}}^{(n)}(t) \Delta y \Delta z \\ &= (I - S_{M_z}) \tilde{v}_{yy}^{(n)} B_y^{(n)}(t) \Delta y + (S_{M_y} - I) \tilde{v}_{zz}^{(n)} B_z^{(n)}(t) \Delta z - J_{\text{ex}}^{(n)}(t) \Delta y \Delta z \end{aligned}$$

### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S [\underline{\underline{\epsilon}}(\mathbf{R}) \cdot \underline{\underline{E}}(\mathbf{R}, t)] \cdot \underline{\underline{dS}} = \oint_{C=\partial S} [\underline{\underline{v}}(\mathbf{R}) \cdot \underline{\underline{B}}(\mathbf{R}, t)] \cdot \underline{\underline{dR}} - \iint_S \underline{\underline{J}}_e(\mathbf{R}, t) \cdot \underline{\underline{dS}}$$

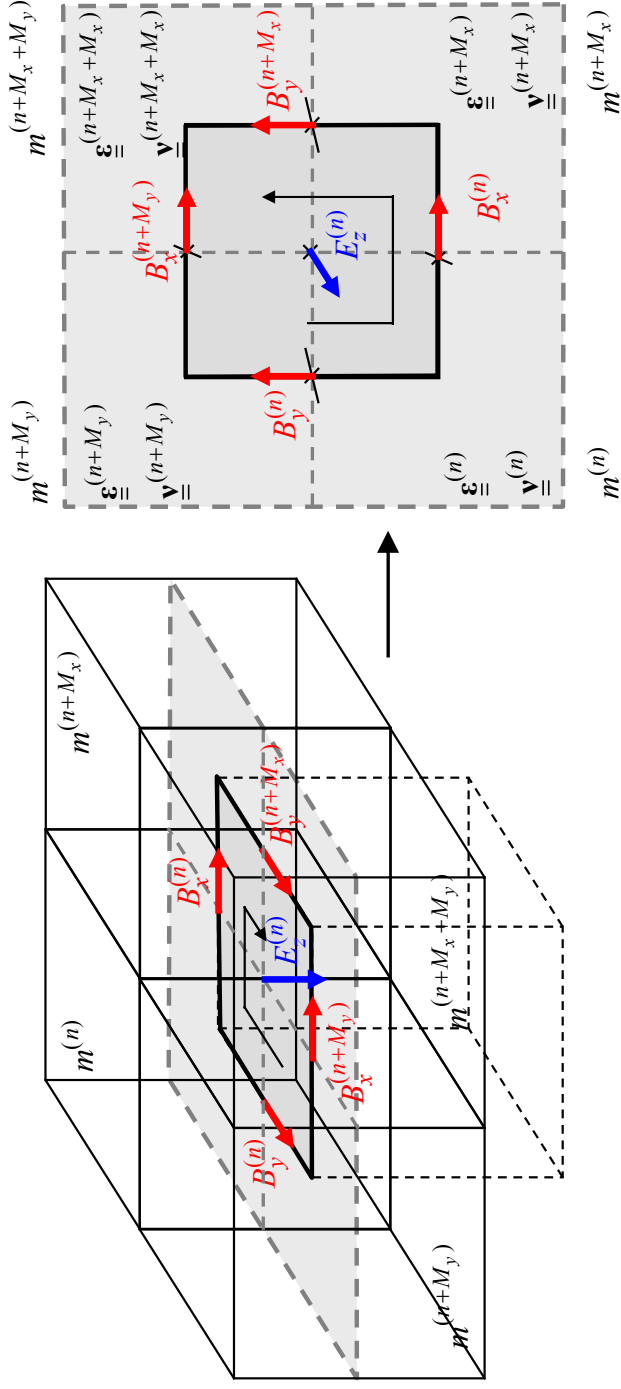
$I_{E_y^{(m)}}$  integration cell /  $I_{E_y^{(m)}}$  -Integrationszelle



### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

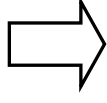
$$\frac{d}{dt} \iint_S [\underline{\boldsymbol{\varepsilon}}(\mathbf{R}) \cdot \underline{\mathbf{E}}(\mathbf{R}, t)] \cdot d\underline{\mathbf{S}} = \oint_{C=\partial S} [\underline{\mathbf{v}}(\mathbf{R}) \cdot \underline{\mathbf{B}}(\mathbf{R}, t)] \cdot d\underline{\mathbf{R}} - \iint_S \underline{\mathbf{j}}_e(\mathbf{R}, t) \cdot d\underline{\mathbf{S}}$$

$I_{E_z^{(m)}}$  integration cell /  $I_{E_z^{(m)}}$  - Integrationszelle



### 3-D FIT – Derivation of the Discrete Grid Equations / 3D-FIT – Ableitung der diskreten Gittergleichungen

$$\frac{d}{dt} \iint_S [\underline{\varepsilon}(\mathbf{R}, t)] \cdot \underline{dS} = \oint_{C=\partial S} [\underline{v}(\mathbf{R}, t) \cdot \underline{B}(\mathbf{R}, t)] \cdot \underline{dR} - \iint_S \underline{J}_e(\mathbf{R}, t) \cdot \underline{dS}$$



$$\begin{aligned} \tilde{\varepsilon}_{xx}^{(n)} \frac{d}{dt} E_x^{(n)} \Delta y \Delta z &= \tilde{v}_{yy}^{(n)} B_y^{(n)}(t) \Delta y - \tilde{v}_{yy}^{(n+M_z)} B_y^{(n+M_z)}(t) \Delta y \\ &\quad + \tilde{v}_{zz}^{(n+M_y)} B_z^{(n+M_y)}(t) \Delta z - \tilde{v}_{zz}^{(n)} B_z^{(n)}(t) \Delta z - J_{ex}^{(n)}(t) \Delta y \Delta z \\ &= (I - S_{M_z}) \tilde{v}_{yy}^{(n)} B_y^{(n)}(t) \Delta y + (S_{M_y} - I) \tilde{v}_{zz}^{(n)} B_z^{(n)}(t) \Delta z - J_{ex}^{(n)}(t) \Delta y \Delta z \\ \tilde{\varepsilon}_{yy}^{(n)} \frac{d}{dt} E_y^{(n)} \Delta x \Delta z &= \tilde{v}_{xx}^{(n+M_z)} B_x^{(n+M_z)}(t) \Delta x - \tilde{v}_{xx}^{(n)} B_x^{(n)}(t) \Delta x \\ &\quad + \tilde{v}_{zz}^{(n)} B_z^{(n)}(t) \Delta z - \tilde{v}_{zz}^{(n+M_x)} B_z^{(n+M_x)}(t) \Delta z - J_{ey}^{(n)}(t) \Delta x \Delta z \\ &= (S_{M_z} - I) \tilde{v}_{xx}^{(n)} B_x^{(n)}(t) \Delta x + (I - S_{M_x}) \tilde{v}_{zz}^{(n)} B_z^{(n)}(t) \Delta z - J_{ey}^{(n)}(t) \Delta x \Delta z \\ \tilde{\varepsilon}_{zz}^{(n)} \frac{d}{dt} E_z^{(n)} \Delta x \Delta y &= \tilde{v}_{xx}^{(n)} B_x^{(n)}(t) \Delta x - \tilde{v}_{xx}^{(n+M_y)} B_x^{(n+M_y)}(t) \Delta x \\ &\quad + \tilde{v}_{yy}^{(n+M_x)} B_y^{(n+M_x)}(t) \Delta y - \tilde{v}_{yy}^{(n)} B_y^{(n)}(t) \Delta y - J_{ez}^{(n)}(t) \Delta x \Delta y \\ &= (I - S_{M_y}) \tilde{v}_{xx}^{(n)} B_x^{(n)}(t) \Delta x + (S_{M_x} - I) \tilde{v}_{yy}^{(n)} B_y^{(n)}(t) \Delta y - J_{ez}^{(n)}(t) \Delta x \Delta y \end{aligned}$$

