# CalculiX USER'S MANUAL - CalculiX GraphiX, Version 2.5 - 

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September 27, 2012


Figure 1: A complex model made from scratch using second order brick elements

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## 1 Introduction

This document is the description of CalculiX GraphiX (cgx). This program is designed to generate and display finite elements (FE) and results coming from CalculiX CrunchiX (ccx). If you have any problems using cgx, this document
should solve them. If not, you might send an email to the author [3]. The Concept and File Format sections give some background on functionality and mesher capabilities. The Getting Started section describes how to run the verification examples you should have obtained along with the code of the program. You might use this section to check whether you installed CalculiX correctly. Then, a detailed overview is given of the menu and all the available keywords in alphabetical order in the Menu and Commands sections respectively. Finally, the User's Manual ends with the appendix and some references used while writing the code.

## 2 Concept

This program uses the openGL library for visualization and the glut library [2] for window management and event handling. This results in very high speed if a hardware-accelerated openGL-library is available and still high speed for software-rendering (MesaGL, [1).

The cgx has pre- and post-processor capabilities. It is able to generate and display beam, shell and brick elements in its linear and quadratic form (fig. (1). In addition, it can display but not create pentahedra- and tetrahedra-elements.

The built-in mesher creates a structured mesh based on a description of the geometry. For example, it uses lines for beam elements, surfaces for shell elements and volumes (bodies) for brick elements. The program distinguishes between the mesh and the underlying geometry. Elements are made from faces and faces are made from nodes. If you move a node, the corresponding face(s) and element(s) will follow. The geometry behaves according to the mesh: Lines are made from points, surfaces are made from lines and bodies are made of surfaces. Surfaces might have 3 to 5 edges and bodies might have 5 to 7 surfaces. As a result, if you modify the position of a point, all related geometry will follow. In other words, if the location of geometric entities is changed, it is necessary to move the points on which the entities rely. It should be noted that faces exist only on free surfaces of the model.

Even though cgx cannot generate tet-meshes, it is still possible to generate a surface-mesh of triangles and export it in stl-format. This format can be read by external meshers such as NETGEN [4. This mesher fills the volume with tetrahedra elements and is able to export the Abaqus file format. This can be read by cgx and ccx (see also "How to deal with cad-geometry').

In addition, entities can be grouped together to make sets. Sets are useful to handle parts of a model. For example, sets can be used to manipulate or display a few entities at a time (see also 'How to define a set of entities').

After a mesh is created in cgx, it needs written to a file for use with the solver. Likewise, several boundary conditions and loads can be written to files (see also ',How to connect independent meshes', 'How to define loads and constraints' and "send'). These files need to be added into the control file for later use in ccx. Additional commands, material description and so on must be added with the help of an external editor.

After the analysis is completed, the results can be visualized by calling the cgx program again in an independent session. The program is primary controlled by the keyboard with individual commands for each function. Only a subset of commands which are most important for post-processing is also available through a pop-up menu. Shaded animations of static and dynamic results, the common color plots and time history plots can be created. Also, a cut through the model can be done which creates a section and it is possible to zoom through the model.

Skilled users might include their own functions. For example someone may need his own functions to manipulate the result-data or he may need an interface to read or write his own results format (see also 'ccall').

Both the pre- and post- processing can be automated in batch-mode (see also 'How to run cgx in batch mode').

## 3 File Formats

The following file-formats are available to write(w) and/or read(r) geometric entities:

- fbd-format(r/w), this format consists of a collection of commands explained in the section 'Commands' and it is mainly used to store geometrical information like points, lines, surfaces and bodies. But it can also be used to define a batch job which uses the available commands.
- step-format(r), reverse engineered based on some cad files. Only points and certain types of lines are supported currently.
- stl-format(r/w), this format describes a shape using only triangles (see the read command to handle edges generated by NETGEN).

Common CAD formats are supported by stand-alone interfaces which translate into fbd-commands.

The following file-formats are available to write a mesh and certain boundaryconditions:

- Abaqus, which is also used by the CalculiX solver ccx.
- Ansys, most boundary conditions available.
- Code_Aster, mesh and sets of nodes and elements are available.
- Samcef, mesh and sets of nodes and elements are available.
- dolfyn, a free cfd-code 5 .
- duns, a free cfd-code 6].
- isaac, a free cfd-code 7.
- OpenFOAM, a free cfd-code [8], only 8 -noded brick-elements are supported.
- Nastran, most boundary conditions available.
- tochnog, a free fem-code [9, only 8 -noded brick-elements are supported.

The following solver-input-file-formats can be read to check the mesh, sets and certain boundary-conditions:

- Abaqus, this is also used by the CalculiX solver ccx.
- Netgen, read Netgen native format (.vol)

The following file-formats are available to read solver results:

- frd-format, files of this format are used to read results of previous calculations like displacements and stresses. This format is described in section "Result Format" It is also used by ccx.
- duns, a free cfd-code 6,
- isaac, a free cfd-code 7,
- OpenFOAM, a free cfd-code [8].

For a more detailed description on how to use cgx to read this formats see " Program Parameters' and the program specific " Tips and Hints' sections. See the "send]' command for how to write them from cgx.

## 4 Getting Started

For installation help, see .../Calculix/cgx_X.X/INSTALL. After the program is installed on your machine, you should check the functionality by running the examples included in the distribution. The examples are located in .../Calculix/cgx_X.X/examples/. Before going further, you should read the section 'Input Devices'. Then, begin with a result file called result.frd. Just type
"cgx result.frd"
and some information is echoed in the xterm and a new window called main window appears on the screen. The name conventions used for the different areas in the main-window are explained in figure 2 Now you should move the mouse pointer into the menu-area and press the left mouse-button. Keep it pressed and continue over the menu item "Dataset" to "Disp". There you release the button. Then press the left button again and continue over "Dataset" and "Entity" to "D1". For background informations look into the subsection "Datasets' and 'Entity' which explains how to display results. After seeing the values you might play around a bit with the "Menu'. See also the commands 'steps',
" $\mathrm{max}^{\prime}$ ', 'min', "scall' which might be used to modify the colour representation of the displayed values. For example type "min 0" to change the lower value of the colour bar. Watch out if you type a command; the cgx window MUST stay active and not the xterm from which the program was started. It is better to stay with the mouse pointer in the cgx window. Next, 'Quit' the program and type
"cgx -b geometry.fbd"
in the xterm. The program starts again but now you see only a wire-frame of the geometry. Move the mouse-pointer into the new window and type "mesh all". The mouse-pointer MUST stay in this window during typing and NOT in the xterm from which the program was started. After you see "ready" in the parent xterm, the mesh is created. To actually see it, type "plus ea all". Now you see the mesh in green color. To see the mesh as a wire-frame, choose in the main menu' 'Viewing' and continue to the entry '"Toggle Element Edges' and then again in '\Viewing' choose 'Dots'. To see the mesh illuminated chose in the main menu '"Viewing' and continue to the entry '"Show Elements With Light'. To see it filled, choose in the main menu 'Viewing' and continue to the entity "Fill'. Most of the time it is sufficient to see the surface elements only. For this purpose, choose in the main menu ' Viewing' and continue to the entry ",Toggle Surfaces/Volumes'. If you start cgx in the post processor mode, as you did in the first example (cgx result.frd), the surface mode is automatically set. To see the interior of the structure, choose in the main menu 'Viewing' and continue to the entity '"Toggle Culling Back/Front'. To save the mesh in the format used by the solver, type "send all abq". To store the mesh in the result format type "send all frd".

To create a new model start the cgx by typing
"cgx -b file"
where "file" will be the name of the new model if you later exit the program with the command "exit'. The way to create a model from scratch is roughly as follows, create

- points with '"qpnt' or ',pnt',
- lines with "qlin',
- surfaces with" "qsur',
- Bodies with "qbod'.

If possible, create higher geometry by sweeping or copying geometry with "swep' or "copy'. The commands require sets to work with. Sets reference entities like bodies or nodes. They are usefull because you can deal with a bunch of entities at once. See the section 'How to define a set of entities' about how to create them.

You can write a file with basic commands like "pnt" to create the basis for your construction and read it with the "read' command. Most commands can be used in batch mode. This allows the user to write a command file for repeated actions.

The interactive commands start with the letter ' $q$ '. Please make yourself familiar with all of them before you start to model complex geometry.

After the geometry is created, the divisions of the lines can be changed to control the density of the elements. Display the lines and their divisions with

- "plot ld all".

To change the element division, use

- "qdiv'.

The default division is "4". With a division of" 4 ," a line will have 6 nodes and will therefore be the edge of two element of the quadratic type. Next, the type of the elements must be defined. This can be done for each of the different sets. A new assignment will replace a previous one. Delete all previous assignments with

- "elty all"
and assign new types with
- "elty all he 20 ".

If a mesh is already defined type

- "del mesh"
and mesh again with
- 'mesh all".

Then choose the menu entity '/Viewing-Show Elements With Light' to see the mesh lighted. Lastly, export the mesh in the calculix solver format with

- "send all abq".

With the "send" command, it is also possible to write boundary conditions, loads and equations to files. The equations are useful to "glue" parts together.

It is advisable to save your work from time to time without exiting the program. This is done with the command

- "savel'.

You leave the program either with

- 'exit'
or with
- "quit'.

Exit will write all geometry to an fbd-file and if a file of this name exists already then the extension of this file will be renamed from fbd to fbb. "quit" closes the program without saving.

A solver input file can be written with the help of an editor (emacs, nedit etc.). If you write a ccx command file, then include the mesh, the boundary conditions etc. with the ccx command "*INCLUDE". After you finished your input-file for the solver (ccx) you might read it by calling the program again with
"cgx -c solverfile.inp"
for a final check. All predefined sets are available together with automatically generated sets which store boundaries, equations and more. These sets start with the " + "-sign. For example the set +bou stores all constrained nodes where the set +bou1, +bou2, +bou3 store the constraints for the individual directions. Further the set + dep and + ind store the dependent and independent nodes involved in equations etc. See which sets are defined with the command

- "prnt se".

Each line starts with the set-index, then the set-name followed by the number of all referenced entities. The sets can be specified by index or name. For example if the index of set "blade" is " 5 " the following commands are equivalent:

- "plot p 5"
- "plot p blade"

Predefined loads are stored as 'Datasets' to be visualized. Sets with the name of the load-type (CLOAD, DLOAD) store the related nodes, faces or elements. Use the command

- 'plot'
or
- "plus
to visualize entities of sets.
Then run the input file with ccx. The result file (.frd) can be visualized with
"cgx filename.frd filename.inp"
were the solver input file "filename.inp" is optional. With this file, the sets, boundary conditions and loads used in the calculation are available together with the results.

If you have problems doing the above or if you want to learn more and in more detail about the cgx continue with the tutorial 10 and look in the appendix, section Tips and Hints and Known Problems,

## 5 Program Parameters

```
usage:
cgx [-a|-b|-bg|-c|-duns2d|-duns3d|-isaac2d|-isaac3d|-foam|-ng|-step|-stl]->
            filename [ccxfile]
-a automatic-build-mode, geometry file derived from a
            cad file is expected
-b build-mode, geometry file in fbd-format is expected
-bg background, suppress creation of graphic output
    otherwhise as -b, geometry (command) file must be provided
-c read an solver input file (ccx, Abaqus)
-duns2d read duns result files (2D)
-duns3d read duns result files (3D)
-isaac2d read isaac result files (2D)
-isaac3d read isaac result files (3D)
-foam read the OpenFOAM result directory structure
-ng read Netgen native format (with surface domains)
-step read an ascii-step file (points and lines only)
-stl read an ascii-stl file (triangles)
[-v] (default) read a result file in frd-format and optional
            a solver input file (ccx) in addition which provides the
            sets and loads used in the calculation.
special purpose options:
    -mksets make node-sets from *DLOAD-values (setname:''_<value>'')
-read forces the program to read the complete result-file
                    at startup
```

If no option is provided then a result-file (frd) is assumed, see 'Result Format'.
A file containing commands or geometric informations is assumed if the option -b is specified. Such a file will be created if you use 'exit' or "save' after you have interactively created geometry. Option -a awaits the same format as option -b but merging, defining of line-divisions and the calculation of the interior of the surfaces is done automatically and the illuminated structure is presented after startup. This should be used if the commandfile was generated by an interface-program which convertes cad-data to cgx-format (for example vda2fbd). With option -a and -b the program will start also if no file is specified.

An input file for the solver can be read with option -c. Certain key-words are known and the affected nodes or elements are stored in sets. For example the default set(s) +bou(dof) store nodes which are restricted in the corresponding degree of freedom and the set(s) $+\operatorname{dep}($ dof $)$ and $+\operatorname{ind}($ dof $)$ store dependent and independent nodes used in equations.

A special case is OpenFOAM. The results are organized in a directory structure consisting of a case containing time-directories in which the result-files are stored. The user must call cgx using the case-directory (cgx -foam case). The
program will then search the time-directories. The time directories must contain a time-file to be recognized. Or in other words each directory in this level containing a time-file is regarded as a result directory.

## 6 Input Devices

### 6.1 Mouse

The mouse is used to manipulate the view-point and scaling of the object inside the drawing area (figure 2). Rotation of the object is controlled by the left mouse button, zoom in and out by the middle mouse button and translation of the object is controlled by the right mouse button. Inside the menu area, the mouse triggers the main menu with the left button.

In addition the mouse controls the animation of nodal values. The animation will stop if the mouse pointer is not in the drawing area but will start again if the pointer enters the drawing area. This can be prevented by pressing the middle mouse button while the mouse pointer is in the menu area. Pressing the right button will release the next frame. A frozen animation can be released by pressing the middle button. The previous frame can be reloaded by pressing the middle mouse button twice and the right button once (while the mouse is in the menu area).

### 6.2 Keyboard

The Keyboard is used for command line input and specifying the type of entities when selecting them with the mouse pointer. The command line is preferable in situations where pure mouse operation is not convenient (i.e. to define a certain value) or for batch controlled operations. Therefore most commands are only available over the command line. The stream coming from the keyboard is echoed in the parent-xterm but during typing the mouse pointer must stay inside the main window. Otherwise the commands will not be recognized by the program.

The following special keys are used:

```
Special Keys:
    ARROW_UP: previous command
    ARROW_DOWN: next command
    PAGE_UP: entities of previous set (if the last command was
    plot or plus) or the previous Loadcase
    PAGE_DOWN: entities of next set (if the last command was
plot or plus) or the next Loadcase
```



Figure 2: structure of the main-window

## 7 Menu

The main menu pops up when pressing the left mouse-button inside the menuarea (figure 3). It should be noted that there are equivalent command-line functions for most of the menu-functions. This can be used for batch-controlled post-processing. Next the entities inside the main menu will be explained:

### 7.1 Datasets

Datasets are selected with the menu-item "Dataset". A dataset is a block of nodal values. These could be displacements due to a linear analysis or for a specific time-step during a nonlinear analysis. It could also contain other values like stresses, strains, temperatures or something else. To select a dataset, make sure that the mouse-pointer is inside the menu area. Then, press the left mouse button and move the mouse-pointer over the menu entry "Dataset", then continue to the right. A sub-menu pops up showing all available datasets with a leading number and sometimes followed by a dataset-value (usually time or frequency) and a dataset-description. Move the mouse-pointer over a dataset you are interested in and release the left mouse button. The dataset is now selected. A results ' 'Entity' must be chosen to see the values in the drawing-


Figure 3: structure of the main-menu
area. This Dataset might also contain automatically calculated values like the v. Mises stress and the maximum principal stress (see Pre-defined Calculations and Result Format). See also the command " ds ' to control the functionality with the command-line.

### 7.1.1 Entity

To view data from the dataset, its also necessary to specify the entity (i.e. dx for a displacement Dataset). It works in the same way as for selecting the dataset but instead of releasing the left mouse button over a Dataset continue to the bottom of the sub-menu to "Entity." Continue from that item to the right and release the mouse button when the pointer is over an entity. Now the data is displayed in the drawing-area.

### 7.2 Viewing

In the following sections, changing properties and styles of the displayed structure are explained. See the command 'view' to control the functions with the command-line.

### 7.2.1 Show Elements With Light

This is the default view of the mesh if the program was started in viewing mode. If used, any animation will be interrupted and no values are displayed.

### 7.2.2 Show Bad Elements

This option presents elements which have a negative Jacobian value at least at one integration point. The solver ccx can not deal with those elements. So far, only TET and HEX elements are checked. These elements are stored in the set called -NJBY. See also the command 'eqal'.

### 7.2.3 Fill

This is the default mode and forces the element faces to be rendered.

### 7.2.4 Lines

The edges of the element faces are displayed. This is especially useful to see into the structure to find hot spots in the displayed field. With "Toggle Move-Z/Zoom, and ' ${ }^{q c u t}$ ', a more detailed analysis can follow. For very dense meshes switch to ' Dots'

### 7.2.5 Dots

The corners of the element faces will be displayed. This is especially useful if values inside the structure need checked.

### 7.2.6 Toggle Culling Back/Front

This removes the faces of volume elements for all elements or for the surface of the structure, depending on the state of "Toggle Surfaces/Volumes'. With this option, the user can visualize internal structures like cracks or a core of a hollow structure.
For shell elements, the behavior is different. Initially only the front faces are illuminated and the back faces are dark. This is helpful to determine the orientation of the elements. If you want to see all faces of the shell-elements illuminated regardless of the orientation, then use this option. If you want to change the orientation use the command ' qfl '.

### 7.2.7 Toggle Model Edges

Per default, all free element edges are shown. The user can remove/show them with this option.

### 7.2.8 Toggle Element Edges

Per default, just the free element edges are shown. The user might add all edges to the structure with that option.

### 7.2.9 Toggle Surfaces/Volumes

This switches the way each volume elements are displayed. Either all faces of the elements or just the element faces on the surface of the structure are displayed. Depending on the state of "Toggle Culling Back/Front", either the faces pointing to the user or the faces pointing away are displayed. The default is just to show the surface pointing to the user. In the lower left corner of the drawing area,(see figure 2) a character is printed, indicating the program is in the surface mode "s" or in the volume mode "v".

### 7.2.10 Toggle Move-Z/Zoom

Instead of zooming in with the help of the middle mouse button, it is also possible to move a clipping plane through the structure to get a view of the inside. The clipping plane is parallel to the screen and will be moved in the direction to and from the user by pressing the middle mouse button and moving the pointer up and down while inside the drawing area. Usually it needs some mouse movements until the clipping plane has reached the structure. Depending on hardware, this functionality could be slow. After zooming in, consider using the ',plot' and 'plus' commands to customize your view.

### 7.2.11 Toggle Background Color

With this option, it is possible to switch between a black and a white background.

### 7.2.12 Toggle Vector-Plot

It is possible to add small "needles" to the plot which point with their heads in the direction of the vectors. Only entities which are marked in the database as vectors will be affected. See 'Nodal Results Block' for information on how entities are marked as vectors. Internally calculated vector-results, like the worst principal stress, are marked automatically. If one component or the value of a vector is selected, then the option takes immediate effect.

This option can be used in combination with "Animate Toggle Dataset Sequence'.
See also the keyboard command ' ${ }^{d s}$ ' how to select datasets and entities with the keyboard. In this case, entities which are NOT marked in the dataset as
vectors can be displayed with vector-needles. This command line approach with "ds" is the only way to display duns-cfd-results with vector-needles. See also the command "scal' how to manipulate the length of the vectors.

### 7.2.13 Toggle Add-Displacement

It is possible to display results on the deformed structure. For example, you can display a stress field on the deformed structure. If you know a suitable amplification factor for your displacements then use the 'scal' command to issue this value but this can also be done later. Of course displacements for the Loadcase must be available.

### 7.3 Animate

This option allows the animation of displacements. See also " ds' and 'scal' to use this functionality with the command-line.

It is possible to create this sequence from just one Dataset, see 'Start'. This is useful for displaying mode-shapes. See also '"Toggle Dataset Sequence' to create a sequence from multiple Datasets to visualize dynamic responses.

### 7.3.1 Start

Creates a sequence of display-lists to visualize displacements (for example modeshapes). The program recognizes displacements just by the name of the dataset. This name must start with the letters "DISP", otherwise the animation will not start (see 'Nodal Results Block').

### 7.3.2 Tune-Value

Controls the amplitude of the animation. If '"Toggle Real Displacements' was chosen before, the tune-value is equivalent to the amplification of the animation.

### 7.3.3 Steps per Period

Determines how many display lists for one period of animation will be used. If "Toggle Dataset Sequence' was chosen, then these number of display lists will be interpreted as one period (see Time per Period).

### 7.3.4 Time per Period

Determines how many seconds per period.

### 7.3.5 Toggle Real Displacements

To see the correct displacement of each node. The animation can be controlled with the help of the mouse,

### 7.3.6 Toggle Dataset Sequence

Creates a sequence of display-lists to visualize values of a sequence of Datasets. The Datasets must use the same type, for example only displacements or only stresses. To activate the animation, after you have selected "Toggle Dataset Sequence" choose the first Dataset to be displayed, then the second and then the last one. Finally choose the entity. The first two datasets define the spacing between the requested datasets and the third-one defines the last dataset to be displayed. The last two selections of datasets can be omitted. Then all datasets which use the same name, starting from the selected one, will be used. The command '"ds' provides the same functionality.

### 7.4 Frame

Adjusts the drawing box.

