

Elektromagnetische Feldtheorie I (EFT I) / Electromagnetic Field Theory I (EFT I)

4th Lecture / 4. Vorlesung

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Exam EFT I / Prüfung EFT I

2511 Elektromagnetische Feldtheorie
23.09.2003, 14:00, R 1603

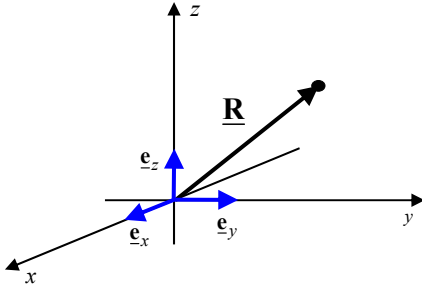
Metric Coefficients / Metrische Koeffizienten

Cartesian Coordinates / Kartesische Koordinaten

$$x, y, z = x_1, x_2, x_3$$

$$\underline{e}_x, \underline{e}_y, \underline{e}_z = \underline{e}_{x_1}, \underline{e}_{x_2}, \underline{e}_{x_3}$$

$$\underline{e}_x \perp \underline{e}_y \perp \underline{e}_z ; \underline{e}_{x_1} \perp \underline{e}_{x_2} \perp \underline{e}_{x_3}$$

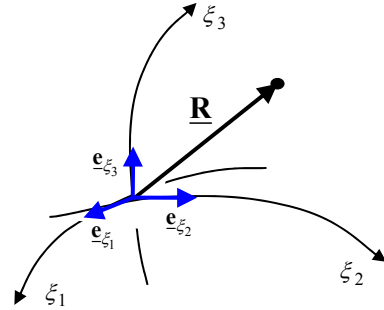


Orthogonal Curvilinear Coordinates / Orthogonale Krummlinige Koordinaten

$$\zeta_1, \zeta_2, \zeta_3$$

$$\underline{e}_{\zeta_1}, \underline{e}_{\zeta_2}, \underline{e}_{\zeta_3}$$

$$\underline{e}_{\zeta_1} \perp \underline{e}_{\zeta_2} \perp \underline{e}_{\zeta_3}$$



$$x = x(\zeta_1, \zeta_2, \zeta_3)$$

$$y = y(\zeta_1, \zeta_2, \zeta_3)$$

$$z = z(\zeta_1, \zeta_2, \zeta_3)$$

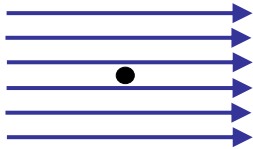
Cartesian Coordinates / Kartesische Koordinaten

$$\zeta_1 = \zeta_1(x, y, z)$$

$$\zeta_2 = \zeta_2(x, y, z)$$

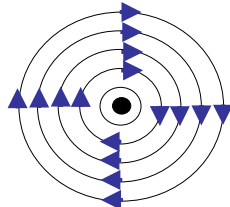
$$\zeta_3 = \zeta_3(x, y, z)$$

Div and Curl Examples / Div und Rot Beispiele



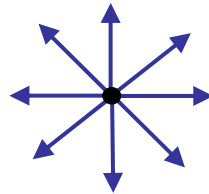
$$\text{div } \underline{A} = \nabla \cdot \underline{A} = 0$$

$$\text{curl/rot } \underline{A} = \nabla \times \underline{A} = \underline{0}$$



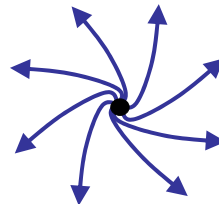
$$\text{div } \underline{A} = \nabla \cdot \underline{A} = 0$$

$$\text{curl/rot } \underline{A} = \nabla \times \underline{A} \neq \underline{0}$$



$$\text{div } \underline{A} = \nabla \cdot \underline{A} \neq 0$$

$$\text{curl/rot } \underline{A} = \nabla \times \underline{A} = \underline{0}$$



$$\text{div } \underline{A} = \nabla \cdot \underline{A} \neq 0$$

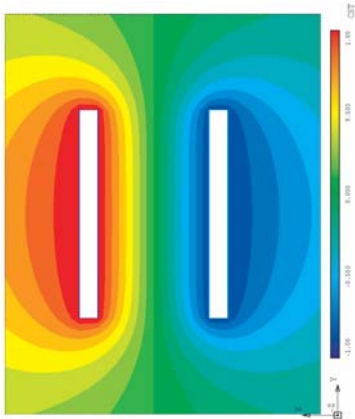
$$\text{curl/rot } \underline{A} = \nabla \times \underline{A} \neq \underline{0}$$

Grad, Div and Curl Examples / Grad, Div und Rot Beispiele

Scalar Field / Skalarfeld

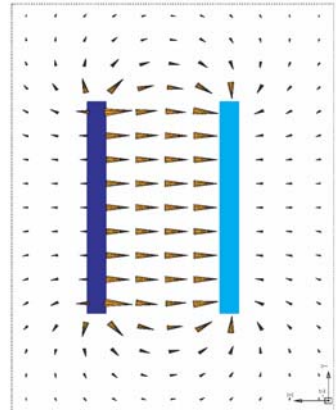
$$\Phi_e(\mathbf{R})$$

$$\text{grad } \Phi_e(\mathbf{R}) = \nabla \Phi_e(\mathbf{R}) = \mathbf{e}_x \frac{\partial}{\partial x} \Phi_e(x, y, z) + \mathbf{e}_y \frac{\partial}{\partial y} \Phi_e(x, y, z) + \mathbf{e}_z \frac{\partial}{\partial z} \Phi_e(x, y, z)$$



Vektor Field / Vektorfeld

$$\underline{\mathbf{E}}(\mathbf{R}) = -\text{grad } \Phi_e(\mathbf{R}) = -\nabla \Phi_e(\mathbf{R})$$

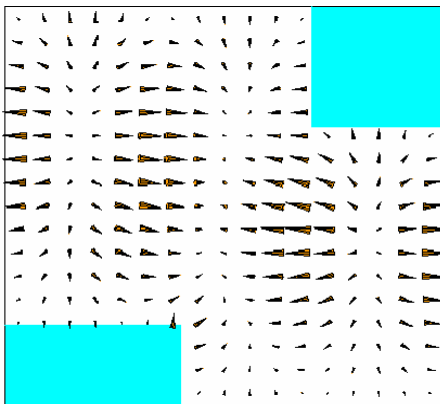


Grad, Div and Curl Examples / Grad, Div und Rot Beispiele

Vector Field / Vektorfeld

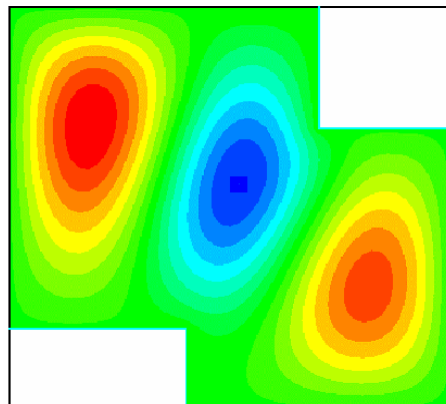
$$\underline{\mathbf{D}}(\mathbf{R})$$

$$\text{div } \underline{\mathbf{D}}(\mathbf{R}) = \nabla \cdot \underline{\mathbf{D}}(\mathbf{R}) = \frac{\partial}{\partial x} D_x(x, y, z) + \frac{\partial}{\partial y} D_y(x, y, z) + \frac{\partial}{\partial z} D_z(x, y, z)$$



Scalar Field / Skalarfeld

$$\rho_e(\mathbf{R}) = \text{div } \underline{\mathbf{D}}(\mathbf{R}) = \nabla \cdot \underline{\mathbf{D}}(\mathbf{R})$$

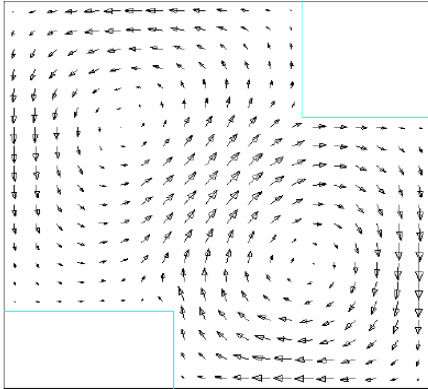


Grad, Div and Curl Examples / Grad, Div und Rot Beispiele

Vector Field / Vektorfeld

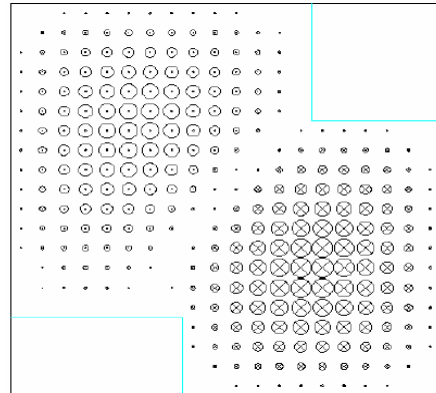
$$\underline{\mathbf{E}}(\underline{\mathbf{R}}, t)$$

$$\text{curl/rot } \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) = \nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) = \left(\mathbf{e}_x \frac{\partial}{\partial x} + \mathbf{e}_y \frac{\partial}{\partial y} + \mathbf{e}_z \frac{\partial}{\partial z} \right) \times \underline{\mathbf{E}}(x, y, z, t)$$