### 3-D FIT – ... Discrete Grid Equations in Local Matrix Form / 3D-FIT – ... diskreten Gittergleichungen in lokaler Matrixform

$$\begin{aligned}
 & \underbrace{\begin{bmatrix} \tilde{\varepsilon}_{xx}^{(n)} \\ \tilde{\varepsilon}_{yy}^{(n)} \\ \tilde{\varepsilon}_{zz}^{(n)} \end{bmatrix}}_{=[\tilde{\varepsilon}]^{(n)}} \underbrace{\begin{bmatrix} \Delta y \Delta z \\ \Delta x \Delta z \\ \Delta x \Delta y \end{bmatrix}}_{=[S]} \frac{d}{dt} \underbrace{\begin{bmatrix} E_x^{(n)}(t) \\ E_y^{(n)}(t) \\ E_z^{(n)}(t) \end{bmatrix}}_{=[E]^{(n)}(t)} \\
 & = \underbrace{\begin{bmatrix} 0 & I - S_{M_z} & S_{M_y} - I \\ S_{M_z} - I & 0 & i - S_{M_x} \\ I - S_{M_y} & S_{M_x} - I & 0 \end{bmatrix}}_{=[\text{curl}]} \underbrace{\begin{bmatrix} \tilde{V}_{xx}^{(n)} \\ \tilde{V}_{yy}^{(n)} \\ \tilde{V}_{zz}^{(n)} \end{bmatrix}}_{=[V]^{(n)}} \underbrace{\begin{bmatrix} \Delta x \\ \Delta y \\ \Delta z \end{bmatrix}}_{=[R]} \underbrace{\begin{bmatrix} B_x^{(n)}(t) \\ B_y^{(n)}(t) \\ B_z^{(n)}(t) \end{bmatrix}}_{=[B]^{(n)}(t)} - \underbrace{\begin{bmatrix} \Delta y \Delta z \\ \Delta x \Delta z \\ \Delta x \Delta y \end{bmatrix}}_{=[S]} \underbrace{\begin{bmatrix} J_{\text{ex}}^{(n)}(t) \\ J_{\text{ex}}^{(n)}(t) \\ J_{\text{ex}}^{(n)}(t) \end{bmatrix}}_{=[J_e]^{(n)}(t)}
 \end{aligned}$$
  

$$\begin{bmatrix} 0 & I - S_{M_z} & S_{M_y} - I \\ S_{M_z} - I & 0 & i - S_{M_x} \\ I - S_{M_y} & S_{M_x} - I & 0 \end{bmatrix} = \begin{bmatrix} 0 & -P_{M_z} & P_{M_y} \\ P_{M_z} & 0 & -P_{M_x} \\ -P_{M_y} & P_{M_x} & 0 \end{bmatrix} = [\text{curl}]$$

# 3-D FIT – ... Discrete Grid Equations in Local Matrix Form / 3D-FIT – ... diskreten Gittergleichungen in lokaler Matrixform