### 7.5 Zoom

Use this command to zoom into a rectangular section of the window. After this option is chosen, use the mouse to select the opposite corners of a rectangle. The display will zoom in on the rectangular area. Note the rectangle is never shown on the screen (see also "'zoom').

### 7.6 Center

Used to choose a new center point for the structure. After this option is chosen, pick either a node, a point or the corner of an entity. To easily find the element corners, the function 'Toggle Element Edges' is triggered automatically (see also "qcnt').

### 7.7 Enquire

Used to investigate parameters like the value and the position of a certain node of the model. Pick a node after this option is chosen. To easily find the element corners, the function 'Toggle Element Edges' is triggered automatically (see also "qenq]').

### 7.8 Cut

Used to cut elements and to create a section of new elements and nodes. Either pick three nodes, or, in case a dataset-entity of a vector was already selected, use the menu entry "vector" and select just one node. The cutting plane is then determined by the direction of the vector (displacements, worstPS). To easily find the element corners, the function 'Toggle Element Edges' is triggered automatically (see also 'qcut' and "cut')

### 7.9 Graph

Used to generate a 2D-plot. The option "Length" will provide a plot "value over distance between nodes". The option "Datasets" will provide a plot "value over Dataset-nr" and the option"Time" will provide "value over Time". For the later two options it is necessary to first create an animation with either the command " 'ds' or the menu option "Toggle Dataset Sequence' (see also "graph' and 'How to generate a time-history plot'). To easily find the element corners, the function "Toggle Element Edges' is triggered automatically.

### 7.10 Orientation

### 7.10.1 +x View

To look along the x -axis.

### 7.10.2 -x View

To look against the x -axis.

### 7.10.3 +y View

To look along the y -axis.

### 7.10.4 -y View

To look against the $y$-axis.

### 7.10.5 +z View

To look along the z-axis.

### 7.10.6 -z View

To look against the z-axis.

### 7.11 Hardcopy

To create a hard-copy during animation, it is useful to stop the animation first with the middle mouse button while inside the menu area of the main window and then release one picture after the other with the right button until the desired amplitude or step is reached.

### 7.11.1 Tga-Hardcopy

To create a window dump in tga format. You might use the program "convert" [11] to convert this format to others.

### 7.11.2 Ps-Hardcopy

To create a window dump in postscript format. The program convert must be installed.

### 7.11.3 Gif-Hardcopy

To create a window dump in gif format. The program convert must be installed.

### 7.11.4 Png-Hardcopy

To create a window dump in png format. The program convert must be installed.

### 7.11.5 Start Recording Gif-Movie

All frames during an animation are stored. The recording ends after the right mouse button is pressed while in the menu area. Finally all frames are combined in the file "movie.gif" which can be displayed with various tools (Firefox [12] or realplay). If the animation is stopped with the middle mouse button while in the menu area, then the movie stops until it is released by pressing the middle mouse button again. See "movi' for the keyboard options. Further remarks in "How to change the format of the movie file'.

### 7.12 Help

Starts the html help and displays this document. It only works if the specified html-viewer is available. The default is Firefox [12] but this can be changed in the "cgx.h" file. The search-path for the documentation is also defined in the "cgx.h" file. Please make sure that the documentation is in the specified location or change the path in the "cgx.h" file and recompile the program after the object-files are deleted. The default location for the html help is .../CalculiX/cgx_X.X/doc/cgx and /CalculiX/ccx_X.X/doc/ccx for cgx and ccx respectively. The html files must be downloaded directly or compiled from the latex source for this function to work properly. The INSTALL file tells how to compile the latex code to html. The INSTALL file is located .../CalculiX/cgx_X.X/ and .../CalculiX/ccx_X.X/ for cgx and ccx respectively.

### 7.13 Quit

This terminates the program without a save.

## 8 Commands

This section is a reference to all commands and their parameters in alphabetic order. If a command is typed the mouse-pointer must be in the main window (figure 2). Only the echo of the input stream is visible in the parent xterm. The keywords are not case sensitive but all command parameters are case sensitive.

Each reference starts with a short description of the command. The following syntax is used for these descriptions:

```
Known commands and syntax:
    '..': Keyword (either uppercase or lowercase)
    <..>: Parameter (case-sensitive)
    [..]: combination of parameters or optional parameter
    (..): Remark
    | : OR
    & : AND
    - : from-to
    -> : command continues in the next line
    RETURN press the RETURN key
```

Entities - with the exception of nodes and elements-are referenced by names which can contain letters and numbers. Usually one to four characters is recommended. If a new entity uses an existing name, the old definition will be overwritten. To overcome this problem, "alias" names can be used. An alias name is defined with the ! sign in front. An already defined alias name can be referenced by placing the \% sign in front. For example:

LINE !L1 \%P1 \%P2 \%SET
will create a line with the alias name L1 and will use the alias names P1 and P2 to define the end-points and uses the set SET to define the point sequence between the end-points.

## 8.1 area

```
'area' <set>
```

This keyword is used to calculate the area and the center of gravity of a set of shell-elements or surfaces of volume-elements.

## 8.2 asgn

```
'asgn' 'n'|'e'|'p'|'l'|'c'|'s'|'b'|'S'|'L'|'se'|->
    'sh'|'alpha'|'beta'|'nadapt' <value>
```

This keyword is used to define the first node or element number which will be used for the next mesh generation. And it is used to redefine the leading character of new entities. The default is $D$ for points $p, L$ for lines $l, C$ for combined lines (lcmb) c, A for surfaces s, B for Bodies b, Q for nurb lines (nurl) L, N for nurb surfaces (nurs) S, A for sets se and H for Shapes sh. For example
$\operatorname{asgn} \mathrm{p} U$
will assign the character $U$ as the leading character to all newly created names of points. The automatically created names of geometric entities use 4 characters. If all possible names with the chosen leading letter are in use then the next alphabetical letter is chosen as a leading letter, so after PZZZ follows Q000. If no more letter follow then the amount of letters per name is increased. The maximum number is 8 . Each entity has its own name-space. Different entities might use the same name. Remark: Currently nurbs-lines are automatically used to create splines sharing the same name. Nurbs-lines can not be used for other purposes than to be displayed and so far they can not be written to a file. The unstructured mesher [14] uses the tree parameters alpha, beta, nadapt for mesh-control. Current default is 0.4 for alpha and beta and 4 for nadapt.

## 8.3 bia

```
'bia' <line> [<bias>]|
'bia' <set> [<bias>]|
    ['mult'|'div' <factor>]]
```

This keyword is used to define the bias of a single line or of a set of lines (see qadd). The bias defines the ratio of the length of the first element to the length of the last element. For example,
bia all 4.5
will force a ratio in which the last element is 4.5 times bigger than the first one. Real numbers are permitted since version 1.5 (see also qbia). To convert from pre 1.5 versions, start the program with the -oldbias option.

## 8.4 body

```
    'body' <name(char<9)>|'!' [<surf1> <surf2>]|
    [<surf1> <surf2> <surf3> <surf4> ->
    <surf5> [<surf6> <surf6>]]
```

This keyword is used to define or redefine a volume (body). Each body must have five, six or seven surfaces to be mesh-able. However, it is sufficient to specify just the "top" and the "bottom" surfaces. But if surfaces with 3 or 5 edges are involved then this surfaces have to be the "top" and "bottom" surfaces. This is also true if surfaces have different line-divisions at opposite edges. The missing surfaces between the "top" and "bottom" surfaces will be created automatically if they do not already exist (they will always have 4 edges with the same division on opposide edges). But all needed lines must exist. More precisely, only single lines or existing combined lines (lcmb can be detected. The user must define the missing surface if just a chain of lines (and no lcmb) is defined between two corner points of the "top" and "bottom" surfaces before he can successfully use the body command. It is a more convenient way to
define a body than the command 'gbod]' but exactly 2 or all surfaces must be specified otherwise the body will not be created (The most convenient way to define bodies is to use the command 'qbod'). For example,
body b1 s1 s2
will look for the missing surfaces and if necessary create them if all lines between the corner points of s1 and s2 are defined; the result is the creation of body, b1. Or for example,
body! s1 s2 s3 s4 s5
will create a body and a new name for it. The new name is triggered by the sign !. Here the body is based on 5 surfaces. If the surfaces are not connected, the body is not mesh-able.

## 8.5 call <br> 'call' <parameters>

This keyword is used to allow the user to control his own functionality in the file "userFunction.c". The data-structures for the mesh and datasets are available. The default function calculates the hydrodynamic stresses with the command:
call hydro
See 'User-Functions' for details.

## 8.6 cntr

'cntr' <pnt|nod>
Defines a new center-point or -node. This command is intended for batch-mode. See also 'qcnt' for the cursor controlled command.

## 8.7 comp

'comp' <set|*chars*> 'u'|'d'|'e'
This keyword is used to add all entities to the specified set (seeseta) which depend on the already included entities ( $u$, up), or to include all entities necessary to describe the already included entities (d, down).
For example the set "lines" stores lines and should also include all dependent points:
comp lines do

Or the set "lines" should also include all surfs and bodies which depend on the lines:
comp lines up
In some cases you will need only the end-points of lines. With the option (e, edges)
comp lines e
only end-points are included in the set. One exception to this logic was introduced for convenience:
comp nodes do
will add all faces described by the nodes in set nodes despite the fact that faces are made from nodes.

Wildcards $\left(^{*}\right)$ can be used to search for setnames of a certain expression:
comp E* do
will complete all sets starting with "E".

## 8.8 copy

```
    'copy' <set> <new_set> ['scal' <fx> <fy> <fz> <pnt> [a] ]|
    ['tra' <dx> <dy> <dz> [a]]|
    ['rot' <p1> <p2> <alfa> [a] ]|
    ['rot' 'x'|'y'|'z'|'p'<PNT> <dr> [a] ]|
    ['rad' <p1> <p2> <alfa>]|
    ['rad' 'x'|'y'|'z'|'p'<PNT> <dr> [a] ]|
    ['mir' <P1> <P2> [a] ]
```

This keyword is used to create a copy of a set (see seta about sets). Geometry, nodes and elements with their results can be copied. The copy of results is usefull to evaluate additional sectors in case of a cyclic symmetric calculation. The copy is included in the new set. Existing sets are extended by the copied entities if the last parameter "a" (append) is provided. Several transformations are available. For example scal creates a scaled copy, the scaling factors fx, fy, fz can be chosen independently,

Several transformations are available. For example scal creates a scaled copy, the scaling factors $\mathrm{fx}, \mathrm{fy}, \mathrm{fz}$ can be chosen independently,
copy part1 part2 scal 2 P0
copy part1 part2 scal 112 P 0
tra will create a copy and will move it away by the vector dx , dy , dz and the optional parameter a will assign the new entities to sets were the mother of each entity is included,
copy set1 set2 tra 102030 a
rot will create a copy and will move it around the axis defined by the points p 1 and p 2 by alfa degrees,
copy set1 set2 rot p0 px 20.
rad will create a copy and will move it radially to the x -, y - or z -axis or will create a spherical section if just a single point is defined,
copy cylinder1 cylinder2 rad x 20 .
copy sphere1 sphere2 rad pP0 10.
mir will create a mirrored copy. The mirror-plane is placed normal to the direction running from P1 to P2 and placed at P2,
copy section1 section2 mir P1 P2.

## 8.9 corrad

'corrad' <set>
This is a very special command to adjust improperly defined arc-lines, like in fillets. The center points of arc-lines included in the set are moved in a way that each arc-line will run tangentially into a connected straight line. But because the end-points of the arc-lines are not moved only one side of each arc-line will run into a connected line. The other side is not controlled and might end in a sharp corner. Therefore for each arc-line exactly one connected straight line must be included into the set (figure (4).

### 8.10 cut

```
'cut' <pnt|nod> [<pnt|nod> <pnt|nod>]
```

This keyword is used to define a cutting plane through elements to visualize internal results. The plane is either defined by three nodes or points, or, in case a dataset-entity of a vector was already selected, by just one node or point. The cutting plane is then determined by the direction of the vector (displacements, worstPS). The menu option 'Show Elements With Light' or the commands "ucut', "Viewsurf" or"view volu" will display the whole model again and will delete the plane. This command is intended for batch-mode. See 'qqut' for the cursor controlled command.


Figure 4: Effect of the corrad command

### 8.11 del <br> 'del' ['p'|'l'|'l0'|'c'|'s'|'b'|'t'|'S'|'L'|'se'|'sh' <entity>]| ['se0'] <br> ['mesh']। <br> ['pic']

This keyword is used to delete entities, the whole mesh (see also qdel) or a background-picture. For example,
del se part
will delete the set "part" but all included entities are untouched. The following entities are known:

Points p, Lines l, Combined Lines c, Surfaces s, Bodies b, Node Texts t, Nurb Surfaces S, Nurb Lines L, Sets se and Shapes sh.

When an entity is deleted, all dependent higher entities are deleted as well. Special cases are
del 10 set (lizero¿ ${ }_{\text {B }}$ )
were all lines with zero length in set "set" are deleted and
del se0
will delete all empty sets. If a background-picture was loaded with the "read' command it can be deleted with:
del pic

### 8.12 div

```
'div' <line> [<division>]|
'div' <set> [<division>]|
    ['mult'|'div' <factor-div> <factor-bias>]|
    ['auto' <node-dist> <angle>]
```

This keyword is used to define the division of line(s). The div keyword also works on a set of lines (see qadd). The division controls the number of nodes created when the geometry is meshed (see elty and mesh). For example,
div all 4
attaches the division of 4 to all lines. With the keyword mult or div in combination with a value, it is possible to multiply or divide already assigned divisions:
div all mult 2.
Or in case you need a starting-point for the individual divisions you can use the option auto with the optional parameters node-dist and angle. Node-dist is the maximum allowed distance between nodes and angle is the maximum allowed angle defined by three sequential nodes. If one parameter is not fulfilled then the division is halved. Default values are defined in the file cgx.h
div all auto

Some rules must be fulfilled before a geometry is meshable. For linear elements (ie. qu4 or he8), the sum of all divisions of each surface must be even. In case of quadratic elements (ie. qu8 or he20) this sum must be divisible by 4 without residue. Opposite edges of a given surface might have different divisions. For example on the left side of a given surface the division is 8 and on the right side it is only 4 . But only two opposite surfaces of a body can use this feature. These surfaces are called top and bottom surfaces. All other surfaces of this body must have unique divisions on opposite edges.

### 8.13 ds

```
'ds' <1.Dataset-Nr> <2.Dataset-Nr> <n.Dataset-Nr> 'a'|->
['e' <entity-nr> (up to 4 times)]|
```

['s' <value>]

This keyword is used to define a Datasets and an Entity The Dataset might be a positive number which has to match the nr in the Dataset-menu or an 'l' (lower case ' $L$ ') which is interpreted as the last available Dataset or a negative number. Then it is interpreted as the last minus the specified number. For example
lc 1 e 1
will display the first entity of the first Dataset.
lc le 1
will display the last Dataset. To start the animation of the second-to-last Dataset (assuming displacements) right away:
lc -1 a

Also sequences can be defined:
lc 2410 e 1
Here the 1st entity of each second Dataset is selected. The selection starts at the second- and ends at the 10th dataset. If more than one entity is defined then a vector-plot will be displayed. If a 4th entity is defined then this entity will be used for the basic color-plot:
lc 2410 e 12131415

In addition, it is possible to scale the entities of the specified datasets:
lc 1 s 1.2
will scale all entities of dataset 1 by a factor of 1.2 .

### 8.14 elem

```
'elem' <nr> <firstNode> .. <lastNode> 'be2'|'be3'|'tr3'|'tr6'|->
'qu4'|'qu8'|'he8'|'he20'
```

This keyword is used to define elements based on nodes and its type (see section Element Types in the appendix for the correct node-order). For example,
elem 11234 qu4
creates a shell element with four nodes.

### 8.15 elty

```
'elty' <set> 'be2'|'be2d'|'be3'|'tr3'|'tr3u'|'tr3e'|'tr3s'|->
            'tr3c'|'tr6'|'tr6e'|'tr6s'|'tr6c'|'qu4'|'qu4e'|->
            'qu4s'|'qu4c'|'qu8'|'qu8e'|'qu8s'|'qu8c'|'he8'|->
            'he8f'|'he8i'|'he8r'|'he20'|'he20r'
```

This keyword is used to assign a specific element type to a set of entities (see section Element Types in the appendix). The element name is composed of the following parts: The leading two letters define the shape (be: beam, tr: triangle, qu: quadrangle, he: hexahedra), then the number of nodes and at last an attribute describing the mathematical formulation or other features (c: axisymmetric, e: plain strain, s: plain stress, u: unstructured mesh, r: reduced integration, i: incompatible modes, f: fluid element for ccx). If the element type is omitted, the assignment is deleted. If all parameters are omitted, the actual assignments are posted:
elty
will print only the sets with assigned elements. Multiple definitions are possible. For example,
elty all
deletes all element definitions. If the geometry was already meshed, the mesh will NOT be deleted. If the mesh command is executed again after new assignments has taken place, additional elements will be created.
elty all he20
assigns 20 node brick-elements to all bodies in the set all.
elty part1 he8
redefines that definition for all bodies in the set part1.
elty part2 qu8
assigns 8 node shell elements to all surfaces in set part2.
Be aware of the command 'mids' to remove or include mid-side nodes of elements. Especially if you use the unstructured element-type tr3u. In this case you might change the linear triangles to tr6 elements with this command.

```
8.16 enq
    'enq' <set> <set> ['set' <setname> ]| ->
    ['rec' <x-value>|',' <y-value>|',' <z-value>|' _' ]| ->
```

```
['cyl' 'x'|'y'|'z' <r-value>|' _' <axis-value>|' _' ] ->
    'tol' 'i'|'a'|'h'|'l' [<value>]
```

This command is used to locate entities from a certain set (first provided set) and stores them in the second set. The following entities are handled: nodes, points, lines, surfaces. But surfaces can only be identified if the command 'rep <setname>" was issued before. In case of nodes with related values (results) it will also determine the highes or lowest value in the specified range, or, all nodes above or below a certain value. The coordinates might be taken from one node or point in a given 3rd set or given in cartesian coordinates (option rec) or cylindrical coordinates (option cyl). Some coordinates might be omitted to specify an infinite range. The '_' key has to be used in this case. The mode is defined by the keys 'i' individual, 'a' all, 'h' high, 'l' low, were h and l will search the highest or lowest value in range. This value will also be written to a file for automatic processing purposes. For example
enq all newset rec 10. _ 100. 0.1 i
will search for entities in set 'all' at the given location $\mathrm{x}: 10 . \mathrm{y}$ :_(infinite range, triggered by the ',' key) z:100. with a tolerance of 0.1 and only the closest entity of all kinds of entities are stored in set 'newset', triggered by the 'i' key. With the 'a' key all in range would be stored. The key 'h' or 'l' would trigger a search for the highest or lowest value in the specified range.

In combination with a certain value
enq all newset rec 10. _ 100. 0.1 h 1013.
all nodes with a value above "1013." would be stored in set "newset". The command
enq domain1 newset cyl x 100. 10. 0.1 a
will search for entities in set 'domain1' at radius:100. around x at $\mathrm{x}: 10$. with a tolerance of 0.1 . All entities in range are stored in set 'newset'.

The following example illustrates the use of "enq" to find the highest value close to a location given by a node-number:

```
# activate dataset 3 with entity 7:
ds 3 e 7
# read a file with one node to define a set:
read pos1.frd pos1
# search the highest value around a radius of 1:
enq all t set pos1 1. h
# move the file with the search result to a meaningfull name:
sys mv enq_lc3_e7_1.out pos1.out
```


### 8.17 eqal

'eqal' 'jbir'|'aspr'|'mca' <value>
The keyword without parameters lists the current element quality thresholds ( $0==$ off):

- JBIR: The maximum ratio of jacobian determinants xsj between all gauspoints. Were $\mathrm{xsj}=$ Vworldcoordinates $/$ Velementcoordinates and jbir $=$ xsj-max / xsj-min.
- ASPR: Element aspect ratio between all element sides.
- MCA: Maximum corner angle between all element sides.

With parameter "value" sets the value of the threshold.

### 8.18 exit

```
'exit'
```

This command terminates the program and saves the geometry (if any) to a file named as the input file but with the extension .fbd. If a file with that name exists already, then this file will be saved with the new file extension .fbb as a backup (see also save).

### 8.19 flip

'flip' <setname>|<surf> ['auto']
This command changes the orientation of a set of surfaces or a single surface. In case of a single surface with the parameter "auto" all surfaces will be flipped in a way that they share a common direction (in or out of a volume). See also qflp.

### 8.20 flpc <br> 'flpc'

This command changes the colour of the scale. Initialy the default is red for high values and blue for low values. The command will invert the current state.

### 8.21 font

```
'font' 'd'|'l' <value(1-6)>
```

This command changes the drawing-font. Six fonts of different heigh are available:
font d 6
selects the highest font for the drawing area were
font 11
selects the smallest one for the legend. The default is selected if no number is specified:
font d or font l

### 8.22 frame

'frame'
This command fits the model into the drawing area.

### 8.23 gbod

```
'gbod' <name(char<9)>|'!' 'NORM' '+|-' <surf> '+|-' <surf> ->
.. ( 5-7 surfaces )
```

This keyword is used to define or redefine a body in the most basic way (see also 'qbod'). Each body must have five to seven surfaces to be mesh-able. However, the number of recommended surfaces is six. The first two surfaces should be the "top" and the "bottom" surfaces. For example,
gbod B001 NORM - S001 + S002 - S005 - S004 - S003 - S006
will create a body B001. The keyword "NORM" is a necessary placeholder for future functionallity but has no actual meaning. Next, follow the surfaces with a sign " + " or "-" in front that indicates the orientation of each surface. These signs will be corrected automatically if necessary. If the an automatically generated name is desired, then type "!" instead of a name.