Vector Field / Vektorfeld

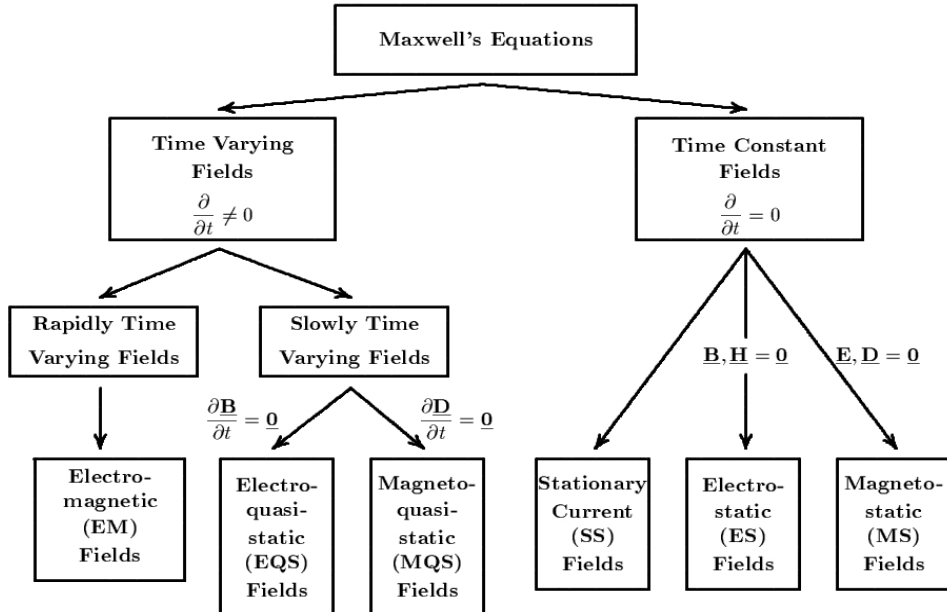
$$\text{curl/rot } \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) = \nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) = -\frac{\partial}{\partial t} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t)$$



Classification of Maxwell's Equations / Klassifikation der Maxwell'schen Gleichungen (1)

- Time Varying Electromagnetic Fields /
Zeitveränderliche elektromagnetische Felder
 - Rapidly Time Varying Fields /
Zeitlich schnell veränderliche Felder
 - Electromagnetic (EM) Fields /
Elektromagnetische (EM) Felder
 - Slowly Time Varying Fields /
Zeitlich langsam veränderliche Felder
 - Electroquasistatic Fields (EQS) /
Elektroquasistatische Felder (EQS)
 - Magnetoquasistatic Fields (MQS) /
Magnetoquasistatische Felder (MQS)
- Time Constant Electromagnetic Fields /
Zeitlich konstante elektromagnetische Felder
 - Stationary Current (SC) Fields /
Stationäre Strömungsfelder (SS)
 - Electrostatic (ES) Fields / Elektrostatische (ES) Felder
 - Magnetostatic (MS) Fields / Magnetostatische (MS) Felder

Classification of Maxwell's Equations / Klassifikation der Maxwell'schen Gleichungen (2)



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Classification ... / Klassifikation ... (3)

Rapidly Time Varying Electromagnetic (EM) Fields / Zeitlich schnell veränderliche elektromagnetische (EM) Felder

Governing Equations in Integral Form /
Grundgleichungen in Integralform

$$\oint_{C=\partial S} \mathbf{E}(\mathbf{R}, t) \cdot d\mathbf{R} = - \iint_S \frac{\partial}{\partial t} \mathbf{B}(\mathbf{R}, t) \cdot d\mathbf{S} - \iint_S \mathbf{J}_m(\mathbf{R}, t) \cdot d\mathbf{S}$$

$$\oint_{C=\partial S} \mathbf{H}(\mathbf{R}, t) \cdot d\mathbf{R} = \iint_S \frac{\partial}{\partial t} \mathbf{D}(\mathbf{R}, t) \cdot d\mathbf{S} + \iint_S \mathbf{J}_c(\mathbf{R}, t) \cdot d\mathbf{S}$$

$$\oiint_{S=\partial V} \mathbf{D}(\mathbf{R}, t) \cdot d\mathbf{S} = \iiint_V \rho_c(\mathbf{R}, t) dV$$

$$\oiint_{S=\partial V} \mathbf{B}(\mathbf{R}, t) \cdot d\mathbf{S} = \iiint_V \rho_m(\mathbf{R}, t) dV$$

$$\oiint_{S=\partial V} \mathbf{J}_c(\mathbf{R}, t) \cdot d\mathbf{S} = - \iiint_V \frac{\partial}{\partial t} \rho_c(\mathbf{R}, t) dV$$

$$\oiint_{S=\partial V} \mathbf{J}_m(\mathbf{R}, t) \cdot d\mathbf{S} = - \iiint_V \frac{\partial}{\partial t} \rho_m(\mathbf{R}, t) dV$$

Governing Equations in Differential Form /
Grundgleichungen in Differentialform

$$\nabla \times \mathbf{E}(\mathbf{R}, t) = - \frac{\partial}{\partial t} \mathbf{B}(\mathbf{R}, t) - \mathbf{J}_m(\mathbf{R}, t)$$

$$\nabla \times \mathbf{H}(\mathbf{R}, t) = \frac{\partial}{\partial t} \mathbf{D}(\mathbf{R}, t) + \mathbf{J}_c(\mathbf{R}, t)$$

$$\nabla \cdot \mathbf{D}(\mathbf{R}, t) = \rho_c(\mathbf{R}, t)$$

$$\nabla \cdot \mathbf{B}(\mathbf{R}, t) = \rho_m(\mathbf{R}, t)$$

$$\nabla \cdot \mathbf{J}_c(\mathbf{R}, t) = - \frac{\partial}{\partial t} \rho_c(\mathbf{R}, t)$$

$$\nabla \cdot \mathbf{J}_m(\mathbf{R}, t) = - \frac{\partial}{\partial t} \rho_m(\mathbf{R}, t)$$

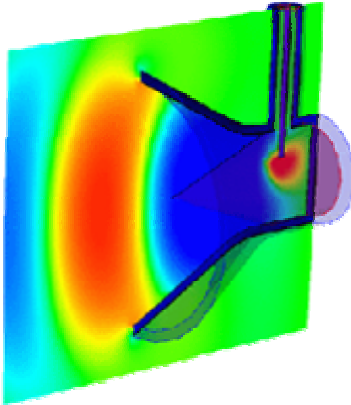
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Classification ... / Klassifikation ... (4)

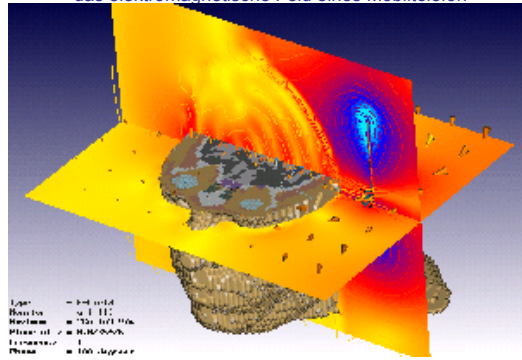
Rapidly Time Varying Electromagnetic (EM) Fields: Examples / Zeitlich schnell veränderliche elektromagnetische (EM) Felder: Beispiele

Horn Antenna: Contour Plot of Electric Field Strength Vector (E_x Component) /
Hornantenne: Konturdarstellung des elektrischen Feldstärkevektors (E_x -Komponente)



(CST Microwave Studio, www.cst.de)

Biomedical Application: Human head model irradiated by the electromagnetic field of a mobile phone /
Biomedizinische Anwendung: Menschliches Kopfmodell bei Bestrahlung durch das elektromagnetische Feld eines Mobiltelefon



(CST Microwave Studio, www.cst.de)

Classification ... / Klassifikation ... (5)

Electroquasistatic (EQS) Fields / Elektroquasistatische (EQS) Felder

$$\frac{\partial \mathbf{B}(\mathbf{R}, t)}{\partial t} = \mathbf{0} \quad (\mathbf{J}_m(\mathbf{R}, t) = \mathbf{0})$$

(Neglect Magnetic Induction /
Vernachlässige magnetische Induktion)

With the typical length L / Mit der Typischen Länge L

$$L \ll \lambda_{em} = cT$$

Governing Equations in Integral Form / Grundgleichungen in Integralform

$$\oint_{C=\partial S} \mathbf{E}(\mathbf{R}, t) \cdot d\mathbf{R} = 0$$

$$\oint_{S=\partial V} \mathbf{D}(\mathbf{R}, t) \cdot d\mathbf{S} = \iiint_V \rho_c(\mathbf{R}, t) dV$$

$$\oint_{S=\partial V} \mathbf{J}_c(\mathbf{R}, t) \cdot d\mathbf{S} = -\iiint_V \frac{\partial}{\partial t} \rho_c(\mathbf{R}, t) dV$$