$$\underbrace{\begin{bmatrix} \tilde{\varepsilon}_{xx}^{(n)} \\ \tilde{\varepsilon}_{yy}^{(n)} \\ \tilde{\varepsilon}_{zz}^{(n)} \end{bmatrix}}_{=[\tilde{\varepsilon}]} \underbrace{\begin{bmatrix} \Delta y \Delta z \\ \Delta x \Delta z \\ \Delta x \Delta y \end{bmatrix}}_{=[S]} = \underbrace{\frac{d}{dt} \begin{bmatrix} E_x^{(n)}(t) \\ E_y^{(n)}(t) \\ E_z^{(n)}(t) \end{bmatrix}}_{=[\dot{E}]} \underbrace{\begin{bmatrix} P_{M_z} & -P_{M_x} & 0 \\ -P_{M_y} & 0 & P_{M_x} \\ 0 & -P_{M_z} & -P_{M_y} \end{bmatrix}}_{=[\text{curl}]} \underbrace{\begin{bmatrix} \tilde{v}_{xx}^{(n)} \\ \tilde{v}_{yy}^{(n)} \\ \tilde{v}_{zz}^{(n)} \end{bmatrix}}_{=[\tilde{v}]} \underbrace{\begin{bmatrix} \Delta x & & \\ & \Delta y & \\ & & \Delta z \end{bmatrix}}_{=[R]} \underbrace{\begin{bmatrix} B_x^{(n)}(t) \\ B_y^{(n)}(t) \\ B_z^{(n)}(t) \end{bmatrix}}_{=[B]} - \underbrace{\begin{bmatrix} \Delta y \Delta z \\ \Delta x \Delta z \\ \Delta x \Delta y \end{bmatrix}}_{=[S]} \underbrace{\begin{bmatrix} J_{ex}^{(n)}(t) \\ J_{ey}^{(n)}(t) \\ J_{ez}^{(n)}(t) \end{bmatrix}}_{=[J_e]}$$

$$[\tilde{\varepsilon}]^{(n)} [\dot{S}] \frac{d}{dt} \{E\}^{(n)}(t) = [\text{curl}] [\tilde{v}]^{(n)} [R] \{B\}^{(n)}(t) - [S] \{J_e\}^{(n)}(t)$$

- $[\tilde{\varepsilon}]^{(n)} \in \mathbb{R}^{3 \times 3}$  Diagonal matrix of permittivities on the grid  $\tilde{G}$  /  
Diagonalmatrix der Permittivitäten auf dem Gitter  $\tilde{G}$
- $[\dot{S}] \in \mathbb{R}^{3 \times 3}$  Diagonal matrix of elementary surfaces on the grid  $\tilde{G}$  /  
Diagonalmatrix der Elementarflächen auf dem Gitter  $\tilde{G}$
- $\{E\}^{(n)}(t) \in \mathbb{R}^3$  Algebraic electric field strength vector /  
Algebraischer elektrischer Feldstärkevektor
- $[\text{curl}] \in \mathbb{R}^{3 \times 3}$  Topological curl operator in matrix form on the grid  $\tilde{G}$  /  
Topologischer Rotationsoperator in Matrixform auf dem Gitter  $\tilde{G}$
- $[\tilde{v}]^{(n)} \in \mathbb{R}^{3 \times 3}$  Diagonal matrix of impermeabilities on the grid  $\tilde{G}$  /  
Diagonalmatrix der Impermeabilitäten auf dem Gitter  $\tilde{G}$
- $[\tilde{R}] \in \mathbb{R}^{3 \times 3}$  Diagonal matrix of elementary lines on the grid  $\tilde{G}$  /  
Diagonalmatrix der Elementarstrecken auf dem Gitter  $\tilde{G}$
- $\{B\}^{(n)}(t) \in \mathbb{R}^3$  Algebraic magnetic flux density vector /  
Algebraischer magnetischer Flussdichtevektor
- $\{J_e\}^{(n)}(t) \in \mathbb{R}^3$  Algebraic electric current density vector /  
Algebraischer elektrischer Stromdichtevektor

### 3-D FIT – ... Discrete Grid Equations in Local and Global Matrix Form / 3D-FIT – ... diskreten Gittergleichungen in lokaler und globaler Matrixform

Maxwell's equations in integral form /  
Maxwell'sche Gleichungen in Integralform

$$\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = - \oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_S \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

$$\frac{d}{dt} \iint_S \underline{\boldsymbol{\varepsilon}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}} = \oint_{C=\partial S} \underline{\mathbf{v}}(\underline{\mathbf{R}}) \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}} - \iint_S \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