### 8.24 gonly <br> 'gonly' 'on'|'off'

This keyword is used to erase the contents of the menu area. Sometimes this is useful for hardcopies.

### 8.25 graph

```
'graph' [<amplitude|*chars*> 'amp' ['l']]|
[<material|*chars*> 'mat' ['l']]|
[<seq> 'length']|
[<set>|'-p' 'nr'|'time'|'descr'|<parameter-name> ->
    [<Dataset-name> <entity-name>|<parameter-name> ] ->
                [<first-Dataset-Nr> <last-Dataset-Nr>] ]
```

This keyword is used to create time history plots of nodal values. The values of the pre-selected nodes stored in the referenced set will be written to a file called "graph.out". A gnuplot command file will be written called "graph.gnu" and executed. The resulting file "graph.ps" will be automatically displayed with the postscript viewer. The default is "ghostview" but this can be changed in the "cgx.h" file before the program is build. See also 'How to generate a time-history plot' for further details.

A set with the nodes of interest must be created (usually with 'qadd') before a graph can be drawn. If the parameter l (length) is used to plot values along the length of a set of nodes then this set has to be of the sequence type (usually created with 'qseq]'):
graph seq length
The length is calculated as the sum of the distances between successive nodes.
Since version 1.8 , there are two ways of operation. One way is to specify the Datasets and the entity as parameters of the command
graph set time DISP D1
which will display the displacement D1 of nodes in "set" vs. the dataset-time of all "DISP" Datasets. The first and the last dataset can be specified optionally.

For the traditional way, a sequence of datasets must have been selected (see Toggle Dataset Sequence). After the selection of the datasets, an Entity must be specified. Then, the user could use the graph command to generate the history-plot of this pre-defined sequence. The command
graph set nr
will display the values on the node-positions vs. the dataset-numbers. The command
graph set time
will display the values on the node-positions vs. the dataset-values (usually time or frequency, see Nodal Results Block parameter "VALUE")) and the command
graph set descr
will display the values on the node-positions vs. the dataset-description (only makes sense if the description is a numerical value. See Nodal Results Block, parameter "TEXT", for the location of this data in the frd-file.

In addition, a second data-file is written "graph.out2" which stores the nodenumber and the node-coordinates and all values at this node-position for all datasets. This file can be used to display values over node-positions, etc. It is up to the user to generate a suitable plot out of this data.

The "graph" files can be edited and combined. For example to plot one type of value vs. another type of value.

If an ccx- or Abaqus-input-file was read then it is also possible to create time history plots of the amplitudes (*AMPLITUDE in ccx) or the materialproperties can be displayed (*MATERIAL in ccx):
graph amplitude-name amp
graph material-name mat
Wildcards $\left(^{*}\right)$ can be used to search for amplitudes or materials of a certain expression. They are listed with all values if the parameter "l" follows after "amp" or "mat":
graph *N* amp l
lists all amplitudes which contain the 'N'-key in its name with all values.
The parameters related to datasets can also be displayed with the graph command:
graph -p time DISP HID
This command plots the nodal-diameters used in a cyclic symmetry calculation over the dataset-value. Only few parameters are written from ccx in frdformat. Other applications might define its own parameters in frd-format (see Parameter Header Record for the format of a parameter record).

### 8.26 grps

## 'grps'

The result format allows to assign elements to a group (frd, see 'Element Definition Block'). One element can only belong to one group. This command creates sets and
stores all elements of a certain group in a certain set called "+grp[nr]".

### 8.27 gsur

```
'gsur' <name(char<9)>|'!' '+|-' 'BLEND|<nurbs>|<shape>' ->
    '+|-' <line|lcmb> '+|-' <line|lcmb> .. (3-5 times)
```

This keyword is used to define or redefine a surface in the most basic way (see also qsur). Each surface which is intended for a regular mesh must have three to five edges which might consist of a single line or a combined line (see $\square \mathrm{cmb}$ ) to be mesh-able. However, the recommend amount of edges is four. For example,
gsur S004 + BLEND - L002 + L00E + L006 - L00C
will create the surface S 004 with a mathematically positive orientation indicated by the "+" sign after the surface name. The keyword "BLEND" indicates that the interior of the surface will be defined according to Coons [13] or a NURBS surface (nurs) or shape (shpe) is referenced. It should be mentioned that only nurbs or shape related surfaces can be meshed with unstructured triangles. Use a " + " or " - " in front of the lines or lcmbs to indicate the orientation. These signs will be corrected automatically if necessary. If the surface is intended for an unstructured mesh it is not necessary to care about the correct orientation of the lines and the number of edges is not limmited. If automatic name generation is desired, then use "!" instead of a name.

### 8.28 gtol <br> 'gtol' [<geometric-tol>]

This keyword is used to enquire the default geometric tolerance:
gtol
Or it is used to set the default geometric tolerance:
gtol value
The merg command will recognize points or nodes as equally located when the distance between them is less than gtol.

### 8.29 hcpy <br> 'hcpy' ['ps'|'xwd'|'gif'|'png']|[make [ls]]|[clean] (def:xwd)

This keyword creates a hardcopy in one of the above formats. Default is xwd. Use the program "convert" to convert to other formats if needed.
hcpy ps
will create a ps file.
hcpy make ls
will bundle all ps files created in one file using the landscape (ls) format. The ls parameter may be omitted. A maximum of six pictures is placed on each page.
hcpy clean
will remove all "hcpy" files. See also the commands "text', "rot', " (ds', "max', and '"min' which might be used in hcpy batch files. These commands should be used in the shown order before using the "hcpy" command.

### 8.30 help

```
'help'
```

This keyword prints a short overview of all commands.

### 8.31 lcmb

```
'lcmb' <name(char<9)>|'!' ['+|-' <line> '+|-' <line> '+|-' ->
<line>..(up to 14 lines)]|
    ['ADD' '+|-' <line> '+|-' <line> ->
'+|-' <line>..(up to 14 lines)]
```

This keyword is used to define, extend or redefine a combined line (lcmb). Combined lines are necessary if the edge of a surface should be made of more than one line. Usually the user does not create lcmb's directly. They are created automatically during the process of defining a surface with the command qsur There is no limitation to the number of lines in a combined line. However with one command, not more than 14 lines can be specified at a time. To specify more than that or to extend an existing lcmb a modify command has to follow. For example,
lcmb U260 + U249 - U248 - U247 - U243 - U237 - U236 - U231 - U219
defines the lcmb U260 with 8 lines and their orientation in the lcmb. The following command
lcmb U260 ADD - U218 - U217
extends the lcmb U260 by two additional lines.

### 8.32 length

'length' <set>
This keyword is used to calculate the length of all lines stored in a set.

### 8.33 line

```
'line' <name(char<9)>|'!' <p1> <p2> <cp|seq> <div>
```

This keyword is used to define or redefine a line. A line depends on points. A line can only be defined if the necessary points are already defined. There are three different types of lines available. The straight line
line 11 p 1 p 24
is defined by: its name 11 (the name could have up to 8 characters), by the points p 1 and p 2 and optionally by the division. The arc
line ! p1 p2 cp 4
needs a center point cp . The radius changes linear from p1 to p2 if the centerpoint cp is excentric. The name is chosen automatically (triggered by the character !). The spline
line 11 p 1 p 2 seq 4
needs a so called sequential-set, seq (use the command seqa to define such a set). This set seq stores the spline points between the end-points in the right order. The spline function is described in [15]. Usually, a line is defined interactively with qlin.

### 8.34 mata

```
    'mata' <Material-Nr> <set>
```

This keyword is used to assign a material-number to a set of elements. Currently, this feature is only useful if the NASTRAN format is used. The material-number is a numeric attribute assigned to each element of the mesh and will be stored with the mesh in the frd-format or nastran-format (see send). For example,
mata 7 part
assigns the material-number 7 to all elements in the set part. Elements can have just one material-number. The default number is 1 . These numbers will be saved with the mesh if the database is written to the file-system with the command:
send all frd or send all nas

If the frd-file is used later, the material-number(s) are available immediately.

### 8.35 map

```
'map' <slave-set> <master-set> [ ->
    ['surf']|
    ['volu']|
    [ 'x'|'y'|'z'|'rx'|'ry'|'rz'] ->
    ] 'ds'[<nr>]
```

This keyword is used to map (or interpolate) values from one mesh to another. For example
map slave master surf ds1
will map the values from Dataset 1 to the nodes of set slave. All available datasets will be mapped if no number follows the "ds" parameter. The parameter "surf" is used for mapping of values from surface to surface (2D to 2D). A typical application would be the mapping of pressure. The parameter "volu" triggers the mapping from a 3D mesh to another 3D mesh of the same shape (i.e. temperatures). The parameters "x,y,z" are used for mapping from 2D to $2 \mathrm{D} / 3 \mathrm{D}$ in the indicated direction. The parameters "rx,ry,rz" are used for rotational mapping of 2 D to $2 \mathrm{D} / 3 \mathrm{D}$ around the $\mathrm{x}, \mathrm{y}, \mathrm{z}$-axis. The "master"-nodes must belong to elements. Unconnected nodes are not allowed. Usually the master nodes (on which the values are known) were included from an external result file with the 'read' command (with the parameter "add"). For further details see 'How to map loads' in the appendix.

### 8.36 mats

```
'mats'
```

This keyword is used to get an overview of all material numbers defined. New sets will be created for all material numbers of elements. This feature is usually used if a mesh with mateial numbers was read. For example if a native-netgen file [4] was read then this command will generate sets which can be used to asign boundary conditions.

### 8.37 max

'max' <value>
This keyword is used to define the upper value of the scale in the menu area (see figure 2).

### 8.38 merg

'merg' 'n'|'e'|'p'|'l'|'c'|'s' <set> <gtol> 'nolock'
This keyword is used to merge close points and nodes or equally defined entities. The following entities are known: Nodes n, Elements e, Points p, Lines l, Combined Lines c, Surfaces s. For example, to merge points included in the set point-set type
merg p point-set
Only entities included in the set are considered. The value gtol determines the maximum distance between merged nodes and points. The parameter nolock will force merging even if the dependent entities, like lines, are degenerated afterwards. For example, a degenerate line will have two equal points.

### 8.39 mesh

```
'mesh' <set> ['fast'] ['block'|'lonly'|'nolength'|'noangle'|'length'|'angle']
```

This keyword is used to start the meshing of the model. before using the mesh command, the element types must be defined with the elty command. Existing elements will not be deleted. Therefore, its possible to start cgx in the viewing mode (-v) with a mesh alone, and then create bodies and fill them with additional elements. To delete a mesh use the command del mesh. See the command "send' to describe areas for boundary-conditions.

In case a blocked grid for cfd-calculations should be generated, use the additional parameter "block":
mesh setname block
see also the section 'Remarks Concerning Duns and Isaad'.
The mesh optimizer is controlled with the additional parameters "nolength" and "noangle". These parameters switch off length and angle optimizations of elements. The parameter "fast" suppresses the Nurbs-based meshing and uses the fast coons-algorithm for surface meshing.

Usually all elements are generated in a structured way. That means that no holes in a surface or volume are permitted. The only exception is the element type "tr3u". This type is generated in an unstructured way using the mesher from [14]. In this case, holes are permitted and a surface coming from a cad system should be meshable. Unfortunately it does not work for all possible combinations of divisions or all possible shapes of surfaces. Also, the surface MUST reference a given NURBS-surface or a shape to be meshable. This is usually
the case if the data is derived from a cad-system with the interface-program (vda2fbd).

### 8.40 mids

```
    'mids' <set> ['lin'|'gen'|'rem']
```

This keyword is used correct the midside node-position of higher order elements stored in a set. It is performed automatically if a new mesh is created or if nodes are projected to target surfaces. The correction will use a circular track defined by the corner-nodes and the midside node. With the parameter "lin," the corrected position is halfway between the corner-nodes for all inner nodes. Nodes on the surface are not affected by the lin option. The "gen" option will generate midside nodes for linear elements like he8 or te4. The "rem" option will remove midside nodes from the element formulation but the nodes are not deleted. The nodes are stored in a new set called "-delete" and the user might "zap' this set.

### 8.41 min

```
'min' <value>
```

This keyword is used to define the lower value in the scale in the menu area (see figure (2).

### 8.42 minus

```
'minus' 'n'|'e'|'p'|'l'|'s'|'b'|'S'|'L'|'sh' <set>
```

This keyword is used to remove entities of a set from the screen (see also plus). The following entities are known:

Nodes n, Elements e, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S, Nurb Lines L and Shapes sh

Only the set which was used to display the entities can be used to remove them.

### 8.43 move

```
'move' <set> ['scal' <fx> <fy> <fz> <pnt>]|
    ['tra' <dx> <dy> <dz>]|
    ['rot' <p1> <p2> <alfa>]|
    ['rad' 'x'|'y'|'z'|'p'<pnt> <dr>]|
    ['mir' <P1> <P2>]
```

This keyword is used to move nodes or points in a set. Related entities will be moved as well. For example to move a line it is necessary to include their points in the set (see comp). Several transformations are available:

For example scal will scale the entities of the set, the scaling factors $f x$, fy, fz can be chosen independently and a reference point can be used,
move part scal 2
move part scal 112
move part scal 2 P0
move part scal 112 P 0
tra will move it away by the vector $d x, d y, d z$,
move all tra 102030
rot will move it around the axis defined by the points p 1 and p 2 by alfa degrees,
move all rot p 0 px 20.
rad will move it radially to the $\mathrm{x}-, \mathrm{y}$ - or z -axis or to a single point,
move cylinder rad x 20.
move sphere rad pP0 10 .
mir will mirror the set. The mirror-plane is placed normal to the direction running from P 1 to P 2 and placed at P 2 ,
move part mir P1 P2.

### 8.44 movi

```
'movi' [delay <sec>]|[start]|[stop]|
    [make <pic-nr> <pic-nr> <prolog.gif>]|
    [clean]
```

This keyword is used to start or stop the recording of a movie. After "start" all frames will be stored in single gif files until the "stop" command is issued. See also the menu options "Start Recording Gif-Movie'. Use the option "make" to assemble the movie from the individual files. An existing movie will be copied in front of a range of frames if it is specified as the last argument. The range consists of the nr of the first and last picture to be used. With the option "delay," a time-delay (in seconds) between frames can be specified. With the option "clean," all single gif-files will be erased.

Here is an example command sequences:

```
movi delay 0.01
movi start
movi stop
movi make 0 500
movi make 0 500 prolog.gif
movi clean
```

Further remarks in 'How to change the format of the movie file'.

### 8.45 msg

```
'msg' 'on|off'
```

This keyword is used to enable or disable full printout during runtime. This is useful for debugging purposes. The default is "off".

### 8.46 node

'node' <nr> <x> <y> <z>
This keyword is used to define or redefine a node. For example
node 23580 10. 0. 1.
defines a node with the number 23580 at the position $\mathrm{x}=10, \mathrm{y}=0, \mathrm{z}=1$.

### 8.47 nurl

```
'nurl' <name(char9)>|'!' ['DEFINE' ['COMPACT'] <pstart> <pend> ->
    <deg> <npnt> <nknt> <div>]|
    ['CONTROL' <index> [<pnt>||x y z>] <weight>]|
    ['KNOT' <index> <value>]|
    ['END']
```

This keyword is used to define a nurbs line. So far, this command is only used to read a nurbs-line definition. Nurbs lines are converted automatically into a spline. Nurbs lines can be displayed but not saved. There are two possible ways of definition. Either by using predefined point-names or by specifying the coordinates explicitly. When the coordinates are defined, the parameter "COMPACT" must be used as shown above. When the point names are used, then "COMPACT" must be omitted. CAD-interfaces might use this functionality.

### 8.48 nurs

```
'nurs' [<name(char9)>|'!' ['DEFINE' ['COMPACT'] <u.deg> <v.deg> ->
                        <u.npnt> <v.npnt> <u.nknt> <v.nknt>]|
                        ['CONTROL' <u.index> <v.index> [<pnt>|<x y z>] ->
                        <weight>]|
                        ['KNOT' <U>|<V> <index> <value>]|
    ['END']] |
    [ <!> <setname(containing surfaces)>]
```

This keyword is used to define a nurbs shape. Surfaces might use nurbs to define the interior geometry. There are two possible ways of definition. The first is using predefined point names and the second is by specifying the coordinates explicitly. When the coordinates are defined, then the parameter "COMPACT" must be used as shown above but when point names are used, then "COMPACT" must be omitted. CAD-interfaces might use this functionality.

REMARK: The knot-vector has to have a multiplicity of "degree +1 ".
There is also a small nurbs-building capability in cgx. It is possible to use existing surfaces (with 4 edges) which do not already reference a given nurbs. The new nurbs will follow the Coons-algorithm but can be modified by moving the control points. The surfaces must be stored in a set. For example,
nurs! surfaceSet
will define nurbs for all surfaces stored in the set surfaceSet. This nurbs can be used to define the interiour of other surfaces. This is necessary if "tr3u" elements (unstructured triangles) should be used and if the surface is not related to a given shape.

### 8.49 ori <br> 'ori' <set>

This keyword is used to trigger the orientation of the entities. This is done automatically and it should never be necessary to use it manually.

### 8.50 plot

```
'plot' ['n'|'e'|'f'|'p'|'l'|'s'|'b'|'S'|'L'|'sh'|'si']\&->
    ['a'|'d'|'p'|'q'|'t'|'v'] ->
    <set> 'w'|'k'|'r'|'g'|'b'|'y'|'m'|'n'|'t'
```

This keyword is used to display the entities of a set. Entities already visible will be erased. The following types of entities are known:

Nodes n, Elements e, Faces f, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S, Nurb Lines L, Shapes sh and the shaded (illuminated) surfaces si

The entities can be displayed in the following colors:
White w, Black k, Red r, Green g, Blue b, Yellow y, Magenta m, Nickel 'n' (metallic grey) and turquois t

To display the entities with attributes, use the type in combination with an attribute (second letter). For example
plot la all
will display all lines with their names. The attribute d works only for lines,
plot ld all
will display all lines with their division and bias (see bia). The division is given by the last two numbers (1-99) and the bias by the leading number. If there is more than one number in front of the division, the number has to be divided by a factor of ten to get the bias ( 10130 means a bias of 10.1 and a div of 30 ). Also, the attribute p works only for lines. In this case the lines with its end-points are drawn:
plot lp all
This is useful to detect the begin and end of all lines. If end-points are deleted, the line is also deleted. Therefore special care with end-points is necessary. Shaded surfaces
plot si all
can only be displayed if the interiour was previously calculated, which is done with the command 'repl' . The attribute $t$ applies only to nodes and will display only the ones which have attached texts:
plot nt all
will display only the nodes which have attached texts out of the set 'all'. They are created with 'qadd', "qenqi' or "qtxt'.

The attribute q works only for elements. With this attribute, only elements which do not pass the element-quality check are displayed:
plot eq all
The threshold for the element-quality is defined with "eqal'. The attribute
v works only for nodes,
plot nv set1
will display the nodes in set set1 with their values. This is only meaningful in post-processing mode (see Datasets how to assign values to nodes). To plot additional entities, see plus

### 8.51 plus

```
'plus' ['n'|'e'|'f'|'p'|'l'|'s'|'b'|'S'|'L'|'sh'|'si']& ->
    ['a'|'d'|'p'|'q'|'t'|'v'] ->
    <set> 'w'|'k'|'r'|'g'|'b'|'y'|'m'|'n'|'t'
```

This keyword is used to display the entities of an additional set after a plot command was used (see also minus). Further details are explained in section plot.

### 8.52 pnt

```
'pnt' <name(char<9)>|'!' [<x> <y> <z>]|
[<line> <ratio> <times>]|
[<P1> <P2> <ratio> <times>]|
[<setname(containing nodes)>]
```

This keyword is used to define or redefine a point. There are four possibilities to define a point. To define a point just with coordinates:
pnt p1 111.234
or,
pnt! 111.234
where the name is chosen automatically. It is also possible to create points on a line or in the direction from P1 to P2 by defining a spacing (ratio) and number-of-points:
pnt! L1 0.253
or
pnt! P1 P2 0.253
will create 3 new points at the positions $0.25,0.5$ and 0.75 times the length of the line or the distance from P 1 to P 2 , and it is also possible to create points
on the positions of existing nodes. The command
pnt! set
will create new points on the positions of the nodes included in the specified set. Usually when points are defined interactive the command qpnt is used.

### 8.53 prnt

```
'prnt' ['se'|'sq' <RETURN|set|*chars*>]|
    ['n'|'e'|'f'|'p'|'l'|'s'|'b' <entity>]|
    ['amp' <RETURN|amplitude|*chars*>]|
    ['mat' <RETURN|material|*chars*>]
```

This keyword is used to print definition of entities. The following entities are known:

Nodes n, Elements e, Faces f, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S, Nurb Lines L, Sets se and Sequences sq

To see all known sets, type:
prnt se
Or type
prnt sq
to see all known sequential sets (sequences). Wildcards $\left(^{*}\right.$ ) can be used to search for setnames of a certain expression. In this case all sets matching the expression will be listed:
prnt se $\mathrm{N}^{*}$
lists all sets starting with ' N '. To see the contents of a specific set, type
prnt se setName
To print the definition of a line, type
prnt l lineName
If an ccx- or abaqus-input-file was read then it is also possible to print the amplitudes (*AMPLITUDE in ccx) or the material-propperties (*MATERIAL in $\operatorname{ccx}$ ):
prnt amp amplitude-name
prnt mat material-name
. Wildcards (*) can be used.