Governing Equations in Differential Form / Grundgleichungen in Differentialform

$$\nabla \times \mathbf{E}(\mathbf{R}, t) = \mathbf{0}$$

$$\nabla \cdot \mathbf{D}(\mathbf{R}, t) = \rho_c(\mathbf{R}, t)$$

$$\nabla \cdot \mathbf{J}_c(\mathbf{R}, t) = -\frac{\partial}{\partial t} \rho_c(\mathbf{R}, t)$$

Magnetoquasistatic (MQS) Fields / Magnetoquasistatische (MQS) Felder

$$\frac{\partial \mathbf{D}(\mathbf{R}, t)}{\partial t} = \mathbf{0} \quad (\mathbf{J}_m(\mathbf{R}, t) = \mathbf{0})$$

(Neglect Displacement Current /
Vernachlässige Verschiebungsstrom)

λ_{em} : Electromagnetic Wavelength / Elektromagnetische Wellenlänge
 c : Propagation Velocity / Ausbreitungsgeschwindigkeit
 T : Length of Period / Periodenlänge

$$\oint_{C=\partial S} \mathbf{E}(\mathbf{R}, t) \cdot d\mathbf{R} = -\iint_S \frac{\partial}{\partial t} \mathbf{B}(\mathbf{R}, t) \cdot d\mathbf{S}$$

$$\oint_{C=\partial S} \mathbf{H}(\mathbf{R}, t) \cdot d\mathbf{R} = \iint_S \mathbf{J}_c(\mathbf{R}, t) \cdot d\mathbf{S}$$

$$\oint_{S=\partial V} \mathbf{B}(\mathbf{R}, t) \cdot d\mathbf{S} = 0$$

$$\oint_{S=\partial V} \mathbf{J}_c(\mathbf{R}, t) \cdot d\mathbf{S} = 0$$

$$\nabla \times \mathbf{E}(\mathbf{R}, t) = -\frac{\partial}{\partial t} \mathbf{B}(\mathbf{R}, t)$$

$$\nabla \times \mathbf{H}(\mathbf{R}, t) = \mathbf{J}_c(\mathbf{R}, t)$$

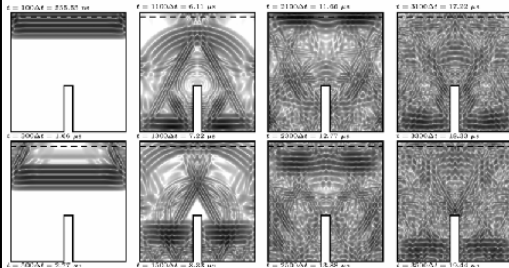
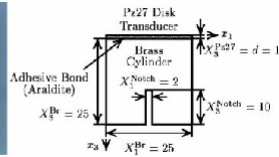
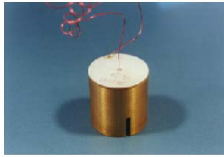
$$\nabla \cdot \mathbf{B}(\mathbf{R}, t) = 0$$

$$\nabla \cdot \mathbf{J}_c(\mathbf{R}, t) = 0$$

Classification ... / Klassifikation ... (6)

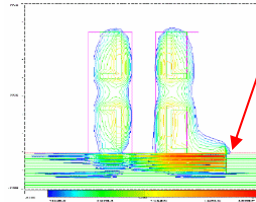
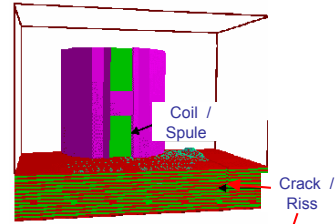
Electroquasistatic (EQS) Fields: Example / Elektroquasistatische (EQS) Felder: Beispiel

Non-Destructive Testing: Piezoelectric Sensor /
Zerstörungsfreie Materialprüfung: Piezoelektrischer Sensor



Magnetoquasistatic (MQS) Fields: Example / Magnetoquasistatische (MQS) Felder: Beispiel

Non-Destructive Testing: Eddy Current Sensor /
Zerstörungsfreie Materialprüfung: Wirbelstromsensor



Electric Energy Density / Elektrische Energiedichte

Classification ... / Klassifikation ... (7)

Stationary Electric Current (SEC) Fields / Stationäre elektrische Strömungsfelder (SEC) Felder

$$\frac{\partial}{\partial t} \{ \underline{E}, \underline{B}, \underline{H}, \underline{D}, \underline{J}_c, \underline{J}_m, \rho_c, \rho_m \} = \{ \underline{0}, 0 \}$$

$$\{ \underline{J}_m, \rho_m \} = \{ \underline{0}, 0 \}$$

$$\nabla \times \underline{E}(\underline{R}) = \underline{0}$$

$$\underline{J}_c(\underline{R}) = \underline{J}_{cc}(\underline{R}) = \sigma_c(\underline{R}) \underline{E}(\underline{R})$$

$$\nabla \cdot \underline{J}_c(\underline{R}, t) = 0$$

Governing Equations in Integral Form / Grundgleichungen in Integralform

$$\oint_{C=\partial S} \underline{E}(\underline{R}) \cdot d\underline{R} = 0$$

$$\oint_{C=\partial S} \underline{H}(\underline{R}) \cdot d\underline{R} = \iint_{S=\partial V} \underline{J}_c(\underline{R}) \cdot d\underline{S}$$

$$\iint_{S=\partial V} \underline{D}(\underline{R}) \cdot d\underline{S} = \iiint_V \rho_c(\underline{R}) dV$$

$$\iint_{S=\partial V} \underline{B}(\underline{R}) \cdot d\underline{S} = 0$$

Governing Equations in Differential Form / Grundgleichungen in Differentialform

$$\nabla \times \underline{E}(\underline{R}) = \underline{0}$$

$$\nabla \times \underline{H}(\underline{R}) = \underline{J}_{cc}(\underline{R})$$

$$\nabla \cdot \underline{D}(\underline{R}) = \rho_c(\underline{R})$$

$$\nabla \cdot \underline{J}_c(\underline{R}) = 0$$

Classification ... / Klassifikation ... (8)

**Electrostatic (ES) Fields /
Elektrostatistische (ES) Felder**

$$\frac{\partial}{\partial t} \{ \underline{\mathbf{E}}, \underline{\mathbf{D}}, \rho_c \} = \{ \underline{\mathbf{0}}, 0 \}$$

$$\{ \underline{\mathbf{B}}, \underline{\mathbf{H}}, \underline{\mathbf{J}}_e, \underline{\mathbf{J}}_m, \rho_m \} = \{ \underline{\mathbf{0}}, 0 \}$$

**Magnetostatic (MS) Fields /
Magnetostatistische (MS) Felder**

$$\frac{\partial}{\partial t} \{ \underline{\mathbf{H}}, \underline{\mathbf{B}}, \underline{\mathbf{J}}_e \} = \{ \underline{\mathbf{0}} \}$$

$$\{ \underline{\mathbf{E}}, \underline{\mathbf{D}}, \underline{\mathbf{J}}_m, \rho_c, \rho_m \} = \{ \underline{\mathbf{0}}, 0 \}$$

with / mit

$$\underline{\mathbf{J}}_e(\underline{\mathbf{R}}) = \underline{\mathbf{J}}_{ei}(\underline{\mathbf{R}})$$

Governing Equations in Integral Form / Grundgleichungen in Integralform

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{R}} = 0$$

$$\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{S}} = \iiint_V \rho_c(\underline{\mathbf{R}}) dV$$

$$\oint_{C=\partial S} \underline{\mathbf{H}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{R}} = \iint_S \underline{\mathbf{J}}_{ei}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{S}}$$

$$\oiint_{S=\partial V} \underline{\mathbf{B}}(\underline{\mathbf{R}}) \cdot d\underline{\mathbf{S}} = 0$$

Governing Equations in Differential Form / Grundgleichungen in Differentialform

$$\nabla \times \underline{\mathbf{E}}(\underline{\mathbf{R}}) = \underline{\mathbf{0}}$$

$$\nabla \cdot \underline{\mathbf{D}}(\underline{\mathbf{R}}) = \rho_c(\underline{\mathbf{R}})$$

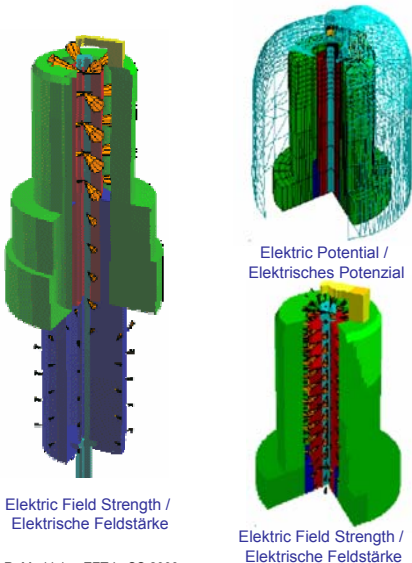
$$\nabla \times \underline{\mathbf{H}}(\underline{\mathbf{R}}) = \underline{\mathbf{J}}_{ei}(\underline{\mathbf{R}})$$

$$\nabla \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}) = 0$$

Classification ... / Klassifikation ... (9)