Discrete grid equations in local matrix form / Diskrete Gittergleichungen in lokaler Matrixform

$$[S] \frac{d}{dt} \{B\}^{(n)}(t) = - [\text{curl}] [R] \{E\}^{(n)}(t) - [S] \{J_m\}^{(n)}(t)$$

$$[\boldsymbol{\varepsilon}]^{(n)} [\widetilde{S}] \frac{d}{dt} \{E\}^{(n)}(t) = [\widetilde{\text{curl}}] [\widetilde{v}]^{(n)} [R] \{B\}^{(n)}(t) - [\widetilde{S}] \{J_e\}^{(n)}(t)$$

Discrete grid equations in global matrix form / Diskrete Gittergleichungen in globaler Matrixform

$$[S] \frac{d}{dt} \{\mathbf{B}\}(t) = - [\text{curl}] [\mathbf{R}] \{\mathbf{E}\}(t) - [S] \{\mathbf{J}_m\}(t)$$

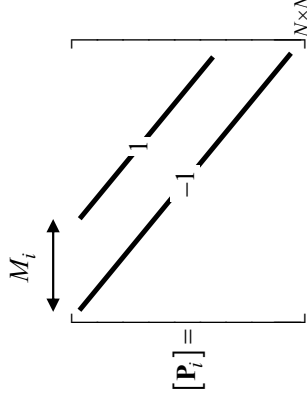
$$[\boldsymbol{\varepsilon}] [\widetilde{S}] \frac{d}{dt} \{\mathbf{E}\}(t) = [\widetilde{\text{curl}}] [\widetilde{v}] [\mathbf{R}] \{\mathbf{B}\}(t) - [\widetilde{S}] \{\mathbf{J}_e\}(t)$$



## Elementary Difference Matrix $[P_i]$ (P Matrix) (...) / Elementare Differenzmatrix $[P_i]$ (P-Matrix) (...)

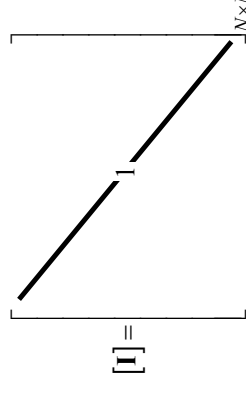
The P matrix can be represented by a sum of an identity matrix  $[I]$  and a band matrix  $[B]$  /  
Die P-Matrix kann als Summe aus einer Einheitsmatrix (Identitätsmatrix)  $[I]$  und Bandmatrix  $[B]$  dargestellt werden

$$[P_{\pm i}] := \mp [I] \pm [B_{\pm i}], \quad i = \{x, y, z\}$$



Identity matrix / Einheitsmatrix (Identitätsmatrix)

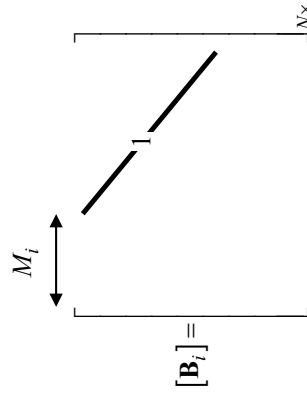
$$([I])_{ij} = \delta_{ij} \quad i, j \in \{1, 2, \dots, N\}$$



Band matrix / Bandmatrix

$$([B_{\pm i}]_{jk}) = \begin{cases} 1 & j = k \mp M_i \text{ or / bzw. } k = j \pm M_i \\ 0 & \text{else / sonst} \end{cases}$$