### 8.54 proj

```
'proj' <set> <target-set>|<shpe> ->
    ['tra' <dx> <dy> <dz> <offset>]|
    ['rot' <p1> <p2> <offset>]|
    ['rot' 'x'|'y'|'z' <offset>]|
    ['rad' <p1> <p2> <offset>]|
    ['rad' 'x'|'y'|'z' <offset>]|
    ['nor' <offset>]
```

This keyword is used to project points (with all related geometry) or nodes onto a set of surfaces or element-faces. Alternative a shape can be specified as the target. In consequence the set with the entities which should be moved must contain nodes and/or points and the target-set must contain surfaces and/or element-faces.

Several transformations are available. For example tra will move points in the direction of the vector $\mathrm{dx}, \mathrm{dy}, \mathrm{dz}$ onto elements or surfaces included in set2. Alternatively an offset could be specified as well,
proj set1 set2 tra 0. 0.50 .7
rot will move points around the axis defined by the points p 1 and p 2 or around the $\mathrm{x}, \mathrm{y}, \mathrm{z}$ axis onto elements or surfaces included in set2,
proj set1 set2 rot p0 px
rad will move points radial to the axis defined by the points p 1 and p 2 or radial to the $\mathrm{x}-$, y - or z -axis onto elements or surfaces included in set2. Alternatively a set of lines could be used instead of surfaces as the target-set. Then the geometry will be moved onto an imaginary rotational surface defined by these lines,
proj set1 set2 rad $x$
nor will move points in a direction normal to the target surface onto surfaces included in set2. An offset might be specified:
proj set1 set2 nor 0.7
If a point does not hit any surface from the target-set, then it will not be
moved.

### 8.55 qadd

'qadd' <set|seq> RETURN <'w'|'a'|'i'|'r'|'n'|'e'|'f'|'p'|'l'| -> 's'|'b'|'S'|'L'|'h'|'m'|'q'|'s'|'t'|'u'>

This keyword is used to add entities to a set. See also seta But a set will not keep the sequence in which the entities were selected. Use seqa or the command 'qseq]' if the order of the selected entities has to be kept.

After an entitiy was selected you get certain informations about the entity. If the node which belongs to the maximum or minimum value in a certain area has to be stored in a set you might use the same key-strokes as described for the command "'qenq]'.

To catch more than one entity with one stroke, type "a" (all) at first. Then create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the selection-rectangle. To catch only the entity which is closest to the user type "i" before.

Then move the mouse pointer over the entity (s) and press one of the following keys, for Nodes n, Elements e, Faces f, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S, node attached texts t and for Nurb Lines L.

Press "q" to quit the command.
It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.56 qali

'qali' RETURN 'w'|'p'|'n'|'q'
This keyword is used to align a plane defined by three points or nodes with the screen (working plane). This is useful if a point or a node should be moved manually along a defined plane (seeqpnt). To define the plane move the mouse pointer over the first entity and press " $n$ " if its a node or a " $p$ " if its a point. Then define the next two entities in the same way. Press "q" to quit the command.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.57 qbia <br> 'qbia' RETURN 'w'|'a'|'i'|'c'|'1'-'9'|' 10'-' 99'|' ${ }^{\prime}$

This keyword is used to change the bias of a line. The bias defines a coarsening or refinement of the mesh along a line. The number defines the ratio of the length of the first element to the length of the last element at a given line. It works by pressing a number between 1 and 9 when the mouse pointer is at the
position of a line. To define numbers between 10 and 99 press the space bar when the mouse pointer is at the position of a line and then the number. To select more than one line with one stroke, type "a" before and create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the rectangle. To select only one line type "i" before. Press "c" to change the direction of the bias. Press "q" to quit the command (see alse bia).

### 8.58 qbod

'qbod' <name>(optional) RETURN 'w'|'b'|'a'|'i'|'r'|'s'|'g'|'q'|'u'
This keyword is used to create a body (see also gbod and body. The user might specify a name in the command-line or by picking an existing body with the key "b". Otherwise the program chooses an unused name. It is possible to create the body out of five to seven surfaces which are needed to define a body or just of two opposite surfaces, but then these two surfaces must be connected on their corner points by lines. To be more precise only single lines or existing combined lines (lcmb) will be detected. If a combined line would be necessary but does not exist then the user should define a surface using this lines which will create the necessary combined-line. Other missed surfaces will be created automatically. To catch more than one surface with one stroke, type "a" before and create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the rectangle. Type "s" to select surfaces. To catch surfaces individually type "i" before (its also the default). After selecting exactly six or two opposite surfaces press "g" to generate the body. Press "q" to quit the command or " u " to undo the last action.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.59 qent

```
'qcnt' RETURN 'w'|'n'|'p'
```

This keyword is used to define a new center-point or -node by pressing "n" or "p" when the mouse pointer is at the position of a node or a point.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.60 qcut

'qcut' RETURN 'w'|'q'|'n'|'p'|'u'|'v'
This keyword is used to define a cutting plane trough elements to visualize internal results (see figure 5). The plane is defined either by picking three nodes (select with key " n ") or points (select with key " p "), or, in case a dataset-entity
of a vector was already selected, by just one node (select with key "v"). The cutting plane is then determined by the direction of the vector (displacements, worstPS ..). Be aware of the key "u" (undo) to return to the un-cutted structure. See also 'cut' for the command-line function.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

| LC39:STRESS |
| :--- |
| Tim:13.000000 |
| Entity:Mises |
| max:$1.33 \mathrm{e}+03$ <br> min: <br> $5.54 e-01$ <br> $5.21 e+02$ <br> $4.98 e+02$ <br> $4.74 e+02$ <br> $4.51 e+02$ <br> $4.27 e+02$ <br> $4.04 e+02$ <br> $3.80 e+02$ <br> $3.57 e+02$ <br> $3.33 e+02$ <br> $3.10 e+02$ <br> $2.86 e+02$ <br> $2.63 e+02$ <br> $2.39 e+02$ <br> $2.16 e+02$ <br> $1.92 e+02$ <br> $1.69 e+02$ <br> $1.46 e+02$ <br> $1.22 e+02$ <br> $9.86 e+01$ <br> $7.51 e+01$ <br> $5.17 e+01$ <br> $2.82 e+01$ |



Figure 5: qcut: A section through a model defined by three nodes

### 8.61 qdel

'qdel' RETURN 'w'|'a'|'i'|'r'|'p'|'l'|'s'|'b'|'S'|'L'|'h'|'q'
This keyword is used to delete entities (see also del). Higher entities (depending ones) will be deleted to. To delete more than one entity with one stroke, type "a" before and create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the rectangle. To delete only one entity type "i" before. Press "q" to quit the command.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated
in the scale of the displayed geometry.

### 8.62 qdis <br> 'qdis' RETURN 'w'|'c'|'n'|'p'|'q'

This keyword is used to measure distances between two nodes or points. Move the mouse pointer over one entity and press the following key, for a node $n$, for a point p or for a center point c . If the key c was pressed then the distance between the two nodes or points are given in cylindrical coordinates. Here lcir is the length of the arc da the angle dr is r2-r1. If no center point was chosen then the distance and its xyz components are given in the Cartesian system. But in addition the cylindrical distances around the origin and around the xyz-axis are also given. Press "q" to quit the command.

- dist: global distance
- $d x, d y, d z:$ distance in the three Cartesian directions
- da: global angle
- dax, day, daz: angle around $x, y, z$
- dr: global radius difference
- drx, dry, drz: radius difference around $x, y, z$

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.63 qdiv

```
'qdiv' RETURN 'w'|'a'|'i'|'1'-'9'|' 10'-' 99'|'q'
```

This keyword is used to change the division of a line by pressing a number between 1 and 9 when the mouse pointer is at the position of a line (see also div). To define numbers between 10 and 99 press the space bar when the mouse pointer is at the position of a line and then the number. To select more than one line with one stroke, type "a" before and create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the rectangle. To select only one line type "i" before. Press "q" to quit the command. General rules are described in "div'.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.64 qele

```
'qele' RETURN 's'|'v'|'n'|'q'
```

This keyword is used to manually define elements. The key " n " selects nodes and the key "s" or " v " generate a surface or volume element based on the node-selection. Mostly used to repair stl files manually.

### 8.65 qenq

```
'qenq' RETURN 'w'|'a'|'i'|'r'|'n'|'e'|'f'|'p'|'l'|'s'|'b'|'S'| ->
'L'|'h'|'m'|'u'|'v'|'t'|'q'
```

This keyword is used to gain information about entities. It is especially useful to get the values on particular nodes.

If the maximum or minimum value in a certain area has to be searched type first " $m$ " to go in the max/min mode and create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the selection-rectangle. Then the key "h" (high) to search the node with the maximum value. The minimum is searched with "l" (low). The search-result is then shown in the xterm and also attached to the node. With the " $u$ " key the last search result can be deleted ("undo"). The 't'-key changes into the "qtxt"mode. The "qtxt' functionallity is now available which allows to manipulate the node-attached-string and its position on the screen. Use "qadd' instead of "qenq" if you need to save the node in a set for further use.

To catch more than one entity with one stroke, type "a" (all) before and create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the rectangle. To catch only the entity which is closest to the user type "i" before.

Then move the mouse pointer over the entity(s) and press one of the following keys, for Nodes n, Elements e, Faces f, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S and for Nurb Lines L.

The position of nodes or points are given in Cartesian and cylindrical coordinates (see figure 6, axyz are the 3 angles around $x, y$ and $z$, rxyz are the 3 radii around $x, y$ and $z$ ). In a second row the sets to which the picked entity belongs are listed.

Press "q" to quit the command.
It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.66 qfil <br> 'qfil' <radius> RETURN 'w'|'l'|'q'

The command creates a fillet line (a radius) between two lines who intersect. After the command-name the value for the fillet-radius has to be specified. Then


Figure 6: qenq: Definition of the cylindrical system
for each pair of selected lines a fillet of this value will be created. Select lines with the "l"-key. Press "q" to quit the command. Currently it works only for straight lines. A curved line can be split and the part which should be used for the fillet can be transformed to a straight form with the "qlin' command ("s" and "x" key-strokes). Figure 7 shows on the right side the initial situation and on the left side the created fillet. The command has also shifted point P002 to the left. Always the end-point of the first selected line closest to the intersection is moved. The second line gets a new end-point.

### 8.67 qflp

```
    'qflp' RETURN 'w'|'e'|'s'|'a'|'i'|'q'
```

This keyword is used to invert the outer- and inner side (the orientation) of shell-elements and surfaces. The orientation of shell-elements or surfaces can be seen by the interior color. The outer face reflects light, if the face is dark-grey it is the back-side. If 'Toggle Culling Back/Front' was selected before then both sides are illuminated. To flip the orientation of a surface and all related shell-elements select either a shell-element with the "e" key or if the illuminated surfaces are displayed (see 'rep]' how to do that) select the surface with the "s" key. To see the effect on the elements immediatelly they must have been


Figure 7: qfil: Based on two intersecting lines a fillet is created
displayed with the "plot' command. If only elements are in the database flip them with the "e" key. The "a" key has a different meaning than usually. If pressed before a selection then a so called auto mode is activated. It makes sense for volumes were a vector pointing in or out can be determined for all surfaces. In this case all related surfaces (and embedded elements) are oriented in the same way as the selected one. It works only in situations were only two surfaces share a common edge. This is the case for volumes without inner surfaces or a 2D model. In case of a volume all surface normals will point either inwards or outwards, depending on the orientation of the selected surface. Press "q" to quit the command.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.68 qint

[^0]This keyword is used to extend two lines to their intersecting location. The end-points of the two lines are moved to the intersecting location but they are not merged. Use the "merg]' command to merge duplicate points. Only straight lines are supported. Select lines with the "l"-key. Press "q" to quit the command.

### 8.69 qlin

```
    'qlin' <name>(optional) RETURN 'w'|'b'|'c'|'e'|'g'|'l'|'m'|'p'|'q'|'s'|'t'|'u'|'x'
```

This keyword is used to create a sequence of lines (or just one, see also line). The user might specify a name in the command-line or by picking an existing line with the key "l". To start a sequence of lines move the mouse pointer over a point and press the key "b" (begin).

To define just a straight line go to the end point and press "g" (generate). This point is also the starting point for the next line. So no "b" is necessary for the next line.

If the line is a sequential line (spline) then the points of the sequence must be defined with the key " t " in the correct order, but the last point must be selected with the key "g".

If the line is an arc then the center point must be selected with the "c" key or one point on the line between the end-points must be selected with the " m " key, but the last point must be selected with the key "g".

In case you need to split a line during the process, you can do that by pressing the "s" key.

When you want to modify the length then pick an existing line with the key "l" and then the endpoint you want to move with the key "p". The displacement is requested and the point is moved in the direction of the line by the specified displacement.

The "x" key will transform the line into a straight line.
One quite special function is triggered by the "e"-key (exchange). This allows to modify an existing combined line (lcmb which is used in surface or body definitions. With that command a line or a line sequence in acmb can be exchanged by the previous generated line. For example one edge of an already existing surface uses a lcmb but the user wants to replace it by a spline then the user defines the new spline and then moves the mouse in an area were one of the old lines (the new one might be present as well) is located and presses the "e" key. The definition of the lcmb will be changed without destroying the surface-definition.

Press "q" to quit the command or "u" to delete the last created line.
It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.70 qnor

```
'qnor' RETURN 'w'|'p'
```

A new line normal to a plane defined by three points is created. It starts at the last point.

### 8.71 qpnt

```
'qpnt' <name>(optional)RETURN 'w'|'p'|'g'|'m'|'n'|'s'|'S'|'u'
```

This keyword is used to create or move points (see also pnt). The user might specify a name in the command-line if a certain name should be used. To create a point move the mouse pointer to the desired location and press the key "g" (generate) or over an existing node and press "n" (uses then the nodecoordinates). After a point was selected with "p" it can be moved in different ways: Either in the screen-plane, for this go to the desired position and press " $m$ " (move). Or the point can be moved to the position of a second point, for this go to the second point which coordinates should be used and press "p" again. If the coordinates of a node should be used press "n" instead. Also a normal projection to a nurbs related surface (from cad-systems) is feasible by choosing the target-surface with the "s" key or a NURBS-surface with the "S" key either before or after the point was marked. See qali or the section Orientation how to rotate the model into a certain position. Press "q" to quit the command or "u" to undo the last action.

If you picked the wrong point (the one which should be moved), just pick the same again and pick then the correct one.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.72 qnod

```
'qnod' RETURN 'W'|'p'|'m'|'u'
```

This keyword is used to move nodes (see also node). To move a node move the mouse pointer to the desired node and press "p" (pick) then go to the desired position and press " $m$ " (move). Seeqali or the section Orientationhow to rotate the model into a certain position. Press "q" to quit the command or "u" to undo the last action.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.73 qrem

'qrem' <set> RETURN 'w'|'a'|'i'|'r'|'n'|'e'|'f'|'p'|'l'|'s'|'b'|'q'

This keyword is used to erase entities from a set (see also setr). To remove entities move the mouse pointer over the entity and press the following keys, for Nodes n, Elements e, Faces f, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S and for Nurb Lines L. To catch more than one entity with one stroke type "a" before and create a rectangular picking area by pressing two times the "r" key. Both strokes define opposite corners of the rectangle. To catch only one entity type "i" before. Press "q" to quit the command.

It is also possible to measure distances between two pixels on the screen. Just press the key " $w$ " on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.74 qseq

'qseq' [<set> RETURN 'n'|'p']|[ RETURN 'nr']
This keyword is used to define a sequence. The sequence might consist of nodes or points. A sequence is nothing else than a set which keeps the selection-order of the entities:
qseq nodeset
will store all selected nodes (selected with the 'n' key) in the order in which they were selected. This set might be used for a subsequent "graph' command. Point sequences are used to define splines. If
qseq
is typed without a setname then an existing line has to be selected with a nummerical keystroke (or the space-bar followed by two numbers). New points will be created on this line which in turn are used to redefine the selected line as a sequence-line which uses the new spline-points. Sequences can be shown with the "prnts" command. Node sequences can be written to a file and read again with the commands "send seqname fbd" and "read seqname.fbd".

### 8.75 qshp <br> 'qshp' RETURN 'w'|'n'|'p'|'g'|'s'|'q'

This keyword is used to define a shape. A shape needs 3 points (or nodes, points at their location will be generated and used) for its definition. The points are selected with the 'p' (nodes 'n') key. After the points are selected it will be generated by a 'g' keystroke. The shape can be assigned to a surface by selecting the surface with the 's' key. The shape will then define the interiour of this surface.

But it is most often used for projection purposes (see "proj') or splitting (see "split').

### 8.76 qspl <br> 'qspl' RETURN 'w'|'s'|'q'

This keyword is used to split one or more lines at a certain position (can also be done with "qlin'). A point is created at the splitting position, the original line is deleted and two new lines will appear instead. All lines running through the selected location will be split at once and the newly created splitting points will be merged to one if they are closer to each other than defined by "gtol'. To split a line move the mouse pointer over the line and press the "s" key. Press "q" to quit the command.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.77 qsur

'qsur' <name>(optional) RETURN
'w'|'a'|'b'|'l'|'i'|'r'|'1'-'g'|'g'|'q'|'u'|'s'|'s'|'h'
This keyword is used to create a surface (see also gsur). The user might specify a name in the command-line or by picking an existing surface with the "s" key.

If the surface is supposed to be meshed with unstructured triangles (element type $\operatorname{tr} 3 \mathrm{u}$ ) it is sufficient to select all lines with the "l" key (lowercase "L"). This can be done either in the "all"-mode (press "a") or "individual"-mode (press " i ") which is default. Then generate the surface by pressing the "g" key. Such surfaces allow holes in it. If the surface is not plane it will need to reference an embedded NURBS surface (see "nurs'). It should be noted that this kind of mesh might be extruded in the 3rd dimension by using the "swep' command. Otherwhise such surfaces can not be used to define meshable bodies (volumes). Only external meshers might use the triangles as a geometry description (see "How to deal with cad-geometry').

For the definition of a regular meshable surface three to five edges must be defined. To create a surface move the mouse pointer over the first line of the first edge and select it with the "1" key (number "one"). If more than one line is necessary to define the first edge select the following ones one after the other with the " 1 " key. Each marked line is listed in the mother xterm. If all lines of the first edge are selected select the lines of the second edge by pressing the " 2 " key, then the third and eventually the fourth and fifth. The last selected line must match the first. All lines defining an edge will create a combined line (see lcmb) and this combined line will show up in the definition of the surface. Then generate the surface by pressing the "g" key and you might continue with the next surface. By default the interior of the surface is defined according to Coons [13] which is a blended function. But it can also follow an embedded NURBS-surface or a shape. To relate the surface to an existing NURBS surface select the NURBS surface with the "S" key (uppercase) or to a shape with the
"h" key. Or replace assignments by the blended function with the "b" key. To quit the command use the "q" key or use "u" to undo the last action.

It is also possible to measure distances between two pixels on the screen. Just press the key "w" on the positions of the two pixels. The distance is calculated in the scale of the displayed geometry.

### 8.78 qtxt <br> 'qtxt' RETURN 'g'|'a'|'i'|'b'|'p'|'m'|'n'|'v'|'f'|'d'|'q'

This keyword is used to move node-attached texts (showing node-number and value, see figure (8) to certain positions in the drawing area or to manipulate them otherwhise. They are created with the key "g" while the mouse-pointer is over the node to which it should be attached. Attention: They are only visible after the command "plus nt all" was used (but they are immediatelly visible when the the commands "qenq]' or "qadd' were used instead of "qtxt"). To move a text pick it at the lower-left corner with the key ' p ' and place it with the key ' $m$ ' in the new location. To move it back to its node use 'b'. Delete them with 'd'. The node-nr and the value in the text can be switched on and off with the ' $n$ ' and 'v' key. The 'f' key will toggle the format of the value between "int", "float" and "exponent". See the command 'font' on how to change the font-size.

To catch more than one entity with one stroke, type 'a' (all) before and create a rectangular picking area by pressing two times the 'r' key. Both strokes define opposite corners of the rectangle. To catch only the entity which is closest to the user type 'i' before.

### 8.79 quit

## 'quit'

This keyword is used to terminate the program without save.

### 8.80 read

```
'read' [<geo-file> ['add']]|
    [<ccx-file> 'inp' ['add'|'ext'|'nom']]|
    [<result-file> ['add'|'ext'|'nom']|[<setname>]]|
    [<list-file> '-n'|'-e'<column>]|
    [<edge-file> 'edg']|
    [<pixel-file>]
```

This keyword is used to read files or commands from a file. Most commands can be read from a file but not all of them. In general all basic commands to create geometry are understood and up to now this is the only way to read pre defined geometry during run-time. To read commands from a file like pnt, line node or seta and so on, type


Figure 8: qtxt: Node attached texts at two locations, one with node-nr and value in exp-form and one just with his value in floating point form. The font with gives biggest numbers was used.
read geo-file
this will eventually replace entities if their names were already in use. To prevent this, type
read geo-file add
this forces the program to change the names which are already in use to unused ones. Therefore no existing geometry will be overwritten.