**Electrostatic (ES) Fields: Example /
Elektrostatistische (ES) Felder: Beispiel**

Spark Plug / Zündkerze

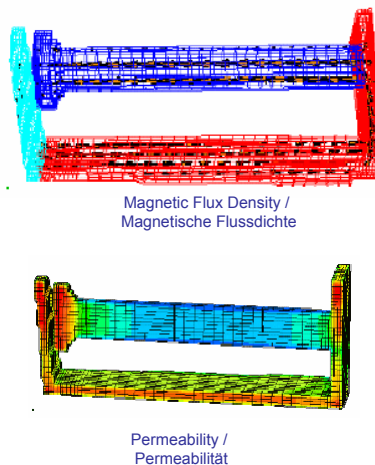


Elektric Field Strength /
Elektrische Feldstärke

Elektric Field Strength /
Elektrische Feldstärke

**Magnetostatic (MS) Fields /
Magnetostatistische (MS) Felder**

Relay / Relais



Magnetic Flux Density /
Magnetische Flussdichte

Permeability /
Permeabilität

Faraday's Induction Law / Faradaysches Induktionsgesetz

$$\nabla \times \underline{E}(\underline{R}, t) = -\frac{\partial}{\partial t} \underline{B}(\underline{R}, t) - \underline{J}_m(\underline{R}, t)$$

$$\oint_{C=\partial S} \underline{E}(\underline{R}, t) \cdot d\underline{R} = -\frac{d}{dt} \iint_S \underline{B}(\underline{R}, t) \cdot d\underline{S} - \iint_S \underline{J}_m(\underline{R}, t) \cdot d\underline{S}$$

Closed Contour Integral / Geschlossenes Kontur- oder Linienintegral
(Open) Surface Integral / (Offenes) Flächenintegral
(Open) Surface Integral / (Offenes) Flächenintegral

$$\oint_{C=\partial S} \underbrace{\underline{E}(\underline{R}, t)}_{\substack{[\text{V/m}] \\ [\text{m}]} } \cdot d\underline{R} = -\frac{d}{dt} \underbrace{\iint_S \underline{B}(\underline{R}, t) \cdot d\underline{S}}_{\substack{[\text{Vs/m}^2] \\ [\text{m}^2]} } - \underbrace{\iint_S \underline{J}_m(\underline{R}, t) \cdot d\underline{S}}_{\substack{[\text{V/m}^2] \\ [\text{m}^2]} }$$

$$\oint_{C=\partial S} \underline{E}(\underline{R}, t) \cdot d\underline{R} = -\frac{d}{dt} \iint_S \underline{B}(\underline{R}, t) \cdot d\underline{S} - \iint_S \underline{J}_m(\underline{R}, t) \cdot d\underline{S}$$

$\dot{u}_e(t)$
Electric Contour Voltage / Elektrische Umlaufspannung
 $\psi_m(t)$
Magnetic Flux / Magnetischer Fluss
 $i_m(t)$
Magnetic Current / Magnetischer Strom

$$\dot{u}_e(t) = -\frac{d}{dt} \psi_m(t) - i_m(t)$$

Faraday's Induction Law / Faradaysches Induktionsgesetz

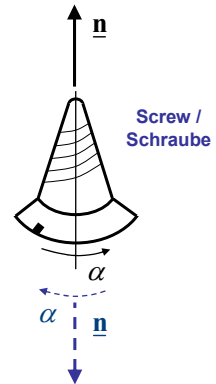
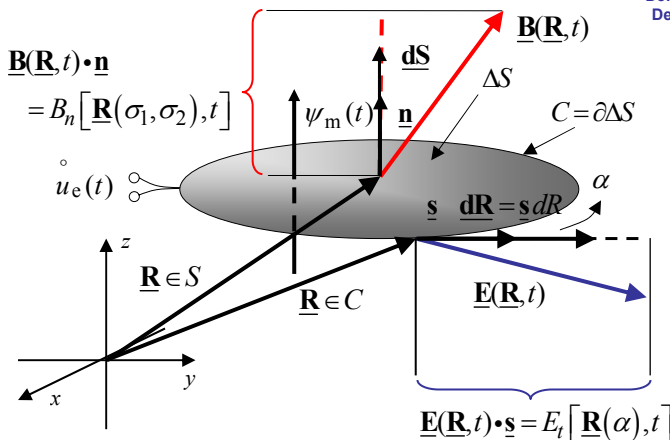
$$\oint_{C=\partial S} \underline{E}(\underline{R}, t) \cdot d\underline{R} = -\frac{d}{dt} \iint_S \underline{B}(\underline{R}, t) \cdot d\underline{S} - \iint_S \underline{J}_m(\underline{R}, t) \cdot d\underline{S}$$

Closed Contour Integral / Geschlossenes Kontur- oder Linienintegral
(Open) Surface Integral / (Offenes) Flächenintegral
(Open) Surface Integral / (Offenes) Flächenintegral

$$\dot{u}_e(t) = -\frac{d}{dt} \psi_m(t) - i_m(t)$$

\underline{J}_m and \underline{B} are treated in a similar way /
 \dot{J}_m und \underline{B} werden ähnlich behandelt

Definition of the Direction of α and \underline{n} /
Definition der Richtung von α and \underline{n}



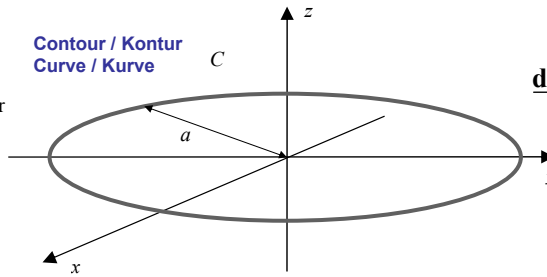
Example: Vector Differential Line and Surface Element / Beispiel: Vektorielles differentielles Linien- und Flächenelement (1)

Circle with Radius a in the xy Plane / Kreis
mit dem Radius a in der xy -Ebene

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{R}}$$

Closed Contour Integral /
Geschlossenes Kontur- oder
Linienintegral

Contour / Kontur
Curve / Kurve

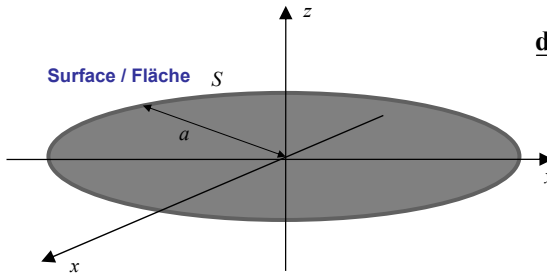


$$d\underline{\mathbf{R}} = ?$$

$$\iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

(Open) Surface Integral /
(Offenes Flächenintegral)

Surface / Fläche



$$d\underline{\mathbf{S}} = ?$$

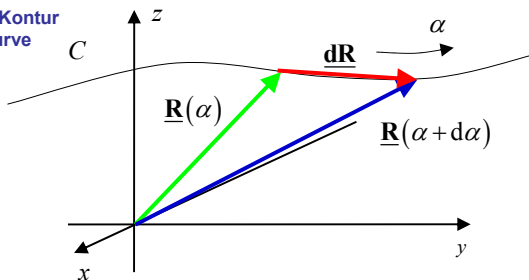
$$\iint_S \underline{\mathbf{J}}_m(\underline{\mathbf{R}}, t) \cdot d\underline{\mathbf{S}}$$

(Open) Surface Integral /
(Offenes Flächenintegral)

Vector Differential Line Element / Vektorielles differentielles Linienelement (1)

Definition:
$$d\underline{\mathbf{R}} \stackrel{\text{def}}{=} \underline{\mathbf{R}}(\alpha + d\alpha) - \underline{\mathbf{R}}(\alpha)$$

Contour / Kontur
Curve / Kurve



α Contour Parameter /
Konturparameter

$\underline{\mathbf{R}}(\alpha)$ Position Vector /
Ortsvektor

$\underline{\mathbf{R}}(\alpha + d\alpha)$ Position Vector /
Ortsvektor

$d\underline{\mathbf{R}}$ Difference Vector /
Differenzvektor

$$d\underline{\mathbf{R}} = \underline{\mathbf{R}}(\alpha + d\alpha) - \underline{\mathbf{R}}(\alpha)$$

Taylor Expansion /
Taylor-Entwicklung

$$= \underline{\mathbf{R}}(\alpha) + \frac{d}{d\alpha} \underline{\mathbf{R}}(\alpha) d\alpha - \underline{\mathbf{R}}(\alpha)$$