$$i = x, y, z; \quad j, k \in \{1, 2, \dots, N\}$$

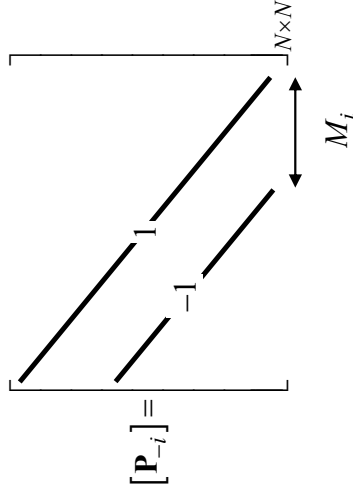
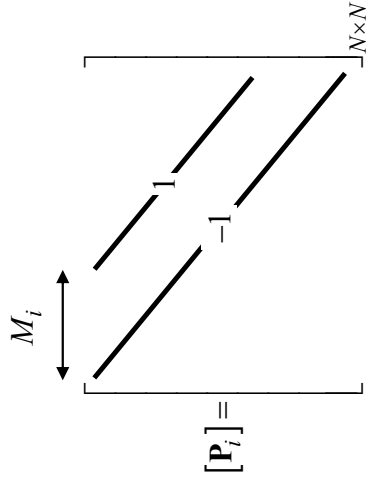


## Properties of the Difference Matrix $[P_i]$ (P Matrix) / Eigenschaften der Differenzmatrix $[P_i]$ (P-Matrix)

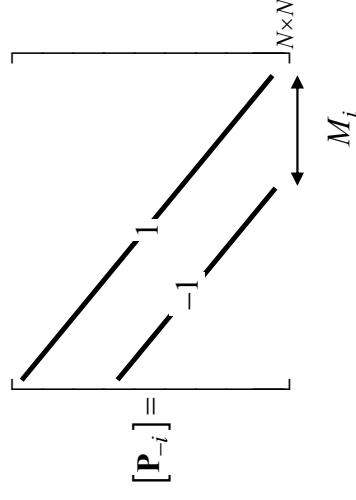
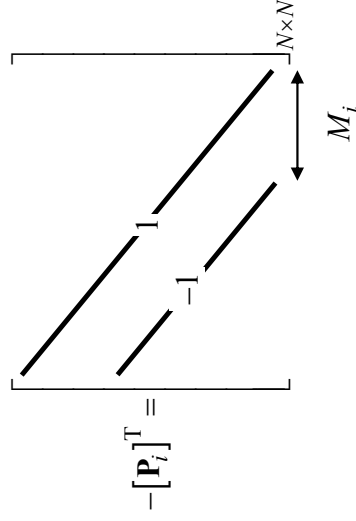
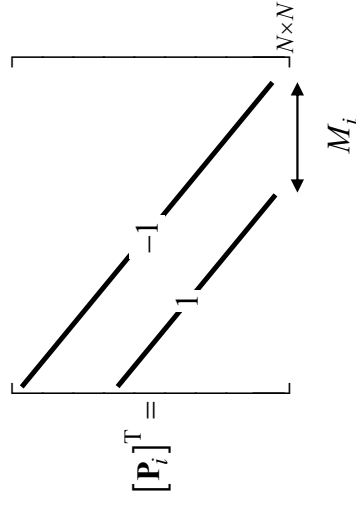
$$[P_{\pm i}] := \mp [I] \pm [B_{\pm i}], \quad i = \{x, y, z\}$$

$$[P_i] := -[I] + [B_i], \quad i = \{x, y, z\}$$

$$[P_{-i}] := [I] - [B_{-i}], \quad i = \{x, y, z\}$$



Property / Eigenschaft  $-[P_i]^T = [P_{-i}]$



## Discrete Global Gradient, Divergence, and Curl Operator / Diskreter globaler Gradienten-, Divergenz- und Rotationsoperator

Discrete gradient operator /  
Diskreter Gradientenoperator

$$[\mathbf{grad}] = \begin{bmatrix} -[\mathbf{P}_x]^T \\ -[\mathbf{P}_y]^T \\ -[\mathbf{P}_z]^T \end{bmatrix}_{3N \times N}$$

$$\widetilde{[\mathbf{grad}]} = \begin{bmatrix} [\mathbf{P}_x] \\ [\mathbf{P}_y] \\ [\mathbf{P}_z] \end{bmatrix}_{3N \times N}$$