If an ccx-input-file with loads, boundary-conditions and sets was read
read ccx-file inp
then the loads and boundary-conditions are stored in automatically created
sets which start with a leading ' + '. For example the ccx command '*BOUNDARY' will trigger the creation of the set '+bou'. The ccx sets are stored in cgx sets of the same name. The load-values are stored in Datasets.

The option "nom" (no-mesh)
read ccx-file inp nom
is used to suppress the reading of nodes and elements. This speeds up the reading and makes sense if the mesh exists and only the set-definitions and loads should be read.

If the parameter "add" is used,
read ccx-file inp add
then existing node- or element-numbers are not overwritten and the program choses new numbers. If the ccx-input-file ends with ".inp" the parameter "inp" might be omitted.

The user might read a result-file in frd format during runtime. If a mesh exists and should not be overwritten just add the parameter "add"
read result-file add
this forces the program to change the numbers which are already in use to unused ones. Existing datasets will be extended by the new node-numbers and their data. The option "ext"
read result-file ext
will also extend the existing datasets but in this case the nodes and elements are updated (modified). If no parameter follows then existing nodes and elements are updated and the new datasets will be appended to existing ones.

It is also possible to read files written in the result format (.frd) during runtime only to define sets of nodes or elements without changing the definitions of them. The command
read result-file setname
will create a set of the name setname and all nodes and elements listed in the file mesh.frd will be added to that set. But this will NOT create or modify the nodes and elements. All nodes and elements must exist and will not be changed.

If a file with the numbers of nodes or elements is not available in the result format (.frd) then a so called list-file could be read instead. In such a file either numbers of nodes or elements can be defined. The numbers found in a specified column is interpreted as a node- or element-number. If "-n" is specified the numbers are interpreted as nodes and if " -e " is specified the numbers are
interpreted as elements. For example
read list-file -e3
will define a set storing names of elements from the third column of file listfile.txt. The created set-name is always the name of the file.

In case NETGEN is used for meshing then the edges which are generated by NETGEN can be included for modifications,
read edge-file edg
will create beam elements based on the defined edges. When the modifications are done, the beam elements can be exported in the NETGEN-edge format with the "send setname stl" command (see also 'How to deal with cad-geometry').

If a pixel-file in xwd-format of a certain geometry is available it can be included as a background-picture. The user can then create geometry based on this picture:
read pixelfile
and delete it with "del pic". The picture can not be modified in any way in cgx. So scaling or other modifications to make it fit into cgx have to be made with another software.

### 8.81 rep

'rep' <set>
This keyword is used to refresh entities of a certain set. This is done automatically but with one exception: The rendering of the interior definition of surfaces must be triggered manually with this command. The rendered surfaces can be displayed with "plot' or 'plus' using the type "si".

### 8.82 rnam

```
    'rnam' <set> <set>
```

This keyword is used to rename a set.

### 8.83 rot

$$
\begin{aligned}
& \text { 'rot' ['u'|'d'|'r'|'l'|'c' <angle>]| } \\
& \text { ['x'|'-x'|'y'|'-y'|'z'|'-z'] }
\end{aligned}
$$

This keyword is used to rotate the view-direction to the model. For example
rot u 10
will rotate the view-direction 10 degrees upwards. The meaning of the other letters is down d, right $r$, left l, clockwise c. The remaining letters will rotate the view into a pre-defined direction. For example the user will look in x direction after the command
$\operatorname{rot} \mathrm{x}$
and against the x direction with the command
rot $-x$
and so on.

### 8.84 save

'save'
This keyword is used to save the geometry (if any) to a file named as the input file but with the extension .fbd. If a file with that name exists already, then this file will be saved with the new file extension .fbb as a backup.

### 8.85 scal

'scal' ['s'|'v'|'d'] [<value>]
This keyword is used to scale the graphic presentation of values but no values of entities. The scaling of the value itself can be done with the command '"ds'. For example the command
scal s 0.5
will scale the range of values presented in the color plot by a factor of 0.5. The command
scal v 5.
will scale the length of vectors by a factor of 5 . The command
scal d 2.
will scale the deformed shape by a factor of 2 . Without a value it restores the default value. See also '"Toggle Vector-Plot', '"Toggle Add-Displacement', '"Datasets'.

### 8.86 send

```
'send' <set> 'fbd' ['c','e']| ->
            'stl'| ->
            'abq'|'ans'|'ast'|'dar'|'duns'|'frd'|'gmp'|'nas'| ->
            'ng'|'pat'|'tcg' <RETURN>|
                ['bin']|
                ['ds'<nr>[+] [e<nr>]]|
                ['tmf']|
                ['sta' <refspeed>]|
                ['crp' <timefact> <refspeed> <writefreq>]|
                ['comp']|
                ['mpc' <rotation> <v1> <v2> <v3>]|
                ['names']|
                ['spc' <dofs(1-6)> <value>]| ->
                ['ds'<nr> e<nr>]| ->
                ['nor' <fac1> [<fac2> <fac3>]
            ['slide' 'c'|'s'|'rx'| ->
                'ry'|'rz'|'tx'|'ty'|'tz']|
            ['pres' [<value>]|['ds'<nr> 'e'<nr>] [+|-] ]|
            ['film' [[<temp>]|['ds'<nr> 'e'<nr>]] ->
                [[<coeff>]|['ds'<nr> 'e'<nr>]] [+|-] ]|
            ['rad' [[<temp>]|['ds'<nr> 'e'<nr>]] ->
                [[<emis>|['ds'<nr> 'e'<nr>]] [+|-] ]|
            ['dflux' [[<load>]|['ds'<nr> 'e'<nr>]] [+|-] ]|
            ['cflux' <load>]|
            ['force' <f1> <f2> <f3>]|
            ['quadlin']|
                ['sur' [+|-] ]
'send' <set> ['dolfyn'|'duns'|'isaac'|'foam'] [<base-type> <set>]| ->
    ['cyclic' <set> <set> 'tx'|'ty'|'tz'|'rx'|'ry'|'rz'| ->
                    'cx'|'cy'|'cz'|<vx,vy,vz>]
'send' <dep-set> <indep-set> 'nas'|'abq'|'ans' ['cycmpc' ->
    'px'|'py'|'pz'|'tx'|'ty'|'tz'| ->
    'rx'|'ry'|'rz'|'cx'|'cy'|'cz'<+-segments> 'c'|'u'<NR>]| ->
    ['areampc' <dofs(1-6,t,p)> 'c'|'u'<Nr>]| ->
    ['areampc' 'slide']| ->
    ['areampc' 'presfit' ['s'<value>]]| ->
    ['gap' <vx> <vy> <vz> <tol>]
```

This keyword is used to send data to the file-system. The following formats are known (but not all options for all formats are fully supported so far); The geometry-format (fbd)
send set fbd
send set fbd c
will complete the set downwards before writing, or
send set fbd e
will write all model-edges as small lines running from node to node, and a surface description with triangles (stl)
send all stl

This triangles are based on elements which were created by meshing surfaces or by automatically triangulated element-faces of all types of supported elements. If be2 elements are included in the mesh (meshed lines) a so called edge file for NETGEN will also be created if stl is written. NETGEN provides also a stand-alone mesher called ng_vol. The mesher can be found in the netgen subdirectory nglib. As for the stl-format triangles can be written for this mesher with:
send set ng
It has the advantage that the triangles are directly used to define tetras and not as with stl are only used to define the outer shape of the body.

The following mesh-related formats are known: Femview and CADfix (frd), Nastran (nas), Abaqus (abq), Ansys (ans), CodeAster (ast), Samcef (sam), Darwin (dar), patran (pat, only sets), gagemap (gmp, only sets) and Tochnog (tcg) but only ccx (Abaqus) is fully supported. Good support is also provided for ansys, darwin and nastran. If no further parameter follows then just the definition of the nodes and elements will be written:
send all abq
will write the mesh in the format used by Abaqus and the CalculiX solver. If the parameter "ds" is provided followed by the dataset-nr
send set abq ds1
then the values stored in Dataset 1 are written. For 'frd' the 'ds' parameter w/o any further values forces $\operatorname{cgx}$ to write all datasets but w/o the internally calculated ones:
send all frd ds

If a "+" sign appears at the end of the 'ds' parameter
send all frd ds+
or
send all frd ds1+
then also the internally calculated values like vMises-stress are written. The "bin" parameter has the same meaning as the "ds" parameter but in this case the result is written in the binary form of the frd-format (always all datasets). In case data should be written for the crack analysis tool Darwin
send all dar ds
will write all datasets. Since Darwin changed the format from version 7.1 on, it is possible to change the format with the parameter 'v7.1' as the last parameter. If the set is of the ordered type and includes nodes (see "qseq]') then the data are written in tabular form for use in a 1D crack-prop Darwin-analysis.

Missing lower entities (nodes, points, lines etc.) will be added to the set before the set is written if the parameter "comp" follows. For example geometry like bodies
send set fbd comp
will be extended by surfaces, lines and points or
send set frd comp
will include all nodes used by the elements to the set elem and will then write the file.

The parameter "quadlin" forces the conversion from second order elements into single order elements were each element is subdivided into 8 single order elements. This takes place during writing and will not change the current state of the mesh in cgx. Up to now it is only available for the abq format:
send all abq quadlin
If the parameter "tmf" follows the definition of a solver format
send set abq tmf
then the mesh plus all temperatures with the necessary solver context for tmf calculations is written. If the parameter "sta" follows
send set abq sta 2900 .
then the mesh plus all temperatures with the necessary solver context for a static calculations is written. Here the value for "speed" is a reference value for eventual numerical values in the TEXT-Block of the Datasets in the result file (frd-file, see "Nodal Results Block'). A scaling factor will be determined based on the reference value (here a ref.speed of 2900.) and the individual TEXT-Block values (factor $=$ speed ${ }^{* * 2} /$ refspeed $^{* *}$ ) . This factor is used in *AMPLITUDE commands which will also be written and will be used to scale static loads which are referenced in the *STEP data. If the parameter "crp" follows
send set abq crp 1. 2900. 1
then the mesh plus all temperatures with the necessary solver context for creep calculations is written. Here the value for "timefact" scales the time-values of the Datasets, "speed" is a reference value for scaling static loads (see option "sta") and writefreq limits the output to the result-file.

If the parameter "names" follows the solver-type then just the element- or nodenumbers are written. This is useful for defining sets for the solvers. The command
send steel abq names
will write the node and element numbers included in "steel". This file could be used to define a set for material assignments, boundary conditions or loads. If all sets should be written at once, use:
send all abq nam
If the solver-format "duns" is used then related numbers of surfaces (3D) or lines (2D) will be written. This information is necessary to apply boundaryconditions to duns. The numbers are used in the connectivity file (duns.conn) which will be created by the mesh-command. The user has to refer this numbers in the duns.script2 file when assigning boundary conditions.

It is also possible to define and send some constraints to the file system. To constrain degrees of freedom (dof) of selected nodes use the parameter "spc" in combination with the numbers of the constrained dofs and optionally a forced deflection. For example:
send hinge abq spc 123
will constrain the translational degrees of freedom of the nodes in set "hinge". Or
send hinge abq spc 12356
will leave just one rotational degree of freedom unconstrained. And
send move-nodes abq spc 10.1
will move the nodes in set move-nodes by 0.1 in direction 1 .
send move-nodes abq spc 1 ds1 e1
will use the values from dataset-nr 1 and the entity-nr 1 for the forced displacement in direction 1 and
send move-nodes abq spc nor 0.1
will force the nodes included in set move-nodes by 0.1 in the normal direction (normal to the element-faces). The components of the vectors at the node positions can be scaled individually (fac1-3)). A subsequent calculation with ccx will move the mesh accordingly. After solving the deformed mesh can be used as a new mesh for further calculations. With this procedure geometric variations are possible without manipulating the geometry (morphing).

The parameter "slide" in combination with one additional parameter will create equations that force the selected nodes to move only in a plane. If the additional parameter " $s$ " is specified then the specified nodes will be attached to their element faces. All nodes of the affected element-faces have to be selected. For example you type:
send sur abq slide s
and this should attach the node with the node-nr. 1 to a plane parallel to the surface of the corresponding element-face. This element uses the node 1 , $2,3,4,5,6,7$ and 8 where $1,2,3$ and 4 are on the surface of the mesh. The program will detect this element face and constrain the node only then if the nodes 2,3 and 4 were also included in the set "sur"! The detected elements or faces of volume-elements will be assigned to the set. So it is possible to check the detected elements. Instead of providing a set with the necessary nodes, you might instead provide a set with shell-elements or/and faces of volume-elements. The nodes will be derived from them. In most cases this is the most convenient way.

A special case which works probably only in ccx (abaqus might give wrong results) is triggered by the "c" parameter. It behaves as for the "s" parameter but works for cycsym calcs:
send cycsur abq slide c
A new set with new nodes will be created with the name "<set>_COPY" which has to be used in the cycsym definition in ccx instead of "<set>". In addition equations are specified which connect the new nodes with the original ones
in the normal direction of the element faces. In this way two faces used in a cyclic symmetry connection will slide at each other instead of beeing glued in all directions.

If nodes should slide radially to the y axis then use "ry":
send sur abq slide ry
or use "ty" if the nodes should move only tangential to the y axis. In both cases the axial movement is still permitted.

The parameter "sur" will write the surfaces of the mesh either in abaqusformat for the *SURFACE command or in frd-format as shell elements. For example
send top abq sur
will write the elements in set top together with the face-nr (Important: Only free surfaces of the mesh are regarded, internal faces are unknown and can not be identified). The front- or rear side of the face (pos or neg) is selected with the ' + ' or '-' parameter:
send surset abq sur -
will write all surfaces in set surset in abaqus format but all surfaces which have a potentially negative side will be written in that manner.

The parameter "pres" is used to assign pressure values to element faces. For example
send surf abq pres 0.05
will assign the pressure value 0.05 to all element-faces in set surf. If a dataset with nodal values is available it is also possible to use this values instead of using a uniform value for all faces. For example
send surf abq pres lc1 e1
will specify the dataset-nr 1 and the entity-nr 1 to be used instead of a uniform value. The front- or rear side of the face (pos or neg) is selected with the '+' or '-' parameter (it has to be the last parameter).

The parameter "film" is used to assign free-stream temperatures and thermal heat coefficients to element faces. It works similar to the "pres" option. For example
send surf abq film 1200. 0.5
will assign the film temperature of 1200 and the coefficient 0.5 to all elementfaces in set surf. If datasets with nodal values are available it is also possible to
use this values instead of using a uniform value for all faces. For example
send surf abq film ds1 e1 0.5
will specify the dataset-nr 1 and the entity-nr 1 to be used for the temperature instead of a uniform value, or
send surf abq rad ds1 e1 lc1 e2
will specify also the dataset-nr 1 with the entity-nr 2 to be used for the filmcoefficients instead of a uniform value. The front- or rear side of the face (pos or neg) is selected with the ' + ' or '-' parameter (it has to be the last parameter).

The parameter "rad" is used to assign a sink temperatures and the emissivity to element faces. It works similar to the "pres" option. For example
send surf abq rad 1200. 0.5
will assign the sink temperature of 1200 and the emissivity 0.5 to all elementfaces in set surf. If datasets with nodal values are available it is also possible to use this values instead of using a uniform value for all faces. For example
send surf abq rad lc1 e1 1200.
will specify the dataset-nr 1 and the entity-nr 1 to be used for the temperature instead of a uniform value, or
send surf abq rad lc1 e1 lc1 e2
will specify also the dataset-nr 1 with the entity-nr 2 to be used for the emissivity instead of a uniform value. The front- or rear side of the face (pos or neg) is selected with the ' + ' or '-' parameter (it has to be the last parameter).

The parameter "dflux" is used to assign an energy stream to element faces. It works similar to the "pres" option. For example
send surf abq dflux 0.5
will assign the flux of 0.5 to all element-faces in set surf. If a dataset with nodal values is available it is also possible to use this values instead of using a uniform value for all faces. For example
send surf abq dflux lc1 e1
will specify the dataset-nr 1 and the entity-nr 1 to be used instead of a uniform value. The front- or rear side of the face (pos or neg) is selected with the '+' or '-' parameter (it has to be the last parameter).

The parameter "cflux" is used to assign an energy stream to nodes. For example
send surf abq cflux 0.5
will assign the flux of 0.5 to all nodes in set surf.
The parameter "force" is used to assign force values to nodes. For example
send nodes abq force 1.20. 0 .
will assign the specified forces to all nodes of the set nodes.
The parameter " mpc " is used to create input for the user-subroutine umpc which forces all nodes from "set" to rotate by an average value specified with "rotation" around the vector v . The value has to be in degree were 90 degree is orthogonal. For example
send nodes abq mpc 4. 1. 0. 0 .
will assign the nodes of the set "nodes" to the user-subroutine umpc and will force them to rotate by 4 degree around the x-axis. Two files are produced. The one with the equations has to be included in the model-definition-section and the boundary-file in the step section.

Another useful method are so called "cyclic symmetry" equations. These equations are used when just a section of a rotation-symmetric part like a disk is modeled. These equations force the two cutting planes of such a section to move exactly equal in the cylindrical system. If the coordinate system of the displacements for the solver is rectangular (xyz) then the syntax is:
send dep indep nas cycmpc rx12 c1
Here "dep" is the set containing the nodes of the dependent side. These nodes will be replaced by the solver with the independent nodes from the set "indep". In this case the equations will be written in the nastran format "nas" (in nastran called MPC). The parameter "rx12" defines the displacement system as rectangular " r ", the rotational axis is " x " and the " 12 " defines the number of segments in 360 deg , therefore the angle of the segment is $360 \mathrm{deg} / 12$. Attention: The sign of the number-of-segments must be negative if the angle between the independent side and the dependent side is negative. If the nr-of-segments is omitted then the value is calculated for each node separate. The "c" triggers the correction of the position of the dependent nodes to a position defined by the angle of the segment (highly recommended), "u" would prevent the correction. The " 1 " will be the identifier for the equations if the format is nas (nastran). In case the format would be ans (ansys) then the " 1 " would be the number of the first equation. No number is required for abq (abaqus and calculix). If the coordinate system of the displacements is cylindrical (rtz) then the example
would be:
send dep indep nas cycmpc cx12 c1

Only the " r " from "rx12" is changed to "c". A thermal connection is created with:
send dep indep nas cycmpc tx c
The thermal connection is triggered by the " $t$ ", a pressure connection with "p". See comments above for the single parameters.

In addition it is possible to "glue" independent meshes together. For this purpose the dependent nodes are tied to independent elements by equations. Choose the finer mesh for the dependent side. The equations are based on the shape-functions of the element types. For example
send dep indep nas areampc 123 c1
will connect the nodes in the set dep to element-faces described by nodes included in the set indep. The set dep must contain all nodes which should be "glued" and the set indep should contain all nodes of the elements surfaces to which the dep nodes should be glued. The numbers " 123 " are the degrees of freedom which will be connected ("t" will create a thermal connection, "p" a pressure connection). The "c" triggers the correction of the position of the dependent nodes to a position on the surface of the independent elements (highly recommended and default), "u" would prevent the correction. Of course the mesh has to be written after the use of such a command, otherwhise the corrected node positions would not be regarded and the equations would lead to increased stiffness and decreased accuracy. The " 1 " will be the identifier for the equations if the format is nas (nastran). In case the format would be ans (ansys) then the " 1 " would be the number of the first equation. No number is required for abq (abaqus and calculix), see also 'How to connect independent meshes'.

There is also the "slide" option in combination with the "areampc" option: For example if the mesh of a turbine-blade and a disk should be connected with each other in a simpler but realistic way then a sliding condition between this parts can be established. The command:
send dep indep abq areampc slide
will connect the nodes in the set dep to element-faces described by nodes included in the set indep but only in the direction perpendicular to a plane defined by nodes of the dep-set. Therefore all dep-nodes and all indep-nodes must lie in the same plane and will slide in the same plane!

Another case is considered with the "presfit" option in combination with the "areampc" option. For example if a cylindrical press fit should be simulated
then a forced displacement between the two intersecting surfaces is necessary. This forces the dependent nodes to move to the independent face. Two modes are available:
send dep indep abq areampc presfit f
simulates sticking friction and with the option s
send dep indep abq areampc presfit s
works for sliding conditions. The user might request a certain value for the press fit if the overlapping of the mesh do not represent the necessary distance:
send dep indep abq areampc presfit s0.06
will move the dep-nodes 0.06 in the normal direction of the independent faces (works also with option f). Additional nodes are generated and can be used to request the reaction forces on the dependent nodes. They are stored in a set named $\mathrm{N}_{j}$ dep-set-name ${ }_{j} \mathrm{i}$ ind-set-namej. Two files are produced. The one with the equations has to be included in the model-definition-section and the boundary-file in the step section.

Special cases are the cfd-solvers Duns, Isaac and OpenFoam. The boundary patches are an integral part of the mesh. So it is necessary to specify all boundary patches when writing the mesh. All free surfaces of the mesh must be specified. This is an example for OpenFoam:
send all foam cyclic cyc1 cyc2 cx patch in patch out wall wall
will write the so called polyMesh description to the file-system. After the send command the set (all) with the mesh is specified, then the format (foam), then cyclic boundary conditions (cyclic cyc1 cyc2 cx) between set cyc1 and cyc2 of the axi-symmetric case around $\mathrm{x}(\mathrm{cx})$, then boundary conditions of type patch for set "in" (patch in), then boundary conditions of type patch for set "out" (patch out) and boundary conditions of type wall for set "wall" (wall wall).