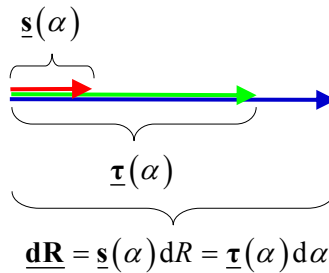
$$d\underline{\mathbf{R}} = \frac{d}{d\alpha} \underline{\mathbf{R}}(\alpha) d\alpha$$

$$= \underline{\boldsymbol{\tau}}(\alpha) d\alpha$$

$$= \underline{\mathbf{s}}(\alpha) d\underline{\mathbf{R}}$$

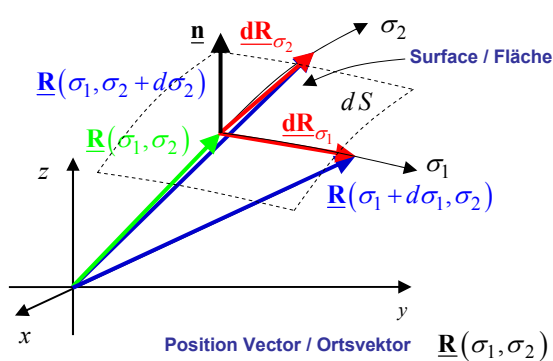
Vector Differential Line Element / Vektorielles differentielles Linienelement (2)

$$\begin{aligned} d\mathbf{R} &= \frac{d}{d\alpha} \underbrace{\mathbf{R}(\alpha)}_{\underline{\boldsymbol{\tau}}(\alpha)} d\alpha & \underline{\boldsymbol{\tau}}(\alpha) & \text{Tangential Vector /} \\ & & & \text{Tangentenvektor} \\ &= \underline{\boldsymbol{\tau}}(\alpha) d\alpha & \underline{\mathbf{s}}(\alpha) & \text{Tangential Unit Vector /} \\ &= \underbrace{\underline{\mathbf{s}}(\alpha)}_{|\underline{\mathbf{s}}(\alpha)|=1} dR & & \text{Tangenteinheitsvektor} \end{aligned}$$



Vector Differential Surface Element / Vektorielles differentielles Flächenelement (1)

Definition: $d\mathbf{S} = \underline{\mathbf{n}} dS$



- σ_1, σ_2 Surface Parameters / Flächenparameter
- $\mathbf{R}(\sigma_1, \sigma_2)$ Position Vector / Ortsvektor
- $\mathbf{R}(\sigma_1 + d\sigma_1, \sigma_2)$ Position Vector / Ortsvektor
- $\mathbf{R}(\sigma_1, \sigma_2 + d\sigma_2)$ Position Vector / Ortsvektor
- $d\mathbf{R}_{\sigma_1}$ Vector Differential Line Elements / Vektorielle differentielle Linienelemente
- $d\mathbf{R}_{\sigma_2}$ Vector Differential Line Elements / Vektorielle differentielle Linienelemente

Tangential Vectors / Tangentialvektoren

$$\underline{\boldsymbol{\sigma}}_1(\sigma_1, \sigma_2) = \frac{\partial}{\partial \sigma_1} \mathbf{R}(\sigma_1, \sigma_2)$$

$$\underline{\boldsymbol{\sigma}}_2(\sigma_1, \sigma_2) = \frac{\partial}{\partial \sigma_2} \mathbf{R}(\sigma_1, \sigma_2)$$

Vector Differential Surface Element / Vektorielles differentielles Flächenelement (2)

Vector Differential Line Elements / Vektorielles differentielles Linienelement

$$\underline{dR}_{\sigma_1} = \underline{\sigma}_1(\sigma_1, \sigma_2) d\sigma_1$$

$$\underline{dR}_{\sigma_2} = \underline{\sigma}_2(\sigma_1, \sigma_2) d\sigma_2$$

Scalar Differential Surface Elements / Skalares differentielles Flächenelement

$$\begin{aligned} dS &= \left| \underline{dR}_{\sigma_1} \times \underline{dR}_{\sigma_2} \right| \\ &= \left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right| d\sigma_1 d\sigma_2 \end{aligned}$$

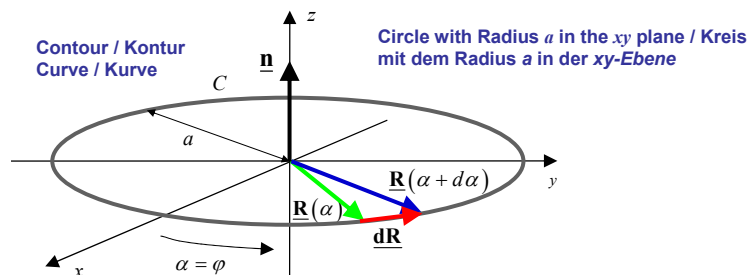
Normal Unit-Vector / Normaleneinheitsvektor

$$\underline{n} = \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{\left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right|}$$

Vector Differential Surface Element / Vektorielles differentielles Flächenelement

$$\begin{aligned} \underline{dS} &= \underline{n} dS \\ &= \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{\left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right|} \left| \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) \right| d\sigma_1 d\sigma_2 \\ &= \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) d\sigma_1 d\sigma_2 \end{aligned}$$

Example: Vector Differential Line Element / Beispiel: Vektorielles differentielles Linienelement (1)

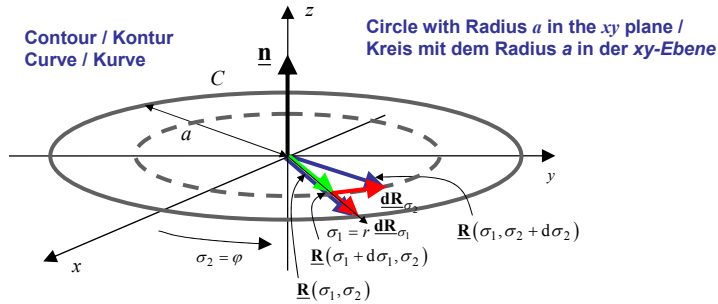


$$\underline{R}(\alpha = \varphi) = a \cos \varphi \underline{e}_x + a \sin \varphi \underline{e}_y \quad \underline{dR} = \frac{d}{d\alpha} \underline{R}(\alpha) d\alpha = \underline{\tau}(\alpha) d\alpha = \underline{s}(\alpha) dR$$

$$0 \leq \varphi < 2\pi$$

$$\begin{aligned} \frac{d}{d\varphi} \underline{R}(\varphi) &= \frac{d}{d\varphi} (a \cos \varphi \underline{e}_x + a \sin \varphi \underline{e}_y) & \underline{dR} &= \frac{d}{d\varphi} \underline{R}(\varphi) \frac{d\varphi}{=d\alpha} = \underbrace{a \underline{e}_\varphi(\varphi)}_{=\underline{\tau}(\alpha)} \frac{d\varphi}{=dR} \\ &= a \underbrace{(-\sin \varphi \underline{e}_x + \cos \varphi \underline{e}_y)}_{\underline{e}_\varphi(\varphi)} & &= \underline{e}_\varphi(\varphi) \frac{a d\varphi}{=dR} \\ &= a \underline{e}_\varphi(\varphi) & &= \underline{dR}_\varphi \end{aligned}$$

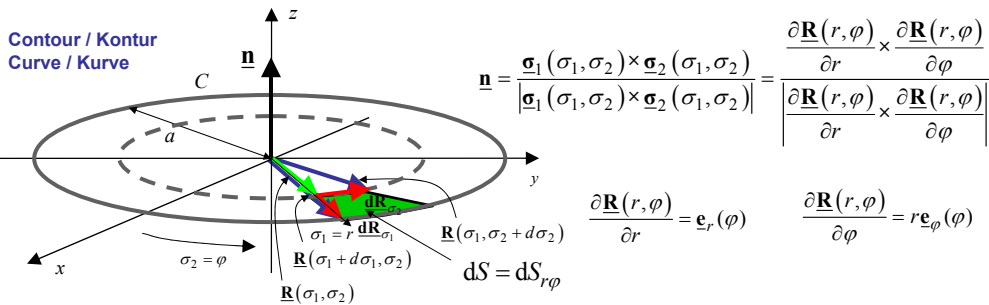
Example: Vector Differential Surface Element / Beispiel: Vektorielles differentielles Flächenelement (1)



$$\underline{\mathbf{R}}(\sigma_1 = r, \sigma_2 = \varphi) = r \cos \varphi \underline{\mathbf{e}}_x + r \sin \varphi \underline{\mathbf{e}}_y, \quad 0 \leq \sigma_1 = r \leq a, \quad 0 \leq \sigma_2 = \varphi < 2\pi$$

$$\begin{aligned} \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial r} &= \frac{\partial}{\partial r} (r \cos \varphi \underline{\mathbf{e}}_x + r \sin \varphi \underline{\mathbf{e}}_y) & \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial \varphi} &= \frac{\partial}{\partial \varphi} (r \cos \varphi \underline{\mathbf{e}}_x + r \sin \varphi \underline{\mathbf{e}}_y) \\ &= \cos \varphi \underline{\mathbf{e}}_x + \sin \varphi \underline{\mathbf{e}}_y & &= r (-\sin \varphi \underline{\mathbf{e}}_x + \cos \varphi \underline{\mathbf{e}}_y) \\ &= \underline{\mathbf{e}}_r(\varphi) & &= r \underline{\mathbf{e}}_\varphi(\varphi) \end{aligned}$$