Discrete curl operator /  
Diskreter Rotationsoperator

$$[\mathbf{curl}] = \begin{bmatrix} [\mathbf{0}] & [\mathbf{P}_z]^T & -[\mathbf{P}_y]^T \\ -[\mathbf{P}_z]^T & [\mathbf{0}] & [\mathbf{P}_x]^T \\ [\mathbf{P}_y]^T & -[\mathbf{P}_x]^T & [\mathbf{0}] \end{bmatrix}_{3N \times 3N}$$

$$\widetilde{[\mathbf{curl}]} = \begin{bmatrix} [\mathbf{0}] & -[\mathbf{P}_z] & [\mathbf{P}_y] \\ [\mathbf{P}_z] & [\mathbf{0}] & -[\mathbf{P}_x] \\ -[\mathbf{P}_y] & [\mathbf{P}_x] & [\mathbf{0}] \end{bmatrix}_{3N \times 3N}$$

Discrete divergence operator /  
Diskreter Divergenzoperator

$$[\mathbf{div}] := \begin{bmatrix} -[\mathbf{P}_x]^T, -[\mathbf{P}_y]^T, -[\mathbf{P}_z]^T \end{bmatrix}_{N \times 3N}$$

$$\widetilde{[\mathbf{div}]} := \begin{bmatrix} [\mathbf{P}_x], [\mathbf{P}_y], [\mathbf{P}_z] \end{bmatrix}_{N \times 3N}$$

The matrix operators /  
Die Matrixoperatoren

$$\begin{bmatrix} \mathbf{grad} \\ \mathbf{div} \\ \mathbf{curl} \end{bmatrix}$$

are **global** matrix operators /  
sind **globale** Matrixoperatoren

## Properties of the Global Matrix Operators / Eigenschaften der globalen Matrixoperatoren

Some properties of the global matrix operators of the dual grid system /  
Einige Eigenschaften der globalen Matrixoperatoren des dualen Gittersystems

$$\begin{aligned} -\widetilde{[\text{div}]} &= [\text{grad}]^T \\ \widetilde{[\text{grad}]}^T &= [\text{div}] \\ [\text{curl}] &= \widetilde{[\text{curl}]}^T \end{aligned}$$

Conservation of important vector identities /  
Erhaltung von wichtigen Vektoridentitäten

Vector identities /  
Vektoridentitäten

$$\begin{aligned} \text{curl grad} &= \nabla \times \nabla = \underline{\mathbf{0}} \\ \text{div curl} &= \nabla \cdot \nabla = 0 \end{aligned}$$



$$\begin{aligned} [\text{curl}][\text{grad}] &= [\mathbf{0}] \\ \widetilde{[\text{curl}]}[\widetilde{\text{grad}}] &= [\mathbf{0}] \\ [\text{div}][\text{curl}] &= [\mathbf{0}] \\ \widetilde{[\text{div}]}[\widetilde{\text{curl}}] &= [\mathbf{0}] \end{aligned}$$

are conserved in the dual grid system /  
bleiben im dualen Gittersystem erhalten

## Properties of the Global Matrix Operators / Eigenschaften der globalen Matrixoperatoren

Consistency test / Konsistenztest

$$\begin{aligned} \underbrace{[\text{curl}]}_{\text{grad}} &= \begin{bmatrix} [0] & -[\mathbf{P}_z] & [\mathbf{P}_y] \\ [\mathbf{P}_z] & [0] & -[\mathbf{P}_x] \\ -[\mathbf{P}_y] & [\mathbf{P}_x] & [0] \end{bmatrix} \begin{bmatrix} [\mathbf{P}_x] \\ [\mathbf{P}_y] \\ [\mathbf{P}_z] \end{bmatrix} \\ &= \begin{bmatrix} [\mathbf{P}_y][\mathbf{P}_z] - [\mathbf{P}_z][\mathbf{P}_y] \\ [\mathbf{P}_z][\mathbf{P}_x] - [\mathbf{P}_x][\mathbf{P}_z] \\ [\mathbf{P}_x][\mathbf{P}_y] - [\mathbf{P}_y][\mathbf{P}_x] \end{bmatrix} \end{aligned}$$