The symmetric boundary-conditions (base-type: cyclic) can be axi-symmetric (c) around $x, y, z$ or rectangular (r) in direction of $x, y, z$. Only for OpenFoam and in the rectangular (Cartesian) case also a vector pointing in the direction of the symmetry can be specified (ie: 1.,1.,0.)

For dolfyn, duns and isaac the same syntax has to be used:
send all duns viscous-wall profil subsonic-inflow in subsonic-outflow out
send all isaac WALL profil FARFIELD far EXTRAPOLATE out
send all dolfyn INLE ingang OUTL uitgang ... etc

To define so called "gap" elements and related control-commands: These elements will connect parts if they are closer as a certain distance. For example if the distance is zero (contact). The command:
send dep indep abq gap 1. 0. 0 .
will connect the nodes in the set dep and indep with gap-elements but only if they match each other in the direction 1.

### 8.87 seqa

```
'seqa' <seq> ['nod'|'pnt' <name> .. <=>] |
    ['afte'|'befo' <name> <name>.. <=>]|
    ['end' <name> .. <=>]
```

This keyword is used to create or redefine a set marked as a sequential set. This set is used for spline definitions (see line). With the command qlin such a sequential set is automatically created. To begin such a set type for example:

## SEQA Q003 PNT P004 P005 P006 P00M P00N

The program will create or overwrite the set Q003. The command will continue in the next line if the sign $"="$ is found:

SEQA Q003 PNT P004 P005 P006 =
P007 P008 P009

The parameter AFTE will insert additional points after the first specified point in the existing sequence. The parameter BEFO will insert additional points before the first specified point and the parameter END will add additional points to the sequence.

### 8.88 seta

```
'seta' <set> '!'|'n'|'e'|'p'|'l'|'c'|'s'|'b'|'S'|'L'|'se'|'sh' <name ..> |
    ['n'|'e' <name> '-' <name> <steps>]
```

This keyword is used to create or redefine a set (see also qadd). All entities like points or bodies and so on must be stored at least in one set to be reachable. The set "all" is created automatically at startup and will be open (see seto) all the time unless explicitly closed (see setc). To add points to the set "dummy" type:
seta dummy p p1 p2
This will add the points p 1 and p 2 to the set dummy. The following entities are known:

Nodes n, Elements e, Faces f, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S, Nurb Lines L, names of other sets se or shapes sh. If the entity of the specified type does not exits a set of that name is assumed and if existing then all it's entities of the specified type are appended:
seta set1 n set2
will append only the nodes in set2 to set1. If the type 'se' is used then the full content of set2 is appended.

The program will automatically determine the type of the entities if not specified, but then the names must be unique. More than one name can be specified. A minus sign between two numbers of nodes or elements specifies a range of entities with steps of "steps":
seta set1 n 1001-1100 12

If the '!' sign is specified instead of a setname then the program generates automatically sets with system defined setnames and stores entities in it. Up to now the only case were this can be used is to separate independent meshes. The single independent meshes are then referenced by new setnames, for example:
seta! all
will determine all separate (disjunct) meshes in set "all" and store them in sets called $+\mathrm{CF}<\mathrm{nr}>$. Figure (9) illustrates this function.

### 8.89 setc

```
    'setc' [<set>]
```

This keyword is used to close an open set. Without parameter setc will close the at last opened set.

### 8.90 sete

```
'sete' <set> 'n'|'e'|'p'|'l'|'c'|'s'|'b'|'S'|'L'|'se'|'sh' ->
    'max'|'min'|'strict'
```

This keyword is used to enquire other sets which have entities in common or which have an identical content. Example:


Figure 9: All disjunct meshes in the jet-engine are successive coloured
sete blade p min
searches for sets who store at least the same points as "blade" (always the set "all"). The option "max" searches for sets whose entities are completely included in the specified set. The option "strict" searches for identical sets regarding the specified type of entity.

### 8.91 seti

```
'seti' <set> 'n'|'e'|'p'|'l'|'c'|'s'|'b'|'S'|'L'|'se'|'sh' ->
    <set> <set>..
```

This keyword is used to generate an intersection of certain sets (what do the specified sets have in common of the specified entity-type?). Example:
seti intersectSet p set1 set2 set3
generates a set intersectSet with points which are stored in each of the sets
set1 set2 set3.

### 8.92 seto

'seto' [<set>]
This keyword is used to enquire open sets:
seto
Or to mark a set as open:
seto set
All newly defined or redefined entities will be members of all open sets. See setch how to close an open set.

### 8.93 setr

'setr' <set> 'n'|'e'|'p'|'l'|'s'|'b'|'S'|'L'|'se'|'sh' <name ..>
This keyword is used to remove entities from a set (see also qrem. The entity will not be deleted. It is just not longer a member of that set. To remove entities from the set dummy type:
setr dummy p p1 p2

This will remove the points p 1 and p 2 from the set. The following entities are known: Nodes n, Elements e, Points p, Lines l, Surfaces s, Bodies b, Nurb Surfaces S, Nurb Lines L, other sets se and shapes sh. The program will automatically determine the type of the entities if not specified, but then the names must be unique.

### 8.94 shpe

'shpe' <name|!> ['pln' <P1> <P2> <P3>] |['cyl'|con'|sph']
This keyword is used to create a shape which can be used to define the interiour of surfaces or to be used as a target for projections (see proj) oe to split entities (see split). A plane shape is defined with the parameter "pln" followed by the names of three points:
shpe H001 pln P1 P2 P3
Other types of shapes are planned but not implemented so far (cyl, con, sph). If automatic name generation is desired, then use "!" instead of a name. See also 'qshp' for the mouse controlled definition of shapes.

### 8.95 split <br> 'split' <set1> <set2>

This keyword is used to split lines, surfaces and elements.
The split command will not generate new surfaces but it will create points along the intersection between the surfaces in set1 and the surfaces (or shapes or faces) in set2.

So far only tetraeder elements (in set1) can be splitted by surfaces, faces or shapes (in set2). In this case the splitted tetraeder elements will be replaced by new tetraeder- and pentaeder elements. It can be used to cut out parts of the mesh to be either used directly in other models or which can be remeshed with tets based on an stl-file derived from them. Or it can be used to apply damages to a structure. See 'How to map loads' in the appendix on how to map loads to the new created nodes from the original mesh.

### 8.96 steps <br> 'steps' <value>

This keyword is used to define the number of different colors in the postprocessor mode. The default is 21 .

### 8.97 surf

```
'surf' <name(char<9)>|'!' <line|lcmb> <line|lcmb> <line|lcmb> ->
<line|lcmb>
```

This keyword is used to define or redefine a surface. It is a more convenient way to define a surface than the command gsur but it requires 3,4 or 5 edges (lines or lcmbs) otherwise the surface will not be created. The most convenient way to define surfaces is to use the command qsur If the name of the surface should be automatically generated, then just type "!" instead of a name.

### 8.98 swep

```
'swep' <set> <set> ['scal' <fx> <fy> <fz> <PO>|<div> [a] ]|
    ['tra' <dx> <dy> <dz> <div> [a] ]|
    ['rot' <p1> <p2> <alfa> <div> [a] ]|
    ['rot' 'x'|'y'|'z'|'p'<pnt> <dr> <div> [a] ]|
    ['rad' <p1> <p2> <alfa> <div> [a] ]|
    ['rad' 'x'|'y'|'z'|'p'<pnt> <dr> <div> [a] ]|
    ['mir' <P1> <P2> <div> [a] ]
```

This keyword is used to sweep entities into the next higher dimension. Sweeping a point will create a line, sweeping a line will create a surface and sweeping a surface will create a body. At first a copy of the first set (see seta and copy) will
be created. The copy of the master-set is included in the second set. Then the connecting lines and surfaces are created and at last the bodies. The divisions of the new lines between set1 and set2 is specified with the parameter "div" or the default is used. Existing sets are extended by the copied entities if the last parameter "a" (append) is provided. Several transformations are available. For example scal creates a scaled copy, the scaling factors fx , fy, fz could be chosen independently,
swep part1 part2 scal 2
swep part1 part2 scal 112 P 0
tra will create a copy and will move it away by the vector $d x, d y, d z$ and the optional parameter a will assign the new entities to sets were the mother of each entity is included,
swep set1 set2 tra 102030
rot will create a copy and will move it around the axis defined by the points p 1 and p2 by alfa degrees (the connecting lines will be arcs),
swep set1 set2 rot p0 px 20.
rad will create a copy and will move it radially to the $\mathrm{x}-$, y - or z -axis or will create a spherical section if just a single point is defined,
swep cylinder1 cylinder2 rad x 20.
swep sphere1 sphere2 rad pP0 10.
mir will create a mirrored copy. The mirror-plane is placed normal to the direction running from P 1 to P 2 and placed at P 2 ,
swep section1 section2 mir p1 p2.

### 8.99 sys

```
    'sys' <shell-command parameters>
```

This keyword is used to issue any shell command (unix or dos shell). For example to move files created by the 'send' command to certain file names or/and locations and to start the analysis. On certain platforms cgx will not wait for the completition of the command if the ' $\&$ ' key was provided as the last argument of the command. Otherwhise cgx waits until the command was completed.

### 8.100 text

'text' <string>
This keyword is used to define a comment. This commend will show up in the menu area of the main window below the file name.

### 8.101 tra

'tra' 'f'|'u'|'d'|'l'|'r' <relative-distance>
This keyword is used to move the model in the window. For example
tra u . 1
will move the model 0.1 times the model dimensions upwards. The meaning of the other letters is forward f , down d , right r , left l .

### 8.102 trfm

```
'trfm' 'rec'|'cyl' ['x'|'y'|'z'|'r'] ->
        ..[<first-Dataset-Nr> [<last-Dataset-Nr>]]
```

Generates additional entities for a new coordinate system. The option 'cyl' transforms the global results to cylindrical and 'rec' from cylindrical ones to global cartesian. In both cases the axis of the cylindrical system must be provided. So far only cylindrical systems around the major x, y, z axes are implemented. The first and the last dataset of a range can be specified optionally. The current dataset is selected if no dataset is specified.

The transformation into the cylindrical system takes place in a way that tensors and vectors are transformed into a new local cartesian system which is alligned with the directions of a true cylindrical system. In this way the dimensions are maintained (for example the displacement in angular direction is not transformed into an angle but into a displacement in tangential direction).

The transformation from a cylindrical into a cartesian system works in the same way. In this case the initial values must be defined in a local cartesian system pointing in the directions of the cylindrical system.

Remark: "rec" does not wor for stresses so far.

### 8.103 ucut

```
'ucut'
```

If a section through the mesh was created with the 'cut' or 'qcut' command then this command will delete the cut and display the un-cutted structure.

### 8.104 view

```
'view' 'edge' ['off']|'elem' ['off']|'surf'|'volu'|'front'|
    'back'|'vec' ['off']|'disp' ['off']
```

Commands to control the graphic output. This command is intended for batchmode. See also '"Viewing' for the menu controlled functions.

- "edge" triggers the display of the model edges were
- "elem" triggers the display of the element edges. They are deselected with the additional parameter "off".
- "surf" and "volu" are used to display the structure either only by it's outer skin (surf) or by drawing all elements (volu).
- "front" and "back" define which side of the structure should be drawn. Either the side which faces the user or the back-side. If the back-side is displayed then internal structures are visible.
- "vec" triggers the vector mode. All vector-entities like displacements are displayed with arrows pointing in the direction of the vector and with a length proportional to the value of the vector. See 'Toggle Vector-Plot' for a detailed description of the equivalent menu-function.
- "disp" will show the deformed structure based on a formerly selected displacement dataset (no entity must be selected). See 'TToggle Add-Displacement' for a detailed description of the equivalent menu-function.


### 8.105 volu

'volu' <set>
This keyword is used to calculate the volume and the center of gravity of a set of volume-elements. If an ccx-input file with density data was read then the mass will be also calculated.

### 8.106 zap

'zap' <set>
This keyword is used to delete all entities of a set and the set itself. All depending entities will be deleted as well.

### 8.107 zoom

'zoom' [<scale>]|[<p1x> <p1y> <p2x> <p2y>]

This keyword is used to scale the model in the window. For example
zoom 2
will increase the size of the representation of the model by a factor of 2 . A certain region of the model can be specified with two corner points of an imaginary rectangle. The coordinates are relative to the graphic-window which has its origin at the left/lower corner and as a fraction of the edge-lengths. For example
zoom 0. 0. 0.50 .5
will display the third quadrant of the window scaled by a factor of 2 .

## 9 Element Types

Node numbering of the elements and the type numbers used in the Result Format (frd-file). The solvers might use different node-numbering rules.



3 node beam element (be3, type 12)


3 node shell element (tr3, tr3u, type 7)


6 node shell element (tr6, type 8)


4 node shell element (qu4, type 9)


8 node shell element (qu8, type 10)


4 node tet element (type 3)


10 node tet element (type 6)


8 node brick element (he8, type 1)


20 node brick element (he20, type 4)


6 node penta element (pe6, type 2)


15 node penta element (pe15, type 5)

## 10 Result Format

Listing of the mesh- and the nodal results format. The data are stored in fixed format. Node-, element-definitions and results might be in ascii or binary coding. The ascii format is able to store element- and node-numbers up to '99999' in the short form or up to '9999999999' in the long form. An example for the short form is shown below:


```
> -1 2 1.00000E+00 0.00000E+00 0.00000E+00
> -3 !end of the current block
>9999 !end of data
```

The binary format applys only for data lines and the "end of the current block" line ( -3 ), which is omitted. All other lines are the same.

### 10.1 Model Header Record

Purpose: Defines the name of the model
Format: (1X,' 1', 'C',A6)
Values: KEY, CODE, NAME

### 10.2 User Header Record

```
Purpose: Stores additional user informations regarding the job
    ie. user id, creation date, model informations
Format:(1X,' 1','U',A66)
Values: KEY, CODE, STRING
```


### 10.3 Nodal Point Coordinate Block

```
Purpose: Defines the nodal coordinates
1. Record:
Format:(1X,' 2','C',18X,I12,37X,I1)
Values: KEY, CODE,NUMNOD, FORMAT
Where: KEY = 2
    CODE = C
    NUMNOD = Number of nodes in this block
    FORMAT = Format indicator
            0 short format
            1 long format
            2 binary format
Following records (ascci, FORMAT=0 | 1):
    Short Format:(1X,'-1',I5,3E12.5)
    Long Format:(1X,'-1',I10,3E12.5)
    Values: KEY, NODE, X,Y,Z
    Where: KEY = -1
        NODE = node number
        X.. = coordinates
```

```
Following records (binary, FORMAT=2):
    Format:(int NCOMPS*float)
    int and float are ansi-c data-types
    Values: NODE, X,Y,Z
    Where:
            NODE = node number
            X.. = coordinates
Last Record (only FORMAT=0 | 1 (ascii), omitted for FORMAT=2):
Format:(1X,'-3')
Values: KEY
```


### 10.4 Element Definition Block

```
Purpose: Defines the topology of the elements
```

Purpose: Defines the topology of the elements

1. Record:
2. Record:
Format:(1X,' 3','C',18X,I12,37X,I1)
Format:(1X,' 3','C',18X,I12,37X,I1)
Values: KEY, CODE,NUMELEM, FORMAT
Values: KEY, CODE,NUMELEM, FORMAT
Where: KEY = 3
Where: KEY = 3
CODE = C
CODE = C
NUMELEM= Number of elements in this block
NUMELEM= Number of elements in this block
FORMAT = Format indicator
FORMAT = Format indicator
O short format
O short format
1 long format
1 long format
2 binary format
2 binary format
Following records (ascci, FORMAT=0 | 1):
Following records (ascci, FORMAT=0 | 1):
The following block of records must be repeated for each element:
The following block of records must be repeated for each element:
The first record initializes an element definition:
The first record initializes an element definition:
Short Format:(1X,'-1',I5,3I5)
Short Format:(1X,'-1',I5,3I5)
Long Format:(1X,'-1',I10,3I5)
Long Format:(1X,'-1',I10,3I5)
Values: KEY, ELEMENT, TYPE, GROUP, MATERIAL
Values: KEY, ELEMENT, TYPE, GROUP, MATERIAL
Where: KEY = -1
Where: KEY = -1
NODE = element number
NODE = element number
TYPE = element type, see section ''Element Types''
TYPE = element type, see section ''Element Types''
GROUP = element group number, see command ''grps''
GROUP = element group number, see command ''grps''
MATERIAL= element material number, see command ''mats''.
MATERIAL= element material number, see command ''mats''.
Then the nodes in the correct order have to follow:
Then the nodes in the correct order have to follow:
Short Format:(1X,'-2',15I5)
Short Format:(1X,'-2',15I5)
Long Format:(1X,'-2',10I10)
Long Format:(1X,'-2',10I10)
Values: KEY,NODE,NODE,NODE,NODE, ...
Values: KEY,NODE,NODE,NODE,NODE, ...
Where: KEY = -2
Where: KEY = -2
NODE = node number
```
            NODE = node number
```

```
Additional lines must follow if more nodes are used.
Following records (binary, FORMAT=2):
    Format:(4*int nodes*int)
    int and float are ansi-c data-types
    Values: ELEMENT, TYPE, GROUP, MATERIAL,NODE,NODE,NODE,NODE, ...
    Where:
            NODE = element number
            TYPE = element type, see section ''Element Types''
            GROUP = element group number, see command ''grps''
            MATERIAL= element material number, see command ''mats''.
            NODE = node number
Last Record (only FORMAT=0 | 1 (ascii), omitted for FORMAT=2):
Format:(1X,'-3')
Values: KEY
```


### 10.5 Parameter Header Record

Purpose: Stores informations related to datasets.
ie. bondary conditions and loads
They should consist of a keyword and a value

Format: (1X,' 1','P',A66)
Values: KEY, CODE, STRING
Where: KEY = 1
CODE $=P$
STRING = Keyword Value (ie: FORCE 1000.)

### 10.6 Nodal Results Block

```
Purpose: Stores values on node positions
1. Record:
Format:(1X,' 100','C',6A1,E12.5,I12,20A1,I2,I5,10A1,I2)
Values: KEY,CODE,SETNAME,VALUE,NUMNOD,TEXT,ICTYPE,NUMSTP,ANALYS,FORMAT
Where: KEY = 100
    CODE = C
    SETNAME= Name (not used)
    VALUE = Could be frequency, time or any numerical value
    NUMNOD = Number of nodes in this nodal results block
    TEXT = Any text
    ICTYPE = Analysis type
            O static
```

```
    1 time step
    2 frequency
    3 load step
    4 user named
NUMSTP = Step number
ANALYS = Type of analysis (description)
FORMAT = Format indicator
    O short format
    1 long format
    2 binary format
```


## 2. Record:

Format: (1X, I2, 2X, 8A1, 2I5)
Values: KEY, NAME, NCOMPS, IRTYPE
Where: KEY = -4
NAME = Dataset name to be used in the menu
NCOMPS = Number of entities
IRTYPE = 1 Nodal data, material independent
2 Nodal data, material dependant
3 Element data at nodes (not used)
3. Type of Record:

Format: (1X, I2, 2X, 8A1, 5I5, 8A1)
Values: KEY, NAME, MENU, ICTYPE, ICIND1, ICIND2, IEXIST, ICNAME
Where: KEY = -5
NAME = Entity name to be used in the menu for this comp.
MENU = 1
ICTYPE = Type of entity
1 scalar
2 vector with 3 components
4 matrix
12 vector with 3 amplitudes and 3 phase-angles in degree
ICIND1 = sub-component index or row number
ICIND2 = column number for ICTYPE=4
IEXIST $=0$ data are provided
1 data are to be calculated by predefined functions (not used)
2 as 0 but earmarked
ICNAME = Name of the predefined calculation (not used)
ALL calculate the total displacement if ICTYPE=2
This record must be repeated for each entity.
4. Type of Record: (not used)

This record will be necessary in combination with the request for predefined calculations. This type of record is not allowed in combination with binary coding of data.

Format: (1X, I2, 2I5, 20I3)
Values: KEY,IRECTY,NUMCPS, (LSTCPS (I) , I=1,NUMCPS)
Where: KEY = -6
IRECTY = Record variant identification number
NUMCPS = Number of components
LSTCPS = For each variant component, the position of the corresponding component in the attribute definition

```
5. Type of Record:
The following records are data-records and the format is repeated for
each node.
In case of material independent data
- ascii coding:
Following records (ascci, FORMAT=0 | 1):
    Short Format:(1X,I2,I5,6E12.5)
    Long Format:(1X,I2,I10,6E12.5)
    Values: KEY, NODE, XX..
    Where: KEY = -1 if its the first line of data for a given node or
                    -2 if its a continuation line
            NODE = node number or blank if KEY=-2
            XX. . = data
- binary coding:
    Following records (ascci, FORMAT=2):
    (int,NCOMPS*float)
    int and float are ansi-c data-types
    Values: NODE, XX..
    Where:
        NODE = node number or blank if KEY=-2
        XX. . = data
In case of material dependant data
REMARK: Implemented only for NMATS=1
- first line:
Short Format:(1X,I2,4I5)
Long Format:(1X,I2,I10,3I5)
Values: KEY, NODENR, NMATS
Where: KEY = -1
            NODENR = Node number
            NMATS = Number of different materials at this node (unused)
- second and following lines:
Short Format:(1X,I2, I5,6E12.5)
Long Format:(1X,I2,I10,6E12.5)
```

```
Values: KEY, MAT, XX, YY, ZZ, XY, YZ, ZX ..
Where: KEY = -2
    MAT = material-property-number if KEY=-2 (unused)
    XX.. = data
Last Record (only FORMAT=0 | 1 (ascii), omitted for FORMAT=2):
Format:(1X,'-3')
Values: KEY
```


## 11 Pre-defined Calculations

Listing of the automatically calculated additional results.