Example: Vector Differential Surface Element / Beispiel: Vektorielles differentielles Flächenelement (2)

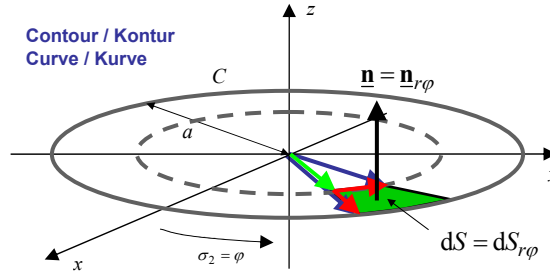


$$\underline{\mathbf{n}} = \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{|\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)|} = \frac{\frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial r} \times \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial \varphi}}{\left| \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial r} \times \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial \varphi} \right|}$$

$$\frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial r} = \underline{\mathbf{e}}_r(\varphi) \quad \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial \varphi} = r \underline{\mathbf{e}}_\varphi(\varphi)$$

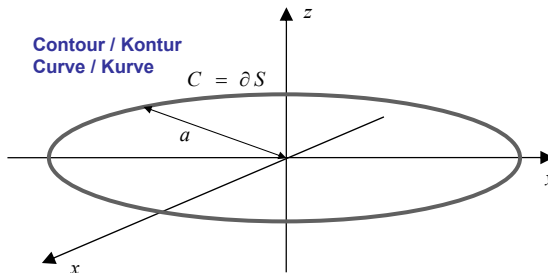
$$\begin{aligned} \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) &= \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial r} \times \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial \varphi} \\ &= \underline{\mathbf{e}}_r(\varphi) \times r \underline{\mathbf{e}}_\varphi(\varphi) \\ &= r \left[\underline{\mathbf{e}}_r(\varphi) \times \underline{\mathbf{e}}_\varphi(\varphi) \right] \\ &= r \underline{\mathbf{e}}_z \end{aligned} \quad \begin{aligned} |\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)| &= \left| \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial r} \times \frac{\partial \underline{\mathbf{R}}(r, \varphi)}{\partial \varphi} \right| \\ &= \left| \underline{\mathbf{e}}_r(\varphi) \times r \underline{\mathbf{e}}_\varphi(\varphi) \right| \\ &= r \left[\underline{\mathbf{e}}_r(\varphi) \times \underline{\mathbf{e}}_\varphi(\varphi) \right] \\ &= r \underline{\mathbf{e}}_z \\ &= r \end{aligned} \quad \Rightarrow \quad \underline{\mathbf{n}} = \frac{r \underline{\mathbf{e}}_z}{r} = \underline{\mathbf{e}}_z$$

Example: Vector Differential Surface Element / Beispiel: Vektorielles differentielles Flächenelement (3)



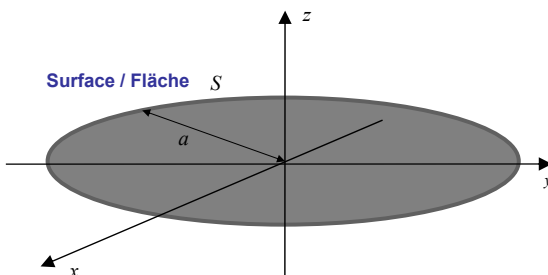
$$\begin{aligned}
 \underline{dS} &= \underline{n} dS \\
 &= \frac{\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)}{|\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)|} |\underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2)| d\sigma_1 d\sigma_2 \\
 &= \underline{\sigma}_1(\sigma_1, \sigma_2) \times \underline{\sigma}_2(\sigma_1, \sigma_2) d\sigma_1 d\sigma_2 \\
 &= \underbrace{\underline{e}_z}_{=\underline{n}_{r\varphi}} \underbrace{r dr d\varphi}_{=dS_{r\varphi}} \\
 &= \underline{n}_{r\varphi} dS_{r\varphi} \\
 &= \underline{dS}_{r\varphi}
 \end{aligned}$$

Example: Vector Differential Line and Surface Element / Beispiel: Vektorielles differentielles Linien- und Flächenelement (2) (Circle with Radius a in the xy Plane / Kreis mit dem Radius a in der xy-Ebene)



$$\underline{dR} = \underline{dR}_\varphi = a \underline{e}_\varphi(\varphi) d\varphi$$

$$\begin{aligned}
 \oint_{C=\partial S} \underline{E}(\underline{R}, t) \cdot \underline{dR} \\
 &= \int_{\varphi=0}^{2\pi} \underline{E}[\underline{R}(r=a, \varphi, z=0), t] \cdot a \underline{e}_\varphi(\varphi) d\varphi
 \end{aligned}$$



$$\underline{dS} = \underline{dS}_{r\varphi} = \underline{e}_z r dr d\varphi$$

$$\begin{aligned}
 \iint_S \underline{B}(\underline{R}, t) \cdot \underline{dS} \\
 &= \int_{\varphi=0}^{2\pi} \int_{r=0}^a \underline{B}[\underline{R}(r, \varphi, z=0), t] \cdot \underline{e}_z r dr d\varphi
 \end{aligned}$$

**Example: Vector Differential Line and Surface Element /
Beispiel: Vektorielles differentielles Linien- und Flächenelement (2)**
(Circle with Radius a in the xy Plane / Kreis mit dem Radius a in der xy -Ebene)

$$\begin{aligned}
 a \int_{\varphi=0}^{2\pi} \underbrace{\underline{E}[\underline{R}(r=a, \varphi, z=0), t]}_{=E_{\varphi}[\underline{R}(r=a, \varphi, z=0), t]} \cdot \underline{e}_{\varphi}(\varphi) d\varphi &= a \int_{\varphi=0}^{2\pi} \underbrace{E_{\varphi}[\underline{R}(r=a, \varphi, z=0), t]}_{E_t[\underline{R}(r, \varphi, z=0), t]} d\varphi \\
 &\quad \text{Tangential Component of } \underline{E} / \text{Tangentiale Komponente von } \underline{E} \\
 \int_{\varphi=0}^{2\pi} \int_{r=0}^a \underbrace{\underline{B}[\underline{R}(r, \varphi, z=0), t]}_{=B_z[\underline{R}(r, \varphi, z=0), t]} \cdot \underline{e}_z r dr d\varphi &= \int_{\varphi=0}^{2\pi} \int_{r=0}^a \underbrace{B_z[\underline{R}(r, \varphi, z=0), t]}_{=B_n[\underline{R}(r, \varphi, z=0), t]} r dr d\varphi \\
 &\quad \text{Normal Component of } \underline{B} / \text{Normalkomponente von } \underline{B} \\
 \int_{\varphi=0}^{2\pi} \underline{E}[\underline{R}(r=a, \varphi, z=0), t] \cdot a \underline{e}_{\varphi}(\varphi) d\varphi \\
 &= - \frac{d}{dt} \int_{\varphi=0}^{2\pi} \int_{r=0}^a \underline{B}[\underline{R}(r, \varphi, z=0), t] \cdot \underline{e}_z r dr d\varphi \\
 &= - \int_{\varphi=0}^{2\pi} \int_{r=0}^a \underline{J}_m[\underline{R}(r, \varphi, z=0), t] \cdot \underline{e}_z r dr d\varphi
 \end{aligned}$$

Ampère-Maxwell's Circuital Law / Ampère-Maxwellsches Durchflutungsgesetz

**Differential Form /
Differentialform**

$$\nabla \times \underline{H}(\underline{R}, t) = \frac{\partial}{\partial t} \underline{D}(\underline{R}, t) + \underline{J}_e(\underline{R}, t)$$

**Integral Form /
Integralform**

$$\oint_{C=\partial S} \underline{H}(\underline{R}, t) \cdot d\underline{R} = \frac{d}{dt} \iint_S \underline{D}(\underline{R}, t) \cdot d\underline{S} + \iint_S \underline{J}_e(\underline{R}, t) \cdot d\underline{S}$$