$$\begin{aligned} [\mathbf{P}_i][\mathbf{P}_j] - [\mathbf{P}_j][\mathbf{P}_i] &= (-[\mathbf{I}] + [\mathbf{B}_i])(-[\mathbf{I}] + [\mathbf{B}_j]) - (-[\mathbf{I}] + [\mathbf{B}_j])(-[\mathbf{I}] + [\mathbf{B}_i]) \\ &= (-[\mathbf{I}][\mathbf{I}] - [\mathbf{I}][\mathbf{B}_j] - [\mathbf{B}_i][\mathbf{I}] + [\mathbf{B}_i][\mathbf{B}_j]) \\ &\quad - (-[\mathbf{I}][\mathbf{I}] - [\mathbf{I}][\mathbf{B}_i] - [\mathbf{B}_j][\mathbf{I}] + [\mathbf{B}_j][\mathbf{B}_i]) \\ &= (-[\mathbf{I}] - [\mathbf{B}_j] - [\mathbf{B}_i] + [\mathbf{B}_j][\mathbf{B}_i]) \\ &\quad - (-[\mathbf{I}] - [\mathbf{B}_i] - [\mathbf{B}_j] + [\mathbf{B}_j][\mathbf{B}_i]) \\ &= -[\mathbf{I}] - [\mathbf{B}_j] - [\mathbf{B}_i] + [\mathbf{B}_j][\mathbf{B}_i] + [\mathbf{I}] + [\mathbf{B}_j] + [\mathbf{B}_i] - [\mathbf{B}_j][\mathbf{B}_i] \\ &= [\mathbf{B}_i][\mathbf{B}_j] - [\mathbf{B}_j][\mathbf{B}_i] \end{aligned}$$

## Properties of the Global Matrix Operators / Eigenschaften der globalen Matrixoperatoren

With the property /  
Mit der Eigenschaft

$$([\mathbf{B}_{\pm i}][\mathbf{B}_{\pm j}])_{kl} = \begin{cases} 1 & k = l \mp M_i \mp M_j \\ 0 & \text{else / sonst} \end{cases}$$



$i$  and  $j$  can be arbitrarily interchanged /  
 $i$  und  $j$  können beliebig vertauscht werden



This means that the matrices  $[\mathbf{B}_{\pm i}]$  and  $[\mathbf{B}_{\pm j}]$   
Das bedeutet, dass die Matrizen  
as well as  $[\mathbf{P}_{\pm i}]$  and  $[\mathbf{P}_{\pm j}]$   
als auch  $[\mathbf{P}_{\pm i}]$  und  $[\mathbf{P}_{\pm j}]$

are commutative!  
kommutativ sind!



$$[\mathbf{B}_{\pm i}][\mathbf{B}_{\pm j}] = [\mathbf{B}_{\pm j}][\mathbf{B}_{\pm i}]$$



$$\begin{aligned} \widetilde{\text{curl}}[\mathbf{grad}] &= [\mathbf{P}_i][\mathbf{P}_j] - [\mathbf{P}_j][\mathbf{P}_i] \\ &= [\mathbf{B}_i][\mathbf{B}_j] - [\mathbf{B}_j][\mathbf{B}_i] \\ &= [\mathbf{B}_i][\mathbf{B}_j] - [\mathbf{B}_i][\mathbf{B}_j] \\ &= [\mathbf{0}] \end{aligned}$$

$$[\mathbf{P}_{\pm i}][\mathbf{P}_{\pm j}] = [\mathbf{P}_{\pm j}][\mathbf{P}_{\pm i}]$$

**End of Lecture 6 /  
Ende der 6. Vorlesung**