### 11.1 Von Mises Equivalent Stress

Entity name: Mises

$$
\sigma_{v M}=\frac{1}{\sqrt{2}} \sqrt{\left(\sigma_{x}-\sigma_{y}\right)^{2}+\left(\sigma_{y}-\sigma_{z}\right)^{2}+\left(\sigma_{z}-\sigma_{x}\right)^{2}+6 \tau_{y z}^{2}+6 \tau_{z x}^{2}+6 \tau_{x y}^{2}}
$$

### 11.2 Principal Stresses

Entity names: P1, P2, P3, worstPS

The principal stresses $\sigma$ are named P1, P2, P3. From the three principal stresses $\sigma$ the absolute maximum value will be calculated and named worstPS. For example if a node has the three values 100,0 and -110 MPa then -110 MPa would be shown. The three principal stresses $\sigma_{1} \sigma_{2} \sigma_{3}$ are derived from the following equation:

$$
\left[\begin{array}{ccc}
\sigma_{x x}-\lambda & \sigma_{x y} & \sigma_{x z} \\
\sigma_{y x} & \sigma_{y y}-\lambda & \sigma_{y z} \\
\sigma_{z x} & \sigma_{z y} & \sigma_{z z}-\lambda
\end{array}\right]\left[\begin{array}{l}
n x \\
n y \\
n z
\end{array}\right]=\left[\begin{array}{l}
0 \\
0 \\
0
\end{array}\right]
$$

They are given by the three roots of the equation (stress tensor is symmetric: $\sigma_{x y}=\sigma_{y x}$ etc.):

$$
\begin{gathered}
\sigma^{3}-\left(\sigma_{x x}+\sigma_{y y}+\sigma_{z z}\right) \sigma^{2}+\left(\sigma_{x x} \sigma_{y y}+\sigma_{y y} \sigma_{z z}+\sigma_{z z} \sigma_{x x}-\sigma_{x y}^{2}-\sigma_{y z}^{2}-\right. \\
\left.\sigma_{z x}^{2}\right) \sigma-\left(\sigma_{x x} \sigma_{y y} \sigma_{z z}+2 \sigma_{x y} \sigma_{y z} \sigma_{z x}-\sigma_{x x} \sigma_{y z}^{2}-\sigma_{y y} \sigma_{z x}^{2}-\sigma_{z z} \sigma_{x y}^{2}\right)=0
\end{gathered}
$$

### 11.3 Tresca Stresses

Entity name: Tresca
This is the maximum shear-stress:

$$
\text { Tresca }=0.5 *\left(\sigma_{1}-\sigma_{3}\right)
$$

### 11.4 Cylindrical Stresses

Entity names: SXX, STT, SRR, SXT, STR, SRX
The Cylindrical Stresses are truly cartesin stresses in a cylindrical system regarding the node-psition. So the stress-tensor is rotated individually for each node. They are calculated on demand (see trfm).

## 12 User-Functions

The user might define his own functions to manipulate the mesh or the results with the user function stored in file "userFunction.c". See the command "call' how to call a user function. The user can generate new nodes, elements or datasets or extend or manipulate existing datasets or interfaces to other software. The file "userFunction.c" includes an example which calculates the hydrostatic stress and stores the result in a new dataset. There the user can see how to deal with datasets.

## A Known Problems

## A. 1 Program is not responding

If the program seems to hang then leave the window with the mouse pointer and go in again. If that does not help then probably a command is waiting for input. Stay with the mouse pointer inside the window and press the "q" key several times. Another very popular error is to move the mouse-pointer into the xterm were the typed commands and the protocol is visible. Please, the mouse-pointer MUST stay in the main-window during typing!

## A. 2 During Meshing

If a body can not be meshed although no obvious error is in its definition then the reason could be that the shape of the body is very far from being bricklike. Subdivide the body to improve the shapes of the single ones. For the moment there are some restrictions for the definition of five- or seven-sided bodies. For example the first two surfaces in the body-topology (see gbod) have to be defined in the same order. That means the first line of the first surface has to be connected with the first line in the second surface by one of the remaining surfaces. This is always the case if the body is a product of a "swep' command.

## A. 3 Program generates a segmentation fault

Write a mail to the author and, if possible, add the input-file. 3 .

## B Tips and Hints

The following collection will give you background information and procedures to deal with common situations.

## B. 1 How to change the format of the movie file

Use a shell command like convert to split up movie.gif with multiple layers into multiple frames, as seperate jpeg files:

```
convert movie.gif %d.jpg
```

Convert any series of multiple jpeg files into WMV format with:

```
mencoder 'mf://*.jpg' -mf type=jpg:fps=25 -ovc lavc -lavcopts
vcodec=wmv2 -o movie.wmv
```

To convert a DivX video file into Flash Movie format use this command:

```
mencoder <inputfile> -ovc lavc -lavcopts vcodec=flv -of lavf
```

In general:To convert a video file from one format into the other, use the program "mencoder". It comes with the mplayer packages.
mplayer movie.wmv

## B. 2 How to define a set of entities

Some knowledge is necessary to efficiently select entities (nodes, points ..). As a golden rule in complicated situations never try to create a set just by "adding" the entities to the set (see qadd). It is much better to catch a bigger group which includes certainly the wanted ones. Then display the set with the plot command and remove all unwanted entities with the qrem command. Entities are selected if at least one pixel of it is inside the selection rectangle. But there is one exception: Only the lower left corner of any text (names of points etc.) can be selected. Surfaces can also be selected by picking its shaded interiour (see "rep)". You might add all lower entities (as points for example) by typing "comp set do". This is necessary for example if you had selected surfaces and you want to move them in space. Only points have locations and therefore nothing will happen unless you completed the set by the related points with "comp" command.

There is another type of set called sequence. The data-structure is the same but with one exception, the data keep their order in which they were selected. This type of set is used for splines (see 'qlin' and '酎') or in combination with the 'graph' command if values along a path should be displayed. Use "prnt sq" to list all existing sequences and use "qseq]' or "sseqa|' to create them. Up to now they are only used to store nodes and points. As sets they will be written to a file if fbd format is specified. In this case also node-sequences can be stored.

## B. 3 How to enquire node numbers and values at certain locations

A very common problem is how to get the exact value on a node position during post-processing. To actually get the value add the element edges to the view (see Toggle Element Edges) and type qenq and press the RETURN key (during typing the mouse-pointer MUST stay in the main window, do NOT move the pointer into the xterm). Then move the mouse-pointer over the location of a node and press the "n" key. The node-number, the value at that node and the location will be written in the xterm from which the cgx was started. See also the "enqj' command for batch controlled value extraction.

## B. 4 How to select only nodes on the surface

Some times you need to select nodes only on the surface of the mesh. This can be done when the mesh is displayed in the surface mode (see 'Toggle Surfaces/Volumes') using the menu-entry 'Show Elements With Light'. To find node positions more easily add the element edges to the view (see Toggle Element Edges).

A different way uses the element-faces (see "plot' with parameter "f"). Store the desired faces in a new set qadd) and complete the set downwards ("comp set do"). Check the selected nodes with "plot n setname".

## B. 5 How to generate a time-history plot

So called time history plots can be created based on a previous displayed sequence of data-sets (see "Toggle Dataset Sequence') with the command 'graph'. It is also possible to use only the command line. For example:

- ds 1 e 3
- ds 1210
- graph set t
will produce a time history plot for the nodes stored in set over all loadcases from 1 to 10 for the entity nr 3. Or
- graph set t DISP D1
will display the displacement in direction 1 for all loadcases. For more details and other options look into the "graph' command description.


Figure 10: example of a time-history plot

## B. 6 How the mesh is related to the geometry

Very often you need the embedded nodes, element-faces or elements of geometric entities to apply boundary conditions. If you understand the underlying concept you will be able to get them more easily.

Geometric entities are the mothers of nodes, faces and elements (so to say) and will remember them. In turn if an entity is not the mother of a given meshentity it will not remember it. Therefore a body will only know about nodes which are not placed on surfaces, lines or points. A surface will only know about nodes which are not placed on lines or points. And so on.

Therefore if you need the nodes on a surface and not only the ones just inside
the surface, then create a set with this surface and do a "comp set do". This will add the lines and points together with their nodes to the set.

On the other hand if you have only a node and you need the geometric entity in which the node is embedded you might also type "comp set do".

## B. 7 How to change the order of elements

Use the command 'mids' to change from second order to first order or vice versa. In this case the amount of elements will not change. Or use the command 'send' with the parameter "quadlin" to change from second order to first order. But in this case each second order element will be splitted in 8 first order elements.

## B. 8 How to connect independent meshes

Sometimes it is advisable to "glue" independent meshes together instead of trying to create one big seamless-mesh. Or you just want to create a contact formulation were you know that no separation will happen. In this situations you might use equations (also called mpc's) which connect one dependent node with one or more independent nodes. The independent side should be coarser than the dependent side to avoid gaps in the connection. See the command "send in combination with the option "areampc" how to create such connections. Sliding and fixed contact as well as press-fits can be modelled. The necessary sets should be defined based on geometry not on the mesh. In this case the definition will be stored with the "save" or "exit" command and can be used after the next program call.

Background: The movement of each location in an element (or on its surface) is fully described by the movement of its associated nodes and its shape-function. In an iterative algorithm element-coordinates are varied until the real-world coordinates of a dependent node are matched. Based on the element coordinates the shape function gives the participation (weight) factors of the independent nodes (the coefficients in the mpc's). This approach delivers valid results as long as the dependent node is not located outside of the independent element. Therefore the location of the dependent node has to be modified in such cases. The dependent will be moved to the surface of the independent element (again decribed by its shape-function) and the procedure is repeated.

## B. 9 How to define loads and constraints

Loads and constraints are not saved in any database. They are just created and written to a file with the 'ssend' command. But the sets which are needed for the definition are stored together with the geometry if you type the "save" command. Of course the sets must have been defined based on geometry and not based on mesh entities like nodes because mesh-entities are not saved with the "save" command. You must know that geometry-sets know also their mesh entities after a 'mesh' command. If you store your commands to write the boundary conditions in a file you can easily repeat them by just reading this


## Four Independent Nodes At The Element Corners

Figure 11: Dependent node on element face to create a connection
command-file (see 'read'). Several types of loads can be applied. That is forces, pressure, thermal-heat-coefficients and radiation etc. For unsupported loads write a set of element-, node- or face-labels (parameter "names") and apply the desired load to that set in the solver input-file. Other boundary conditions like single-point-constraints for structural, thermal and fluid-calculations can be written. The sliding condition (parameter "slide") were nodes are bound to the element-faces to which they belong can be used for structural calculations or for fluid calculations. In the later case it forces the flow to follow the surface of the elements. This is necessary in inviscid calculations to prevent the fluid to penetrate the walls. Results from a previous calculation can be written in the solver input format for further calculations (parameter "ds", "tmf" etc.). For example temperatures for thermal mechanic fatigue analysis or velocities, pressures and thermals for a restart of a cfd calculation.

## B. 10 How to map loads

Values at nodes can be mapped (interpolated) from a second mesh with the "map' command. This second mesh (data source or "master") is usually available as a result-file from a previous calculation. The "read' command with the "add" parameter can be used to include this file in the current model. Solverinput files (inp) and result files (frd) can be used as a data source. The command
will add an offset to the nodes and elements so that existing nodes and elements will not be overwritten. The original mesh is the target or "slave" of the mapping process. The mapping process will add the values to the dataset(s). The mapped values can be visualized by selecting the mapped dataset and entity and then by plotting the slave elements or faces with 'plot fv slave". An example of the necessary commands for the mapping process (2D to 2 D ) is listed below:

```
Define a set with the slave nodes or faces. For example with:
    qadd slave
    comp slave do (to extend the set by the referenced faces or nodes)
Then open a set and read the master-model:
    seto new
    read result.frd add
    setc
If necessary move 'new' in space to match the position of the
slave (see ''move'').
Add the faces to the 'new' set
(only nodes and elements are already stored in "new"):
    comp new do
    plot f new
Define the master set:
    qadd master (catch the right faces)
    comp master do
Map the values of dataset 1 with:
    map slave master surf ds1
Check the mapping with:
    ds 1 e 1
    plot fv slave
Write the file with the mapped values:
    send slave abq pres ds1 e1
Check the file ''slave_ds1e1.dlo'' with an editor and use it
in an inp-file.
```

If the master values are not available in either inp or frd format but in any other format which can be read by cgx (isaac, openFoam ..) it is then possible to write them in frd format with the "send' command.

## B. 11 How to run cgx in batch mode

Most commands can be executed in batch-mode. Actually if you read a file with geometry (fbd-file) then you run cgx in batch mode already! You just have to add "exit" or "quit" at the end of the file and it will be obvious. You might use the 'read' command in such a command-file to reference other command-files or to read files with mesh-entities for whatever purposes. In such a way you can create and modify geometry or meshes in batch-mode or evaluate results in batch-mode. But you need a graphic-capable computer because cgx needs it also if no graphic output is requested. Nevertheless the popup of the graphic window can be suppressed if cgx was started with the "-bg" parameter.

## B. 12 How to deal with cad-geometry

A simple step-reader is integrated in cgx. It can deal with points and lines. You might start with a file containing a 2D-section, subdivide it in meshable surfaces and sweep it in the 3rd dimension to create your geometry. If features exist in the 3rd dimension only on a certain location then this feature must be included in the 2 D -section. Then sweep the 2 D -section to the location were the feature starts, then right to the end and at last to the end of the geometry. Then delete the bodies before and after the feature. You might also project the sweped sections to target surfaces if the feature is shaped in the 3rd dimension. This is the approach which I often use even to generate complex 3D-models. For complicated models you should also consider to use a tet-mesher like NETGEN [4] which can read step and generates quite nice tet-meshes. You can read this meshes with cgx and combine it with cgx-geometry and meshes. Then create your boundary conditions etc. You might read the native-netgen format (.vol) instead of abaqus-format because this stores also the 2D meshing regions as separate sets which can be used to apply boundary conditions ("cgx -ng file.vol").

But you can also create a so called stl-file based on your cgx-geometry and feed it to external meshers. The following section explains how to do that:

In general hexahedra-elements perform better than tets but if the mesh should be derived from a cad-geometry it is often more convenient to create a tetrahedra mesh as to modify or rebuild the geometry to make it meshable with hexahedra-elements. In this case the user can mesh the surfaces with unstructured triangles and export them in the stl-format (see 'send') as a basis for an auto-mesher [4]. The following steps have to be done:

- Use the interface program to convert the cad format to fbd format

```
(ie: vda2fbd cad.vda > cad.fbd).
```

Sometimes the header of the vda file causes some trouble and must be modified to make the program run.

- Start cgx with that file (cgx -a cad.fbd). Usually some warnings appear on the screen but the program will fix that automatically (triggered by


Figure 12: CAD-file meshed with tet-elements using NETGEN
-a). After all geometry has been read the program will merge points and lines to close the volume. Then all nurbs related surfaces are trimmed. Finally all surfaces are rendered and the result is displayed in the main window. The whole process might need some time. If problems occur the user might start the program with option -b instead of -a (cgx -b cad.fbd). Then no automatic post-processing is done and the user has to fix the geometry manually. See the commands merg, div, qdiv, rep. Quite often adjacent surfaces do not use common lines. Make sure the divisions match. This has to be done because later on every created triangle must have three adjacent triangles.

- Flip the surfaces in a way that its normal direction points outwards (use '"qflp' with key "a"). If a surface points inwards it is not illuminated and appears only dark grey.
- Define the element type, usually: elty all tr3u. In rectangular situations the element type tr3 gives better results. If you use NETGEN 4 later on for the generation of the tet-mesh then you should also prepare edges for the mesher. Usually it is good enough if you mesh all lines Use be2 elements for the edges.
- Mesh all (mesh all). If some surfaces can not be meshed then modify the divisions of the lines of this surfaces (see "qdiv') or chose the structured element type tr3 for this surfaces. Or change some parameters of the
unstructured mesher (see "asgni'). See also the commands 'qdel' and '"qele' to fix elements manually.
- Visualize and check the mesh (plus e all).
- Export the mesh (send all stl). If the model consists of several unconnected parts separate them in single sets and send one after the other in stl format (see qadd qrem comp). Beside the stl file a so called edge file for NETGEN will be created if be2 elements are included in the mesh.
- Create the tet-mesh outside of cgx. If you use NETGEN then better use the self created edges. In NETGEN open the stl-doctor and go in the edges menu. There delete all edges with "all undefined" then load the edges with "load edgedata" and activate them with "candidate to confirm". Then mesh the model. Use Abaqus format for the export. Or if you use NETGEN use the native-netgen format (file extensin .vol). The latter will keep the surface meshing domains which can then be used to apply BC after reading with cgx. See the 'Program Parameters' section on how to do that.
- Back in cgx delete the existing surface mesh (del me) and import the Abaqus-tet-mesh (read mesh.msh inp) or start a new session (cgx -c mesh.msh). If the mesh is composed of several parts or if you want to "add" the tetmesh to an existing one then assemble all parts by reading one after the other with 'read'.
- Create sets of nodes, faces or elements to create boundary conditions and export them with 'send'.
- Create the input deck for ccx with an editor and start the calculation.
- Look at the results with cgx (cgx results.frd).


## B. 13 How to check an input file for ccx

A quick check of a ccx input-file can be done with cgx by reading the file with the option -c (cgx -c file.inp). After startup all defined node-, element-, and surface-sets are availabe together with internal sets which group togeter certain entities according to their purposes. The following internal sets will be created if appropriate data were found:

- +bou(DOF): Created if *BOUNDARY is found. All affected nodes are stored in + bou were + bou(DOF) store just the nodes which are constrained in the related DOF number.
- $+\operatorname{dep}(\mathrm{BOU})$ : Created if $*$ EQUATION is found. All dependent nodes are stored in +dep.
- +ind(BOU): Analog to +dep.
- +clo[nr]: Created if *CLOAD is found. The nr counts the number of appearance.
- +dlo[nr]: Created if *DLOAD is found.
- $+\mathrm{mpc}[\mathrm{nr}]$ : Created if *MPC is found.
- +rad[nr]: Created if *MPC is found.
- +flm[nr]: Created if *FILM is found.
- $+\mathrm{cflx}[\mathrm{nr}]$ : Created if *CFLUX is found.
- +dflx[nr]: Created if *DFLUX is found.
- +tie[1-2]: Created if *TIE is found. The set +tie1 stores the slave entities and + tie 2 the master. The single sets which define the contact areas are linked together so if identified with the "qenq" command the referenced (linked) opposing set is listed in the xterm.
- +trans...: Created if *TRANSFORM is found. The name consists of the definition of the transformation.
- +[elty]: Created for all known element types like *C3D20.

Check the element quality with 'Show Bad Elements' or use 'eqall' to set thresholds and 'plot' to actually plot the affected elements. The forces regard their referenced coordinate-system (*TRANSFORM). The values are automatically transformed into the global cartesian system so that the vectors point in the correct direction.

## B. 14 Remarks Concerning NETGEN

It is not necessary to write the mesh in abaqus format if you use netgen as a mesher. The native netgen format (.vol) can be read by cgx (cgx -ng file.vol). The netgen mesh format (.vol) includes also the surface-patches which were defined by the edges of the model and used for the generation of the volumemesh. This patches can be used to define boundary conditions or loads. The nodes and faces of this patches are stored in sets named "+set[nr]". To get an overview over the patches type "prnt|se". To see were the patches are located type "plotf all" and use the "PAGE_DOWN"-key to scan through all sets.

A netgen surface mesh can be written based on the faces of elements. The faces of hex, tet, quad and tria elements are triangulated and written in the stand-alone netgen mesher format (file.ng). This mesher can be found in the netgen sub-directory nglib and is named ng_vol. It will create tet4 elements which use and keep the shape of the provided tri3 elements. Back in cgx you might convert to tet10 with the 'mids' command (hint for the experienced user: A projection of the new midside nodes to the original faces should be possible with the 'proj' command).

## B. 15 Remarks Concerning dolfyn

Some support for dolfyn (a free cfd code) was provided by Runar Tenfjord. In the CalculiX/cgx_(nr)/examples/dolfyn directory is a patch for the dolfyn source-code included. This patch enables dolfyn to write frd-result files which can be visualized with cgx. There is also an example which allows cgx to be used as an pre-processor for dolfyn. The mesh can be written in dolfyn format with the command 'send'.

## B. 16 Remarks Concerning Duns and Isaac

If you intent to create a 2 D -mesh for the cfd-code duns or isaac you have to watch out that all surfaces are created in the same order. That means that all surfaces must be defined clockwise or counter-clockwise. For isaac they have to be counter-clockwise if you look in z direction. The block-structure can be detected only in this case. You can check the mesh by simply mesh it with linear shell-elements and display them. All elements must be either dark or illuminated. A later "qflp" or "flip" command will not cure wrong oriented surfaces since it only changes the "sign" in their definition and not the basic edge sequence, which is necessary here. The results of a calculation can be opened by specifying the parameter (-duns2d -duns3d -isaac2d -isaac3d) and the filenmae without any extention(cgx -isaac2d RAE2822). See also 'Program Parameters', "'mesh', 'ssend'. Watch also the airfoil-example in the distrib.