Closed Contour Integral / Geschlossenes Kontur- oder Linienintegral
(Open) Surface Integral / (Offenes) Flächenintegral
(Open) Surface Integral / (Offenes) Flächenintegral

$$\oint_{C=\partial S} \underbrace{\underline{H}(\underline{R}, t)}_{\substack{[A/m] \\ [m] \\ [A]}} \cdot d\underline{R} = \frac{d}{dt} \iint_S \underbrace{\underline{D}(\underline{R}, t)}_{\substack{[As/m^2] \\ [m^2] \\ [A]}} \cdot d\underline{S} - \iint_S \underbrace{\underline{J}_e(\underline{R}, t)}_{\substack{[A/m^2] \\ [m^2] \\ [A]}} \cdot d\underline{S}$$

$$\oint_{C=\partial S} \underbrace{\underline{H}(\underline{R}, t) \cdot d\underline{R}}_{\substack{\overset{\circ}{u}_m(t) [A] \\ \text{Magnetic Contour Voltage /} \\ \text{Magnetische Umlaufspannung}}} = \frac{d}{dt} \iint_S \underbrace{\underline{D}(\underline{R}, t) \cdot d\underline{S}}_{\substack{\psi_e(t) [As] \\ \text{Electric Flux /} \\ \text{Elektrischer Fluss}}} + \iint_S \underbrace{\underline{J}_e(\underline{R}, t) \cdot d\underline{S}}_{\substack{i_e(t) [A] \\ \text{Electric Current /} \\ \text{Elektrischer Strom}}}$$

$$\overset{\circ}{u}_m(t) = \frac{d}{dt} \psi_e(t) + i_e(t)$$

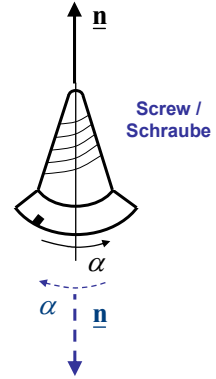
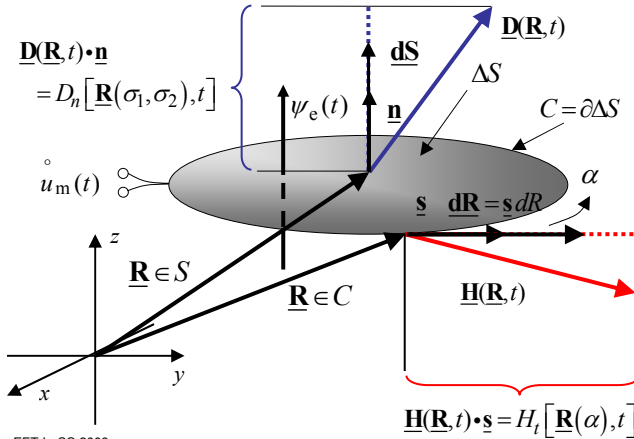
Ampère-Maxwell's Circuital Law / Ampère-Maxwellsches Durchflutungsgesetz

$$\underbrace{\oint_{C=\partial S} \underline{H}(\underline{R}, t) \cdot d\underline{R}}_{\text{Closed Contour Integral / Geschlossenes Kontur- oder Linienintegral}} = \frac{d}{dt} \underbrace{\iint_S \underline{D}(\underline{R}, t) \cdot d\underline{S}}_{\text{(Open) Surface Integral / (Offenes) Flächenintegral}} + \underbrace{\iint_S \underline{J}_e(\underline{R}, t) \cdot d\underline{S}}_{\text{(Open) Surface Integral / (Offenes) Flächenintegral}}$$

$$\dot{u}_m(t) = \frac{d}{dt} \psi_e(t) + i_e(t)$$

\underline{J}_e and \underline{D} are treated in a similar way /
 \underline{J}_e und \underline{D} werden ähnlich behandelt

Definition of the Direction of α and \underline{n} /
Definition der Richtung von α and \underline{n}



Gauss' Electric Law / Gaußsches elektrisches Gesetz

Differential Form /
Differentialform

$$\nabla \cdot \underline{D}(\underline{R}, t) = \rho_e(\underline{R}, t)$$

Integral Form /
Integralform

$$\underbrace{\oiint_{S=\partial V} \underline{D}(\underline{R}, t) \cdot d\underline{S}}_{\text{Closed Surface Integral / Geschlossenes Flächenintegral}} = \underbrace{\iiint_V \rho_e(\underline{R}, t) dV}_{\text{Volume Integral / Volumenintegral}}$$

$$\underbrace{\oiint_{S=\partial V} \underline{D}(\underline{R}, t) \cdot d\underline{S}}_{\substack{[\text{As/m}^2] [\text{m}^2] \\ [\text{As}]}} = \underbrace{\iiint_V \rho_e(\underline{R}, t) dV}_{\substack{[\text{As/m}^3] [\text{m}^3] \\ [\text{As}]}}$$

$$\underbrace{\oiint_{S=\partial V} \underline{D}(\underline{R}, t) \cdot d\underline{S}}_{\substack{= \psi_e(t) [\text{As}] \\ \text{Electric Flux /} \\ \text{Elektrischer Fluss}}} = \underbrace{\iiint_V \rho_e(\underline{R}, t) dV}_{\substack{= q_e(t) [\text{As}] \\ \text{Electric Charge /} \\ \text{Elektrische Ladung}}}$$

$$\psi_e(t) = q_e(t)$$

Gauss' Magnetic Law / Gaußes magnetisches Gesetz

Differential Form /
Differentialform

$$\nabla \cdot \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) = \rho_m(\underline{\mathbf{R}}, t)$$

Integral Form /
Integralform

$$\underbrace{\oiint_{S=\partial V} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}}_{\text{Closed Surface Integral /
Geschlossenes Flächenintegral}} = \underbrace{\iiint_V \rho_m(\underline{\mathbf{R}}, t) dV}_{\text{Volume Integral /
Volumenintegral}}$$

$$\underbrace{\oiint_{S=\partial V} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}}_{\substack{[\text{Vs/m}^2] [\text{m}^2] \\ [\text{Vs}]}} = \underbrace{\iiint_V \rho_m(\underline{\mathbf{R}}, t) dV}_{\substack{[\text{Vs/m}^3] [\text{m}^3] \\ [\text{Vs}]}}$$

$$\underbrace{\oiint_{S=\partial V} \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}}_{\substack{=\psi_m(t) [\text{Vs}] \\ \text{Magnetic Flux /} \\ \text{Magnetischer Fluss}}} = \underbrace{\iiint_V \rho_m(\underline{\mathbf{R}}, t) dV}_{\substack{=q_m(t) [\text{Vs}] \\ \text{Magnetic Charge /} \\ \text{Magnetische Ladung}}}$$

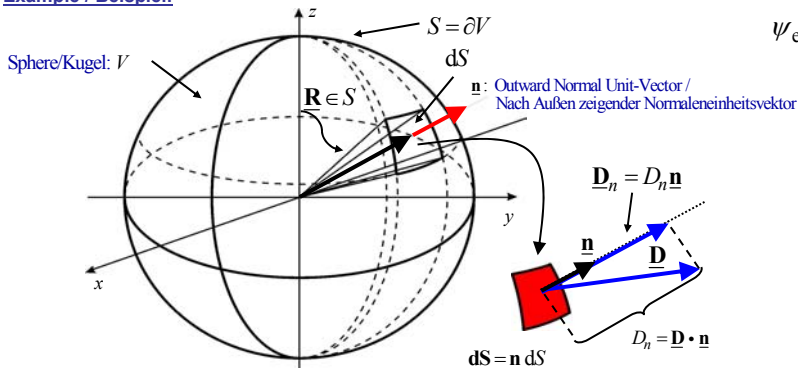
$$\psi_m(t) = q_m(t)$$

Gauss' Electric Law / Gaußsches elektrisches Gesetz

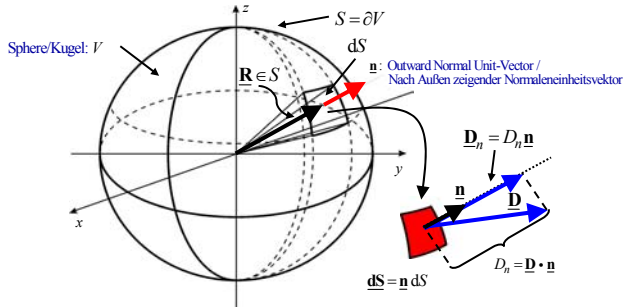
$$\underbrace{\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}}_{\text{Closed Surface Integral /
Geschlossenes Flächenintegral}} = \underbrace{\oiint_{S=\partial V} \underline{\mathbf{D}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{n}} dS}_{\substack{=D_n(\underline{\mathbf{R}}, t) \\ \text{Summation of all Normal Components of } \underline{\mathbf{D}} \\ \text{at the Closed Surface } S=\partial V \text{ of} \\ \text{the Volume } V / \\ \text{Summation aller Normalkomponenten von } \underline{\mathbf{D}} \\ \text{auf der geschlossenen Oberfläche } S=\partial V \text{ des} \\ \text{Volumens } V}} = \underbrace{\iiint_V \rho_e(\underline{\mathbf{R}}, t) dV}_{\substack{\text{Volume Integral /} \\ \text{Volumenintegral} \\ \text{Summation of all charges} \\ \text{inside the Volume } V / \\ \text{Summation aller Ladungen in} \\ \text{dem Volumen } V}} = q_e(t)$$

Flux Through the Closed Surface /
Fluss durch die geschlossene Oberfläche

Example / Beispiel:



Example: Sphere with Radius a / Beispiel: Kugel mit Radius a (1)



$$\begin{aligned} \oiint_{S=\partial V} \underline{D}(\underline{R}, t) \cdot \underline{n} \, dS &= D_n(\underline{R}, t) \\ &= \iiint_V \rho_e(\underline{R}, t) \, dV \end{aligned}$$

$$\underline{dS} = \underline{n} dS \quad (= \underline{n}_{\vartheta\varphi} h_\vartheta h_\varphi \, d\vartheta \, d\varphi)$$

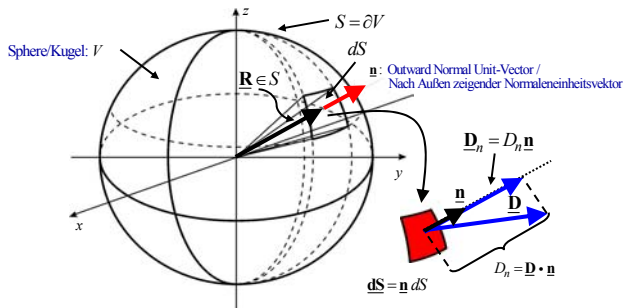
$$= \underbrace{\underline{e}_R(\vartheta, \varphi)}_{\underline{n}} R^2 \sin \vartheta \, d\vartheta \, d\varphi \Big|_{R=a} = \underbrace{\underline{e}_R(\vartheta, \varphi)}_{\underline{n}} a^2 \sin \vartheta \, d\vartheta \, d\varphi$$

$$\begin{aligned} \oiint_{S=\partial V} \underline{D}(\underline{R}, t) \cdot \underline{dS} &= \oiint_{S=\partial V} \underbrace{\underline{D}(\underline{R}, t) \cdot \underline{n}}_{=D_n(\underline{R}, t)} \, dS = \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi} \underbrace{\underline{D}[\underline{R}(R=a, \vartheta, \varphi), t] \cdot \underline{e}_R(\vartheta, \varphi)}_{=D_n[\underline{R}(R=a, \vartheta, \varphi), t]} a^2 \sin \vartheta \, d\vartheta \, d\varphi \\ &= \psi_e(t) \end{aligned}$$

$$0 \leq \vartheta \leq \pi$$

$$0 \leq \varphi < 2\pi$$

Example: Sphere with Radius a / Beispiel: Kugel mit Radius a (2)



$$\begin{aligned} \oiint_{S=\partial V} \underline{D}(\underline{R}, t) \cdot \underline{n} \, dS &= D_n(\underline{R}, t) \\ &= \iiint_V \rho_e(\underline{R}, t) \, dV \end{aligned}$$

$$dV = R^2 \sin \vartheta \, dR \, d\vartheta \, d\varphi \quad (= h_R h_\vartheta h_\varphi \, dR \, d\vartheta \, d\varphi)$$

$$\begin{aligned} \iiint_V \rho_e(\underline{R}, t) \, dV &= \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi} \int_{R=0}^a \rho_e[\underline{R}(R, \vartheta, \varphi), t] R^2 \sin \vartheta \, dR \, d\vartheta \, d\varphi \\ &= q_e(t) \end{aligned}$$

$$0 \leq R \leq a$$

$$0 \leq \vartheta \leq \pi$$

$$0 \leq \varphi < 2\pi$$

Example: Electric Field Due to Spherically Symmetric Charge Distribution / Beispiel: Elektrisches Feld einer kugelsymmetrischen Raumladungsdichte

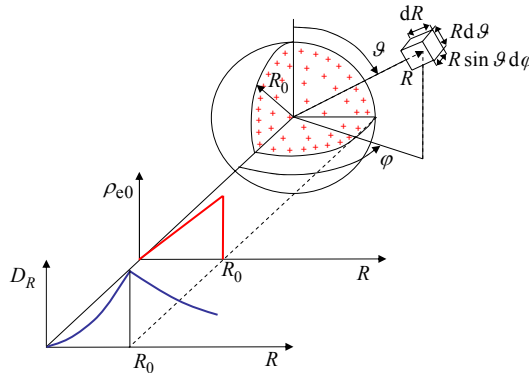
Consider the Electrostatic (ES) Case /
Betrachte den elektrostatischen Fall

$$\oiint_{S=\partial V} \underbrace{\mathbf{D}(\mathbf{R}) \cdot \mathbf{n}}_{=D_n(\mathbf{R})} dS = \iiint_V \rho_e(\mathbf{R}) dV$$

Electric Charge Density /
Elektrische Raumladungsdichte

$$\rho_e(\mathbf{R}) = \begin{cases} \rho_{e0} \frac{R}{R_0} & R < R_0 \\ 0 & R > R_0 \end{cases}$$

Radial Symmetry /
Radialsymmetrisch !



Continuity Equations for Electric and Magnetic Charges / Kontinuitätsgleichung für elektrische und magnetische Ladungen

(Conservation of Electric Charge /
Erhaltung der elektrischen Ladung)

$$\oiint_{S=\partial V} \underbrace{\mathbf{J}_e(\mathbf{R}, t) \cdot \mathbf{dS}}_{\substack{\text{Closed Surface Integral /} \\ \text{Geschlossenes Flächenintegral}}} = - \frac{d}{dt} \underbrace{\iiint_V \rho_e(\mathbf{R}, t) dV}_{\substack{\text{Volume Integral /} \\ \text{Volumenintegral}}}$$

$$\underbrace{\oiint_{S=\partial V} \mathbf{J}_e(\mathbf{R}, t) \cdot \mathbf{dS}}_{\substack{[\text{A/m}^2] \quad [\text{m}^2] \\ [\text{A}]}} = - \frac{d}{dt} \underbrace{\iiint_V \rho_e(\mathbf{R}, t) dV}_{\substack{[\text{1/s}] \quad [\text{As/m}^3] \quad [\text{m}^3] \\ [\text{As}] \\ [\text{A}]}}$$

$$\underbrace{\oiint_{S=\partial V} \mathbf{J}_e(\mathbf{R}, t) \cdot \mathbf{dS}}_{=i_e(t) [\text{A}]} = - \frac{d}{dt} \underbrace{\iiint_V \rho_e(\mathbf{R}, t) dV}_{=q_e(t) [\text{As}]} \\ \text{Electric Current /} \quad \text{Elektrischer Strom} \quad \text{Electric Charge /} \quad \text{Elektrische Ladung}$$

$$i_e(t) = - \frac{d}{dt} q_e(t)$$

(Conservation of Magnetic Charge /
Erhaltung der magnetischen Ladung)

$$\oiint_{S=\partial V} \underbrace{\mathbf{J}_m(\mathbf{R}, t) \cdot \mathbf{dS}}_{\substack{\text{Closed Surface Integral /} \\ \text{Geschlossenes Flächenintegral}}} = - \frac{d}{dt} \underbrace{\iiint_V \rho_m(\mathbf{R}, t) dV}_{\substack{\text{Volume Integral /} \\ \text{Volumenintegral}}}$$

$$\underbrace{\oiint_{S=\partial V} \mathbf{J}_m(\mathbf{R}, t) \cdot \mathbf{dS}}_{\substack{[\text{V/m}^2] \quad [\text{m}^2] \\ [\text{V}]}} = - \frac{d}{dt} \underbrace{\iiint_V \rho_m(\mathbf{R}, t) dV}_{\substack{[\text{1/s}] \quad [\text{Vs/m}^3] \quad [\text{m}^3] \\ [\text{Vs}] \\ [\text{V}]}}$$

$$\underbrace{\oiint_{S=\partial V} \mathbf{J}_m(\mathbf{R}, t) \cdot \mathbf{dS}}_{=i_m(t) [\text{V}]} = - \frac{d}{dt} \underbrace{\iiint_V \rho_m(\mathbf{R}, t) dV}_{=q_m(t) [\text{Vs}]} \\ \text{Magnetic Current /} \quad \text{Magnetischer Strom} \quad \text{Magnetic Charge /} \quad \text{Magnetische Ladung}$$

$$i_m(t) = - \frac{d}{dt} q_m(t)$$

Field and Circuit Relations / Feld- und Schaltungsrelationen

Field Relation / Feldrelation

$$\oiint_{S=\partial V} \underline{\mathbf{J}}_e(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}} = -\frac{d}{dt} \iiint_V \rho_e(\underline{\mathbf{R}}, t) dV$$

*(Continuity Equation for Electric Charges /
Kontinuitätsgleichung für elektrische Ladungen)*

$$\oint_{C=\partial S} \underline{\mathbf{E}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dR}} = -\frac{d}{dt} \iint_S \underline{\mathbf{B}}(\underline{\mathbf{R}}, t) \cdot \underline{\mathbf{dS}}$$

*(Faraday's Induction Law /
Faradaysches Induktionsgesetz)*

Circuit Relation / Schaltungsrelation

$$\sum_n i_e^{(n)}(t) = -\frac{d}{dt} q_e(t) = -C_s \frac{d}{dt} u_e(t)$$

*(Kirchhoff's Current Law /
1. Kirchhoffsches Gesetz, Knotenpunktregel)*

$$\sum_n u_e^{(n)}(t) = -\frac{d}{dt} \psi_m(t) = -L_s \frac{d}{dt} i_e(t)$$

*(Kirchhoff's Loop Voltage Law /
2. Kirchhoffsches Gesetz, Maschenregel)*

End of 4th Lecture /
Ende der 4. Vorlesung