## B. 17 Remarks Concerning OpenFOAM

The mesh can be written in OpenFOAM polyMesh format with the command "send'. If you work in the polyMesh-directory of the OpenFOAM case then all mesh-related files will be already in place. So far the physical-type is not written in the boundary file as it is not mandatory. The results of an OpenFOAM calculation can be viewed by specifying the parameter -foam and the case (the relative or absolute path including the directory-name of the case). See also '"Program Parameters', 'mesh'.

## B. 18 Remarks Concerning Code Aster

From Paul CARRICO (2005/02/12)
Brief presentation of CODE ASTER: Code Aster is an implicit solver under GPL licence from the French company EDF (Électricité de France).

Code Aster and its documentations is downloadable at the following address:
http://www.code-aster.org
(NOTA : the documentation is in French at the moment but many users are translating it in English and in German)

The following list is not exhaustive but it briefly presents the capabilities of the solver:

- Mechanical modeling: Code aster allows linear and non linear calculations in static, dynamic, acoustic etc. Many mechanical laws are implemented in the solver such as damage, fatigue, creep, viscosities (elastic, plastic) etc. For isotropic and non-isotropic materials (orthotropic ones for example). Because of EDF fields, the materials used in Code Aster are essentially Metallic ones and Geo material one, but there are probably some others.
- Thermal and thermomechanical calculations: The Thermal solver performs linear and non-linear calculations for pure thermal but also for thermomechanical simulations.
- Input interface: EFICAS is the input interface for coding the input file, but it's not a pre-processing as you can find in many commercial code.
- Tools: Many tools are provided with Code Aster: HOMARD for mesh refinement, GIBI and GMSH for post-processing.

CGX to ASTER export format (i.e HOWTO use this export format) The export format allows to export meshes and sets from CGX to Code Aster for linear and quadratic 1D, 2D and 3D elements. For this, just type: 'send all aster' for exporting a complete mesh. The file will have the '.mail' extension. Type 'send set aster nam' for exporting the GROUP-NO (node group) and the GROUP-MA (mesh group) which compose the set. The file will have '.nam' extension

The later item is particularly useful to apply boundary conditions onto (DOF, pressure, force, displacement, temperature, etc.). Since of these boundary conditions are coded with EFICAS in the input file, I thought it was not necessary to develop another features than the 2 previous ones !

## B. 19 Remarks Concerning Samcef

From Paul CARRICO (2006/04/17)
BASIC TUTORIAL FOR HOWTO USE THE SAMCEF EXPORT FORMAT

```
1- Definition of the points
K: pnt p0 0 0 0
K: pnt p1 1 0 0
K: pnt p2 0 1 0
K: pnt p3 2 1 0
K: plot pa all
2- Definition of the lines
K: plus l all
K: qlin (link the points p0 p1 p3 p2 p2 p0)
3- Creation of the first surface
```

```
K: qsur
4- Creation of 10 (between p0 & p1) and l1 (between p1 & p3) sets
K : qadd lo
K : qadd l1
4- Creation of the 2 other surfaces
K : swep l0 l1 tra 0 -3 0
K : swep l1 l1b tra -3 0 0
5- Creation of the SYMETRY set
K : plot s all
K : qadd SYMETRY (use both a and rr keys to select all the surfaces)
6- Creation of the volumes
K : swep SYMETRY s1 swep tra 0 0 1 (all the volume will be automatically
created)
7- Looking for common points, lines and surfaces
In the order :
K : merg p all
K : merg l all
K : merg s all
8- Creation of the LOAD set and ANCHORAG one
K : qadd LOAD (use rr keys to select the surface)
K : qadd ANCHORAG (use rr keys to select the surface)
NOTA : It's easy to verify the different sets ; for example :
K : plot b all (you can see all the volumes)
K : plus s LOAD (you can see the set LOAD)
K : plus s ANCHORAG
K : plus s SYMETRY
9 - Mesh
K : plot ld all
K : div all mult 2
K : elty all HE2O (to specify HEXAHEDRA with 20 nodes)
K : elty LOAD qu8 (to mesh the set LOAD otherwise no quads will be created)
K : elty ANCHORAG qu8
K : elty SYMETRY
K : mesh all (to mesh the part with all.dat name)
K : send all sam (to export the mesh into Samcef format)
K : send LOAD sam nam (to export groups into Samcef format)
K : send ANCHORAG sam nam (see previous remark)
K : send SYMETRY sam nam
```

```
10- Modifications
It's possible now to make some modifications :
a- open all.dat file with your favorite text editor (Vi for me)
b- open ANCHORAG.nam & the SYMETRIC.nam files and do the same as previously
c- concatenate under Linux the files using the following schema :
    cat all.dat LOAD.nam > s1.m
    cat s1.m ANCHORAG.nam > s2.m
    cat s2.m SYMETRY.nam > part.dat
(all the sx.m files will be erased afterward)
d- open PART.dat file and go to the end => then add RETURN
e- the mesh file now works with Samcef
Another interesting way : add for each .nam file an input in your bank file:
input ''part.dat''
input ''LOAD.nam''
input ''ANCHORAG.nam''
etc. ...
11 IMPORTANT REMARK
After, it's possible to modify the mesh into BACON (extrusions, etc. ...) ;
that's why the element hypothesis is not added at the end of the file ;
=> you must define the element definition AFTER the last mesh modification
(.HYP MINDLIN)
12- Comments
if you've any remark or any comment or any suggestion to improve this export
format, please send a mail to paul.carrico_at_free.fr
```


## C Simple Examples

The following listings show simple geometry input-files. The pictures show this geometry together with their labels and the generated mesh. The models were made based on three points. Two points defined one axis of rotation and one was the basis of several "swep]' and "merg]' operations. In case of the sphere the surfaces on the pole had to be redefined using only three lines per surface.

## C. 1 Disc

| PNT py | -0.00000 | 1.00000 | 0.00000 |
| :--- | ---: | ---: | ---: |
| PNT p0 | -0.00000 | -0.00000 | 0.00000 |
| PNT P001 | 0.70711 | -0.00000 | -0.70711 |



Figure 13: disc made of four 90 degree segments

| PNT P003 | -0.00000 | -0.00000 | -1.00000 |
| :---: | :---: | :---: | :---: |
| PNT P005 | -0.70711 | -0.00000 | -0.70711 |
| PNT P006 | -1.00000 | -0.00000 | 0.00000 |
| PNT P009 | -0.70711 | -0.00000 | 0.70711 |
| PNT P00A | 0.00000 | -0.00000 | 1.00000 |
| PNT POOG | 0.70711 | -0.00000 | 0.70711 |
| PNT POOI | 1.00000 | -0.00000 | -0.00000 |
| LINE L001 | P00I P001 p0 4 |  |  |
| LINE L002 | P001 P003 p0 4 |  |  |
| LINE L003 | P003 p0 8 |  |  |
| LINE L004 | p P POOI 8 |  |  |
| LINE L005 | P003 P005 p0 4 |  |  |
| LINE L006 | P005 P006 p0 4 |  |  |
| LINE L007 | P006 p0 8 |  |  |
| LINE L009 | 006 P009 p0 4 |  |  |
| LINE LOOA | P009 P00A p0 4 |  |  |
| LINE LOOC | P00A p0 8 |  |  |

```
LINE LOOG POOA POOG p0 4
LINE LOOI POOG POOI pO 4
GSUR A001 + BLEND - L003 - L002 - L001 - L004
GSUR A002 + BLEND - L007 - L006 - L005 + L003
GSUR A003 + BLEND - LOOC - L00A - L009 + L007
GSUR A004 + BLEND + LOO4 - LOOI - LOOG + LOOC
ELTY all QU4
```


## C. 2 Cylinder



Figure 14: cylinder made of four 90 degree segments

| PNT p0 | -0.00000 | -0.00000 | 0.00000 |
| :--- | ---: | ---: | ---: |
| PNT py | -0.00000 | 1.00000 | 0.00000 |
| PNT p1 | 1.00000 | -0.00000 | 0.00000 |
| PNT P001 | 1.00000 | 1.00000 | 0.00000 |
| PNT P002 | -0.00000 | -0.00000 | -1.00000 |
| PNT P003 | -0.00000 | 1.00000 | -1.00000 |
| PNT P006 | -1.00000 | -0.00000 | 0.00000 |



## C. 3 Sphere

| PNT py | -0.00000 | 1.00000 | -0.00000 |
| :--- | ---: | ---: | ---: |
| PNT p1 | 1.00000 | -0.00000 | -0.00000 |
| PNT P001 | 0.70711 | -0.00000 | -0.70711 |
| PNT P003 | -0.00000 | -0.00000 | -1.00000 |
| PNT P006 | 0.70711 | 0.50000 | -0.50000 |
| PNT P008 | -0.00000 | 0.70711 | -0.70711 |
| PNT P00C | 0.70711 | -0.00000 | -0.00000 |
| PNT P00K | 0.70711 | 0.70711 | -0.00000 |
| PNT P00L | -0.00000 | -0.00000 | -0.00000 |
| PNT P00N | -0.00000 | 1.00000 | -0.00000 |
| LINE L001 p1 P001 P00L 8 |  |  |  |
| LINE L002 P001 P003 P00L 8 |  |  |  |
| LINE L003 p1 P006 P00L 8 |  |  |  |
| LINE L004 P006 P008 P00L 8 |  |  |  |
| LINE L006 P001 P006 P00C 8 |  |  |  |
| LINE L008 P003 P008 P00L 8 |  |  |  |
| LINE L00A p1 P00K P00L 8 |  |  |  |
| LINE L00C P00K P00N P00L 8 |  |  |  |
| LINE L00G P006 P00K P00C 8 |  |  |  |
| LINE L00J P008 P00N P00L 8 |  |  |  |
| GSUR A005 + BLEND - L003 + L001 + L006 |  |  |  |
| GSUR A002 + B begin\{appendix\} |  |  |  |
| LEND - LO02 + LO06 + LO04 - L008 |  |  |  |



Figure 15: Segment of a Sphere

```
GSUR A006 + BLEND + L003 + LOOG - LOOA
GSUR A004 + BLEND - L004 + LOOG + LOOC - LOOJ
ELTY all QU4
```


## C. 4 Sphere (Volume)

| PNT py | 0.00000 | 1.00000 | 0.00000 |
| :--- | :--- | ---: | ---: |
| PNT p1 | 1.00000 | 0.00000 | 0.00000 |
| PNT P006 | 0.70711 | 0.50000 | -0.50000 |
| PNT P008 | 0.00000 | 0.70711 | -0.70711 |
| PNT P00C | 0.70711 | 0.00000 | 0.00000 |
| PNT P00K | 0.70711 | 0.70711 | 0.00000 |
| PNT P00L | 0.00000 | 0.00000 | 0.00000 |
| PNT P00N | 0.00000 | 1.00000 | 0.00000 |
| LINE LO01 p1 P00L 8 |  |  |  |
| LINE L002 P00L P008 8 |  |  |  |
| LINE L003 p1 P006 P00L 8 |  |  |  |



Figure 16: Segment of a Sphere (Volume)

```
LINE L004 P006 P008 P00L 8
LINE LOO5 POOL POON 8
LINE LOOA p1 POOK POOL 8
LINE LOOC POOK POON POOL 8
LINE LOOG P006 POOK POOC 8
LINE LOOJ POO8 POON POOL 8
GSUR A001 + BLEND - L003 + L001 + L002 - L004
GSUR A002 + BLEND - L005 - L001 + L00A + L00C
GSUR A006 + BLEND + L003 + LOOG - LO0A
GSUR A004 + BLEND - L004 + LOOG + LOOC - LOOJ
GSUR A003 + BLEND + LOO2 + LOOJ - L005
GBOD B001 NORM + A006 - A003 - A004 + A002 + A001
ELTY all HE20
```


## C. 5 Airfoil for cfd codes

All surfaces must be oriented in the same way. The sets are used to define areas for the boundary conditions.


Figure 17: Airfoil for cfd codes

| PNT P002 | -0.24688 | 0.00667 | 0.00000 |
| :--- | :--- | :--- | :--- |
| PNT P003 | -0.24375 | 0.00903 | 0.00000 |
| PNT P004 | -0.23750 | 0.01228 | 0.00000 |
| PNT P005 | -0.23125 | 0.01450 | 0.00000 |
| PNT P006 | -0.22500 | 0.01608 | 0.00000 |
| PNT P007 | -0.21250 | 0.01798 | 0.00000 |
| PNT P008 | -0.20000 | 0.01875 | 0.00000 |
| PNT P009 | -0.18750 | 0.01900 | 0.00000 |
| PNT POOA | -0.17500 | 0.01888 | 0.00000 |
| PNT POOC | -0.15000 | 0.01785 | 0.00000 |
| PNT POOE | -0.12500 | 0.01602 | 0.00000 |
| PNT POOG | -0.10000 | 0.01368 | 0.00000 |
| PNT POOI | -0.07500 | 0.01090 | 0.00000 |


| PNT P00J | -0.05000 | 0.00770 | 0.00000 |
| :--- | ---: | ---: | ---: |
| PNT P00K | -0.02500 | 0.00420 | 0.00000 |
| PNT P00L | -0.01250 | 0.00230 | 0.00000 |
| PNT P000 | -0.25000 | 0.00000 | 0.00000 |
| PNT P00P | -0.24688 | -0.00308 | 0.00000 |
| PNT P00R | -0.24375 | -0.00427 | 0.00000 |
| PNT P00S | -0.23750 | -0.00565 | 0.00000 |
| PNT P00T | -0.23125 | -0.00653 | 0.00000 |
| PNT P00V | -0.22500 | -0.00730 | 0.00000 |
| PNT P00W | -0.21250 | -0.00875 | 0.00000 |
| PNT P00X | -0.20000 | -0.00993 | 0.00000 |
| PNT P00Z | -0.18750 | -0.01070 | 0.00000 |
| PNT P010 | -0.17500 | -0.01115 | 0.00000 |
| PNT P011 | -0.15000 | -0.01120 | 0.00000 |
| PNT P012 | -0.12500 | -0.01043 | 0.00000 |
| PNT P013 | -0.10000 | -0.00917 | 0.00000 |
| PNT P014 | -0.07500 | -0.00750 | 0.00000 |
| PNT P015 | -0.05000 | -0.00540 | 0.00000 |
| PNT P016 | -0.02500 | -0.00308 | 0.00000 |
| PNT P017 | -0.01250 | -0.00175 | 0.00000 |
| PNT P019 | 0.00000 | 0.00000 | 0.00000 |
| PNT P1 | -0.50000 | -0.50000 | 0.00000 |
| PNT P2 | 0.50000 | -0.50000 | 0.00000 |
| PNT p3 | 0.50000 | 0.50000 | 0.00000 |
| PNT p4 | -0.50000 | 0.50000 | 0.00000 |
| PNT P01A | -0.18162 | 0.01898 | 0.00000 |
| PNT P01B | -0.18180 | -0.01094 | 0.00000 |
| PNT P046 | -0.27025 | 0.01256 | 0.00000 |
| PNT P059 | -0.26599 | 0.28688 | 0.00000 |
| PNT P049 | -0.25144 | 0.02439 | 0.00000 |
| PNT P05A | -0.35589 | 0.17566 | 0.00000 |
| PNT P04C | -0.22636 | 0.03241 | 0.00000 |
| PNT P04D | -0.20128 | 0.03643 | 0.00000 |
| PNT P05C | -0.38027 | 0.00958 | 0.00000 |
| PNT P04G | -0.12604 | 0.03833 | 0.00000 |
| PNT P04H | -0.07588 | 0.03616 | 0.00000 |
| PNT P04I | -0.02572 | 0.03231 | 0.00000 |
| PNT P05D | -0.31932 | -0.21136 | 0.00000 |
| PNT P04L | -0.27652 | -0.00154 | 0.00000 |
| PNT P04M | -0.27025 | -0.00803 | 0.00000 |
| PNT P05F | -0.20962 | -0.27840 | 0.00000 |
| PNT P04P PNT P04T | -0.25373 | -0.01567 | 0.00000 |
| PNT P04W | -0.12604 | -0.02143 | 0.00000 |
| PNT | -0.22676 | -0.02394 | 0.00000 |
| P04 | 0.29145 | 0.00000 |  |
| PN |  | 0.00000 |  |


| PNT P04X | -0.07588 | -0.02519 | 0.00000 |
| :--- | :---: | :---: | :--- |
| PNT P04Z | -0.02572 | -0.02355 | 0.00000 |
| PNT P05H | 0.00065 | -0.30887 | 0.00000 |
| PNT P052 | -0.18074 | 0.03754 | 0.00000 |
| PNT P054 | -0.18133 | -0.02465 | 0.00000 |
| PNT P056 | 0.00118 | 0.02891 | 0.00000 |
| PNT P058 | 0.00010 | -0.02250 | 0.00000 |
| PNT P05I | 0.01244 | 0.50000 | 0.00000 |
| PNT P05J | 0.00610 | -0.50000 | 0.00000 |
| PNT P05L | 0.50000 | -0.34112 | 0.00000 |
| PNT P05M | 0.50000 | 0.29206 | 0.00000 |
| PNT P05N | 0.50000 | 0.05780 | 0.00000 |
| PNT P05S | 0.50000 | -0.05314 | 0.00000 |
| PNT P05V | 0.50000 | -0.00217 | 0.00000 |
| PNT P00N | -0.23448 | 0.01345 | 0.00000 |
| PNT P02M | -0.23471 | -0.00608 | 0.00000 |
| PNT P03B | -0.24164 | 0.02804 | 0.00000 |
| PNT P03C | -0.23405 | -0.02029 | 0.00000 |
| PNT P03E | -0.24536 | 0.00794 | 0.00000 |
| PNT P03P | -0.24464 | -0.00400 | 0.00000 |
| PNT pl1 | -1.00000 | 0.00000 | 0.00000 |
| PNT pl2 | 1.00000 | 0.00000 | 0.00000 |
| SEQA S006 | pnt | P01A |  |
| SEQA | P007 | P00 |  |
| SEQA | S00W | pnt | P0019 P017 |

LINE L00N P03B P03C S00W 130
LINE L03R P052 P056 S00R 120
LINE LOOI PO5V P05N 210
LINE L03S P058 P054 S00S 120
LINE L04V p4 P059 -204
LINE L04W P059 P052 -912
LINE L04X P054 P05F 912
LINE L04Z P05F P1 204
LINE L050 P05F P059 S00T 150
LINE L052 P059 P05G 120
LINE L054 P05F P05H 120
LINE L056 P05H P058 -912
LINE L058 P056 P05G 912
LINE L059 p3 P05I 130
LINE L05A P05I p4 120
LINE L05D P05J P2 130
LINE L05V P056 P05N 130
LINE L05I P05M p3 204
LINE L05L P05N P05M 912
LINE L05Z P058 P05S 130
LINE L06C P019 P05V 130
LINE L06F P05M P05G 130
LINE L06H P05G P05I 204
LINE L06I P05L P05H 130
LINE L06J P05H P05J 204
LINE L001 P01A P00N S001 -210
LINE L00A P03E P03P S00E 120
LINE L00K P052 P03B S00L 110
LINE L009 P02M P01B S00A 210
LINE L000 P03C P054 S00X 110
LINE L002 POON P03E S002 -205
LINE LOOL P03P P02M S00P 205
LINE cl pl1 pl2 120
LINE L005 P000 P019 120
LCMB C001 + L001 + L002 + L00A + L00L + L009
LCMB C004 + LOOK + LOON + LOOO
GSUR A001 + BLEND + L003 + C004 - L006 - C001
GSUR A002 + BLEND + L006 - L03S + L008 + L00E
GSUR A003 + BLEND + L00C + L007 - L03R - L003
GSUR A004 + BLEND - L008 + L05Z + L00G - L06C
GSUR A005 + BLEND + L06C + L00I - L05V - L007
GSUR AOOI + BLEND - L04W - L050 - L04X - C004
GSUR A00J + BLEND - L04V + L004 - L04Z + L050
GSUR A00K + BLEND + L04Z + L05C - L06J - L054
GSUR A00L + BLEND + L06J + L05D + L05F + L06I
GSUR A00N + BLEND + L04V + L052 + L06H + L05A

```
GSUR A000 + BLEND - L06H - L06F + L05I + L059
GSUR A00P + BLEND + L04W + L03R + L058 - L052
GSUR A00R + BLEND + L04X + L054 + L056 + L03S
GSUR A00S + BLEND - L058 + L05V + L05L + L06F
GSUR A00T + BLEND - L056 - L06I + L05S - L05Z
SETA wall l LO5C
SETA wall l L059
SETA wall l L05A
SETA wall l LO5D
SETA profil l LOOC
SETA profil l LOOE
SETA profil l L001
SETA profil l LOOA
SETA profil l L009
SETA profil l LOO2
SETA profil l LOOL
SETA in l L004
SETA out l L05F
SETA out l LO5S
SETA out l LOOG
SETA out l LOOI
SETA out l LO5I
SETA out l LO5L
```


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[^0]:    'qint' RETURN 'w'|'l'|'q'

